

# Splitting Algorithms and Generalized Normalizing Flows

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# Lectures

0. Motivation
1. Splitting Algorithms
2. Optimal Transport and SMART
3. Normalizing Flows
4. Generalized Normalizing Flows

Porter des hiboux à Athènes

Eulen nach Athen tragen

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# Motivation: Inverse Problems in Imaging

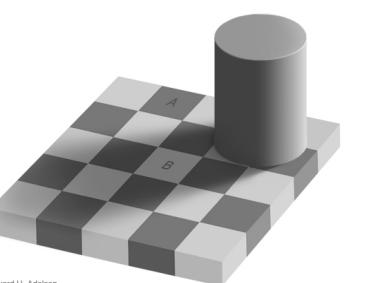
**Gray-value images:**  $x : \Omega \rightarrow \mathcal{M}$

e.g.  $\Omega = [1 : m] \times [1 : n]$  and  $\mathcal{M} = \{\underbrace{0}_{black}, \dots, \underbrace{255}_{white}\}$



|     |     |     |     |     |     |     |     |     |     |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 98  | 93  | 90  | 91  | 94  | 94  | 97  | 104 | 101 | 97  |
| 123 | 114 | 108 | 105 | 97  | 93  | 93  | 95  | 97  | 97  |
| 111 | 105 | 98  | 96  | 97  | 96  | 94  | 103 | 106 | 104 |
| 99  | 94  | 91  | 95  | 103 | 109 | 92  | 91  | 98  | 98  |
| 93  | 95  | 100 | 100 | 93  | 94  | 85  | 79  | 79  | 79  |
| 99  | 109 | 105 | 89  | 81  | 77  | 78  | 76  | 74  | 75  |
| 99  | 99  | 91  | 78  | 76  | 76  | 83  | 84  | 77  | 76  |
| 95  | 85  | 78  | 76  | 83  | 90  | 102 | 100 | 79  | 78  |
| 82  | 77  | 77  | 83  | 98  | 114 | 123 | 106 | 81  | 81  |
| 79  | 83  | 95  | 115 | 134 | 141 | 137 | 101 | 91  | 114 |

**Visual system:** Checkerboard shadow illusion of Adelson



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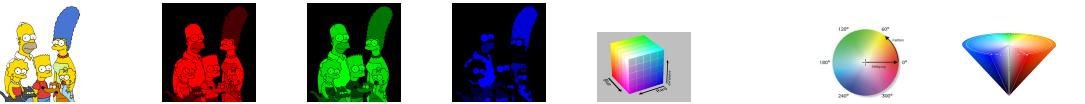
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# Other Images

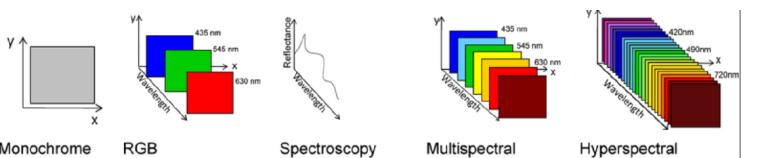
**Color images:** Many color systems, e.g. RGB system from computer screen, HSV ...



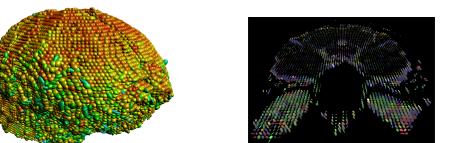
**Visual system:** Illustration of the lateral inhibition (Courtesy: M. Bertalmio)



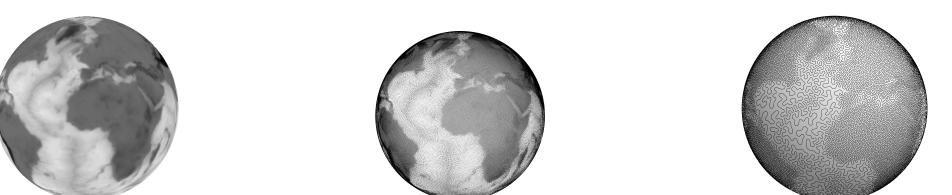
**Hyperspectral images:**



**Manifold-values images:** DT-MRI, IN-SAR



**Images on  $\mathbb{R}^3$  and manifolds:**



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# Motivation: Inverse Problems in Imaging

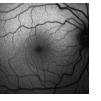
**Inverse Problem:** Find  $x$  given  $y$  with (known/unknown) forward operator  $F$ ,

$$y = \text{noisy}(F(x))$$

Find solution as minimizer of **variational model**:

$$\mathcal{J}(x) = \underbrace{\mathcal{D}_F(x, y)}_{\text{data term}} + \lambda \underbrace{\mathcal{R}(x)}_{\text{regularizer, prior}}, \quad \lambda > 0$$

Examples:

- ◆ image restoration: denoising, (blind) deblurring, inpainting, superresolution,  
...    
- ◆ computerized tomography (CT) (Video Siltanen)
- ◆ MRI (Fouriermatrix)
- ◆ FIB: Focused ion beam
- ◆ EBSD: Electron backscatter diffraction ( $\mathcal{M} = \text{SO}(3)/\mathcal{S}$ )
- ◆ diffraction tomography
- ◆ SMLM: single molecule localization microscopy

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- ◆ **Regularizer** to make the problem well-posed, since  $F$  is in general ill-posed/ill-conditioned
  - $F(x) = y$  has no solution (PCA) 
  - no unique solution (inpainting) 
  - solution does not depend continuously on input data (compact operators, deblurring, CT) 
- mildly ill-posed**  $\sigma_n > Cn^{-\gamma}$ ,  $\gamma \leq 1$ ,
- moderately ill-posed**  $\sigma_n > Cn^{-\gamma}$ ,  $\gamma > 1$ ,
- severely ill-posed** singular values decay faster than polynomial speed
- ◆ **Prior** for certain class of images: Bayesian (MAP) approach

$$\begin{aligned} \hat{x} \in \operatorname{argmax}_x \log(p_{X|Y=y}(x)) \quad & \text{Bayes: } p_{X|Y=y}(x) = \frac{p_{Y|X=x}(y)p_Y(y)}{p_X(x)} \\ = \operatorname{argmin}_x \{ -\log(p_{Y|X=x}(y)) - \log(p_X(x)) \} \quad & \\ = \operatorname{argmin}_x \{ \underbrace{\mathcal{D}_F(x, y)}_{\text{data-fidelity term}} + \lambda \underbrace{\mathcal{R}(x)}_{\text{prior}} \} \quad & \end{aligned}$$

e.g. Gibbs prior

$$p_X(x) = e^{-\lambda \mathcal{R}(x)} \in L_1(\mathbb{R}^d)$$

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# Motivation: Inverse Problems in Imaging

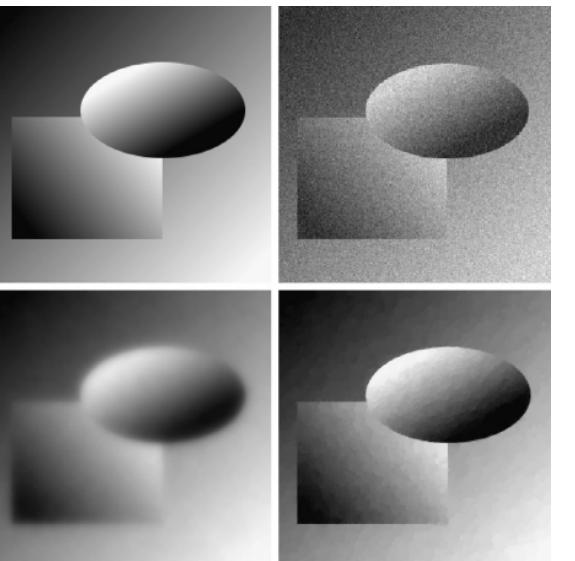
Typical regularizer/prior:

◆ Tikhonov regularizer:

- continuous:  $\mathcal{R}(u) = \int_{\Omega} |\nabla u|^2 dx = \|u\|_{W_2^1}^2$
- discrete:  $\mathcal{R}(x) = \|\nabla x\|_1 = \sum_{i,j} (x_{i+1,j} - x_{i,j})^2 + (x_{i,j+1} - x_{i,j})^2$

◆ Total Variation regularization:

- continuous:  $\mathcal{R}(u) = |Du|_{TV} = \sup_{\varphi \in C_c^1(\Omega, \mathbb{R}^2), \|\varphi\|_{\infty} \leq 1} \langle u, \operatorname{div} \varphi \rangle = \|u\|_{W_2^1}$
- discrete:  $\mathcal{R}(x) = \|\nabla x\|_1 = \sum_{i,j} \sqrt{(x_{i+1,j} - x_{i,j})^2 + (x_{i,j+1} - x_{i,j})^2}$



$$\operatorname{argmin}_x \left\{ \frac{1}{2} \|y - x\|^2 + \lambda \mathcal{R}(x) \right\}$$

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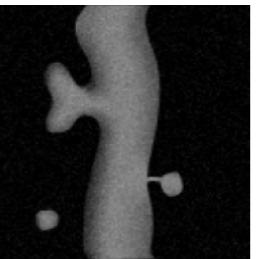
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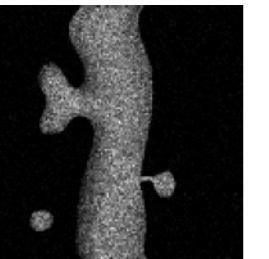
# MAP Estimation



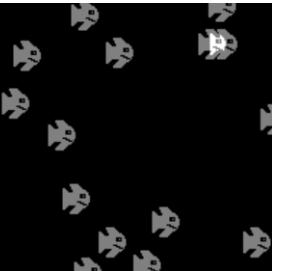
(a) Phantom.



(b) Gaussian noise.



(c) Poisson noise



Right: Phantom of a confocal microscopy image illustrating a neuron. Middle: white additive Gaussian noise Right: Poisson noise (Courtesy: A. Jeziarska, PhD thesis)

$$\blacklozenge \quad \operatorname{argmin}_x \left\{ -\log(p_{Y|X=x}(y)) - \log(p_X(x)) \right\}$$

$$p_{Y|X=x}(y) = \begin{cases} \frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{\|y-F(x)\|_2^2}{2\sigma^2}} & \text{Gaussian noise,} \\ \prod_{i=1}^N \frac{(F(x)_i)^{y_i} e^{-F(x)_i}}{y_i!} & \text{Poisson noise} \end{cases}$$

Up to a constant

$$-\log(p_{Y|X=x}(y)) = \begin{cases} \frac{1}{2\sigma^2} \|y - F(x)\|_2^2 & \text{Gaussian,} \\ -\sum_i y_i \log(F(x)_i) + F(x)_i = \text{KL}(y, F(x)) + c & \text{Poisson} \end{cases}$$

with **Kullback-Leibler divergence** (componentwise)

$$\text{KL}(u, v) = u \log u - u \log v - u + v$$

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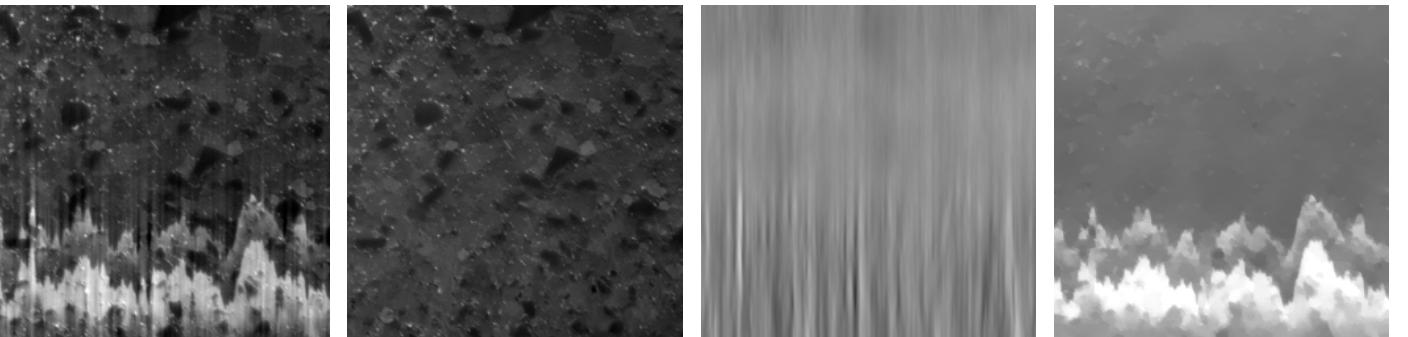
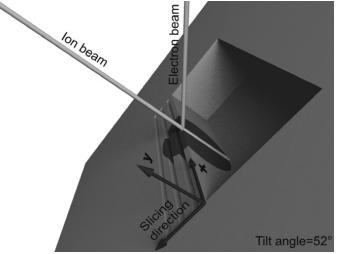
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# Example 1: Removal of Curtaining Effects in FIB



Model:

$$\mathcal{J}(u, s, l) = \|f - (u + s + l)\|_2^2 + \varphi_1(u) + \varphi_2(s) + \varphi_3(l),$$

with

$$\varphi_1(u) := \mu_1 \|\nabla_{x,z} u\|_{2,1} + \mu_2 \|\Delta_z u\|_1 + \iota_{[0,1]^N}(u),$$

$$\varphi_2(s) := \|\nabla_y s\|_1,$$

$$\varphi_3(l) := \mu_3 \|\nabla_{x,y} l\|_{2,1}$$

◆ Video: J.-H. Fitschen

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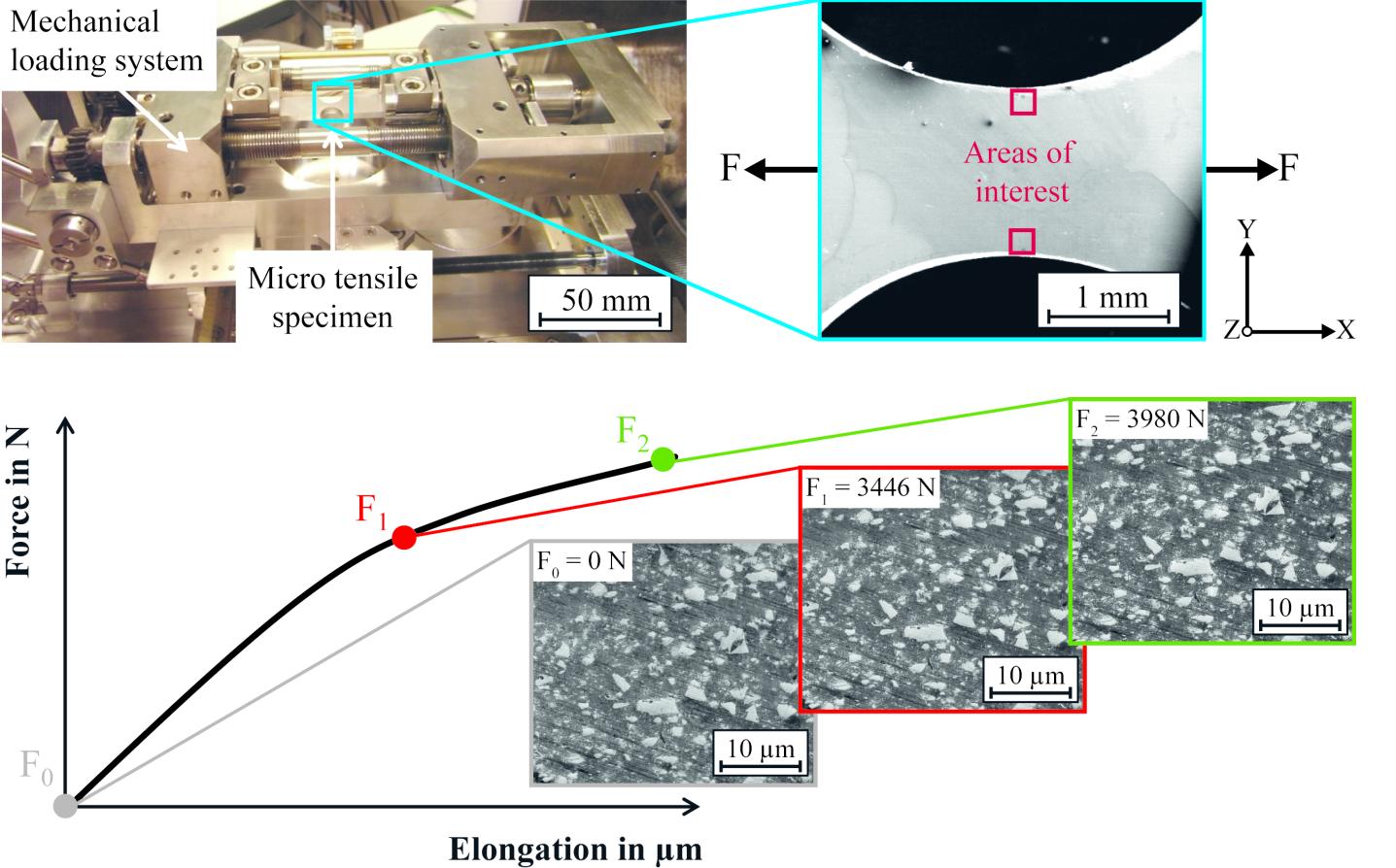
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## Example 2: Strain Computation



Top: Experimental setup for the tensile test inside a scanning electron microscope. Bottom: Load-deformation diagram with three selected micrographs taken under increasing load.

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## Example 2: Strain Computation

Model:  $u = (u_1, u_2)^\top$  vector field

$$\mathcal{J}(u) := \|A_{f_2}u + c_{f_1, f_2}\|_1 + \text{TGV}(u)$$

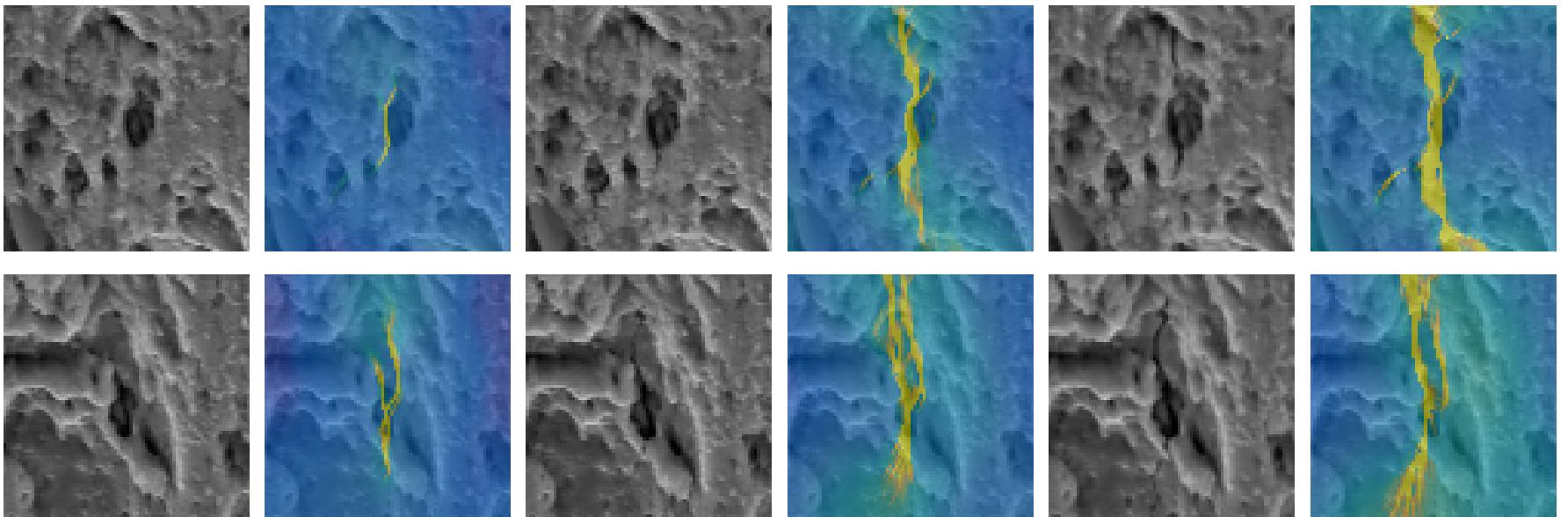
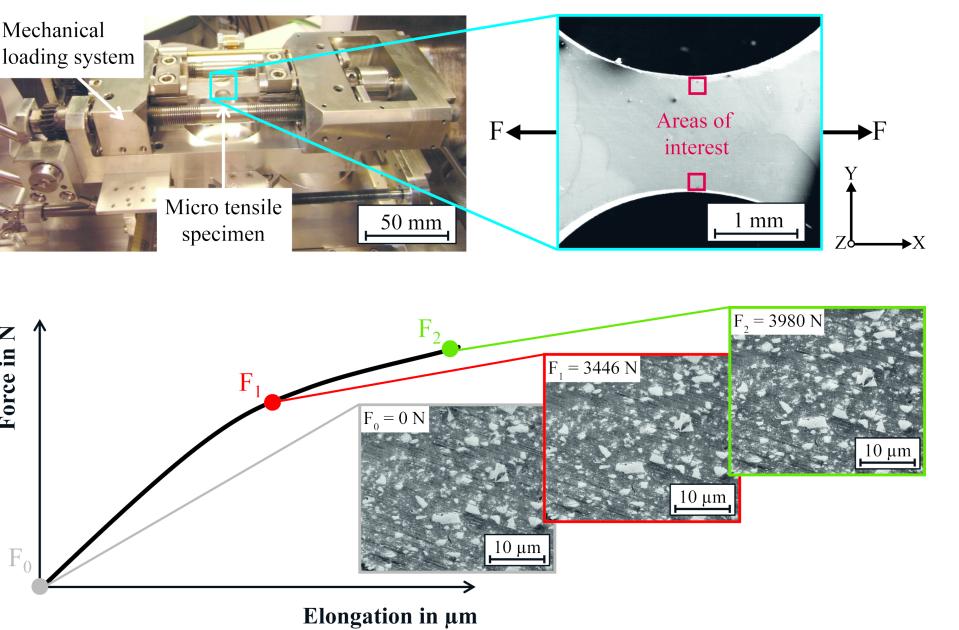
where the data term arises from linearizing the brightness invariance assumption:

$$\begin{aligned} 0 &\approx f_1(x) - f_2(x + u(x)) \\ &\approx f_1(x) - f_2(x + \bar{u}(x)) - \langle \nabla f_2(x + \bar{u}(x)), u(x) - \bar{u}(x) \rangle \end{aligned}$$

and the regularizer is

$$\text{TGV}(u) := \inf_a \left\{ \int_{\Omega} \lambda_1 \underbrace{\|\nabla u - a\|_F}_{\text{local feature}} + \lambda_2 \underbrace{\|\nabla a\|_F}_{\text{global feature}} dx \right\}$$

## Example 2: Strain Computation



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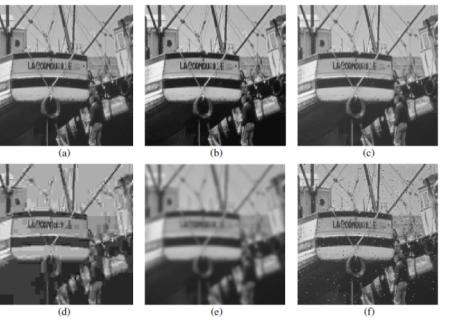
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# Quality Measures

- ◆ MSE:  $\text{MSE}(u, f) := \frac{1}{N} \|u - f\|_2^2$
- ◆ PSNR: Peak signal to noise ratio  $\text{PSNR}(u, f) := 10 \log_{10} \frac{|\max f - \min f|^2}{\frac{1}{N} \|u - f\|_2^2}$ ,
- ◆ MAE: Mean absolute error  $\text{MAE}(u, f) := \frac{1}{N} \|f - u\|_1$ .
- ◆ SSIM: Structure similarity measure (Simoncelli et al. 2004)
- ◆ Sharpness index (Moisan et al. 2011)
- ◆ LPIPS: Learned Perceptual Image Patch Similarity (Zhang/Efros 2018)



Different type of distortions, all with  $\text{MSE} = 210$ . (a) Original image, (b) Contrast-stretched image, SSIM = 0.9168, (c) Mean-shifted image, SSIM = 0.9900, (d) JPEG compressed image, SSIM = 0.6949, (e) Blurred image, SSIM = 0.7052, (f) Salt-pepper noise contaminated image, SSIM = 0.7748. Image: Simoncelli et al 2004.

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# Motivation: Neural Networks and Deep Learning ⚡

M. Elad (2017) SIAM News: **Deep, deep trouble:**

Deep learning's impact on image processing, mathematics, and humanity

Change to: **High, high challenge**

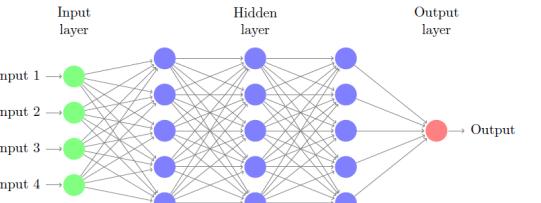


Figure 1: Model of a NN with three hidden layers, i.e.,  $d = 4$ ,  $K = 4$ ,  $n_1 = n_2 = n_3 = 5$ ,  $n_4 = 1$ .

**NN:**  $\Phi(\cdot; \theta) : \mathbb{R}^d \rightarrow \mathbb{R}^{n_K}$  of the form

$$\Phi(\cdot; \theta) := A_K \sigma \circ A_{K-1} \sigma \circ \dots \sigma \circ A_1$$

with non-linear activation  $\sigma: \mathbb{R} \rightarrow \mathbb{R}$  acting componentwise and affine functions

$$A_k(x) := W_k x + b_k, \quad W_k \in \mathbb{R}^{n_k, n_{k-1}}, \quad b_k \in \mathbb{R}^{n_k}$$

**Training** of a NN by minimizing

$$\mathcal{J}(\theta) := \sum_{i=1}^N \ell(\Phi(x_i; \theta); y_i),$$

**Minimization Algs:** stoch. gradient descent algorithm (filtered backprojection, automatic differentiation), inertial stoch. PALM Refs: Hertrich/Steidl 2022

Fitschen: „most stupid method to solve problems“

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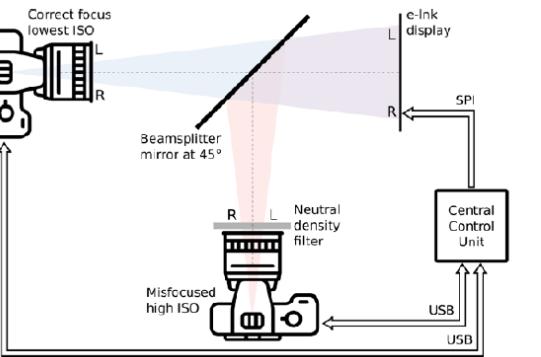
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# Example 1: Deblurring

Helsinki Deblur Challenge 2021 organized by the Finish Inverse Problem Society

Winner: Genzel, MacDonald, März (PhD), T. Trippe (Master thesis) TUB

- ◆ Goal: deblurring of text images obtained by an optical aperture



- ◆ 20 levels of increasing defocus blur, 200 samples per level
- ◆ Results:

|  |  |   |  |   |                                      |   |
|--|--|---|--|---|--------------------------------------|---|
| ZIXDGCrue<br>KrextnikKeC<br>gSvmJmJEKE   | ZJXDGCrue<br>KrextnikKeC<br>gSvmJmJEKE   | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | TF2ATuNQEZ<br>jaxiglunTqpd<br>PwyPrnTapD | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | zM bisrpe]<br>UgeEAuDzT<br>LmfQtsV   | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick |
| ZuYFSJuNTB<br>NTEXqAPhMa<br>nSxvTbwAyM   | ZuYFSJuNTB<br>NTEXqAPhMa<br>nSxvTbwAyM   | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | NtYGMvQPwv<br>NRBgrTrVztp<br>xGCCDnTbsp  | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | LxZrvGdD k<br>qLUnuYKsw<br>anUSQzUhc | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick |
| UNLTuSwXtp<br>DJHJWwEuwY<br>RXEgjK5XC    | UNLTuSwXtp<br>DJHJWwEuwY<br>RXEgjK5XC    | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | Yd1b sHvRp<br>Qd2YcfchP<br>hwuqif YCD    | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | fFSSTpUVr<br>UWgbWdsCMe<br>nxNbemjYj | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick |
| cXF XfnulLM<br>ueBwRqmuMyC<br>vpSYztftTM | cXF XfnulLM<br>ueBwRqmuMyC<br>vpSYztftTM | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | mZrgnyUljJ<br>giSmxAvcNe<br>sSh AFWwsf   | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | Sutl MonkB<br>asqmfvqh<br>gvE bmmMQL | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick |
| uQNGzUpgdQ<br>FHuxtmckpB<br>fkhuhvPlyh   | uQNGzUpgdQ<br>FHuxtmckpB<br>fkhuhvPlyh   | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | TvLzQgcWfE<br>LcuJCsSyD<br>Rwtb xxYxt    | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | SRqDchHi<br>zCFZBChPf<br>zfIyyHKqKD  | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick |
| PdsgpYnDQs<br>midaInVnneB<br>tfdTHbzZwp  | PdsgpYnDQs<br>midaInVnneB<br>tfdTHbzZwp  | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | TRUswRbjp<br>mTOPVwEwD<br>TSBWRNstFB     | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | wfHixXeC<br>SWuymrddP<br>egSeavDYC   | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick |
| TEHBlwWhQg<br>PyCzwGzKw<br>vbcDvaAzeF    | TEHBlwWhQg<br>PyCzwGzKw<br>vbcDvaAzeF    | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick | dmCSzMD np<br>fniCLxztog<br>XsuuPEk2C    | original characters:<br>0.1 mm height,<br>0.05 mm width,<br>0.05 mm thick |                                      |   |

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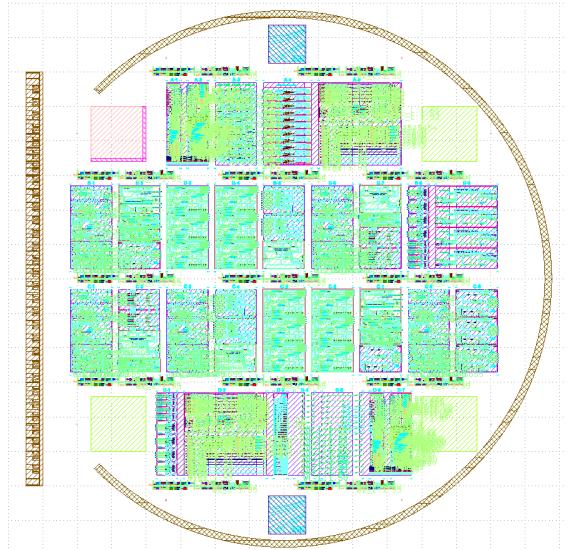
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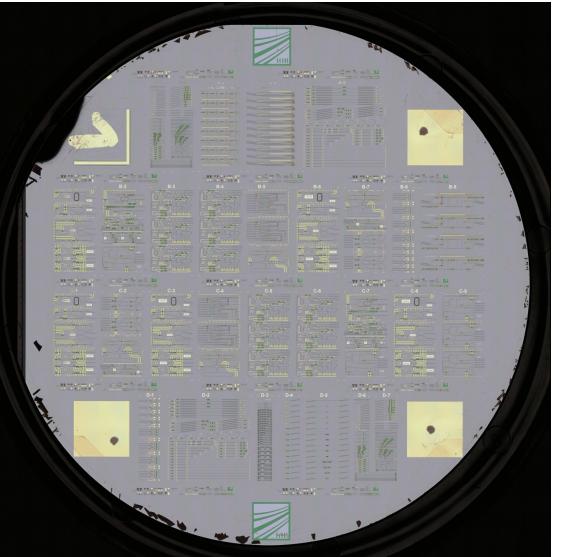
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## Example 2: Photo Integrated Circuit Design

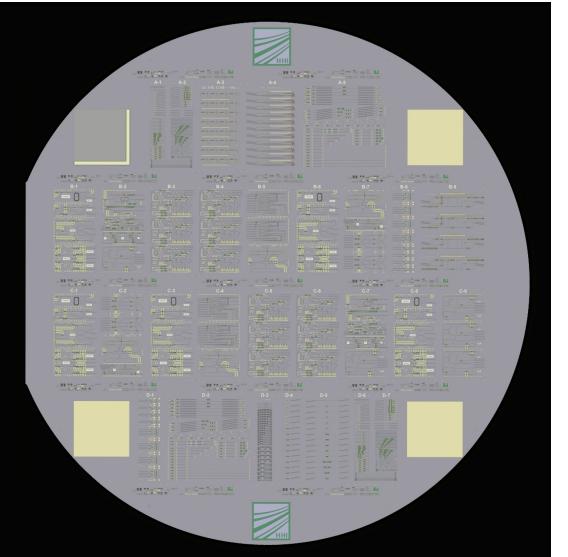
Master thesis C. Wittmann (with Hertz Institute Berlin)



plan



photo



NN simulation

- ◆ LPIPS as loss function

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# End of Motivation

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How to model and minimize variational models in inverse problems  
and how NNs can be incorporated?

Let's do some MATH.

A. Maslow (1966):

"If the only tool you have is a hammer,  
you treat everything as if it were a nail."

Berlin Mathematics Research Center

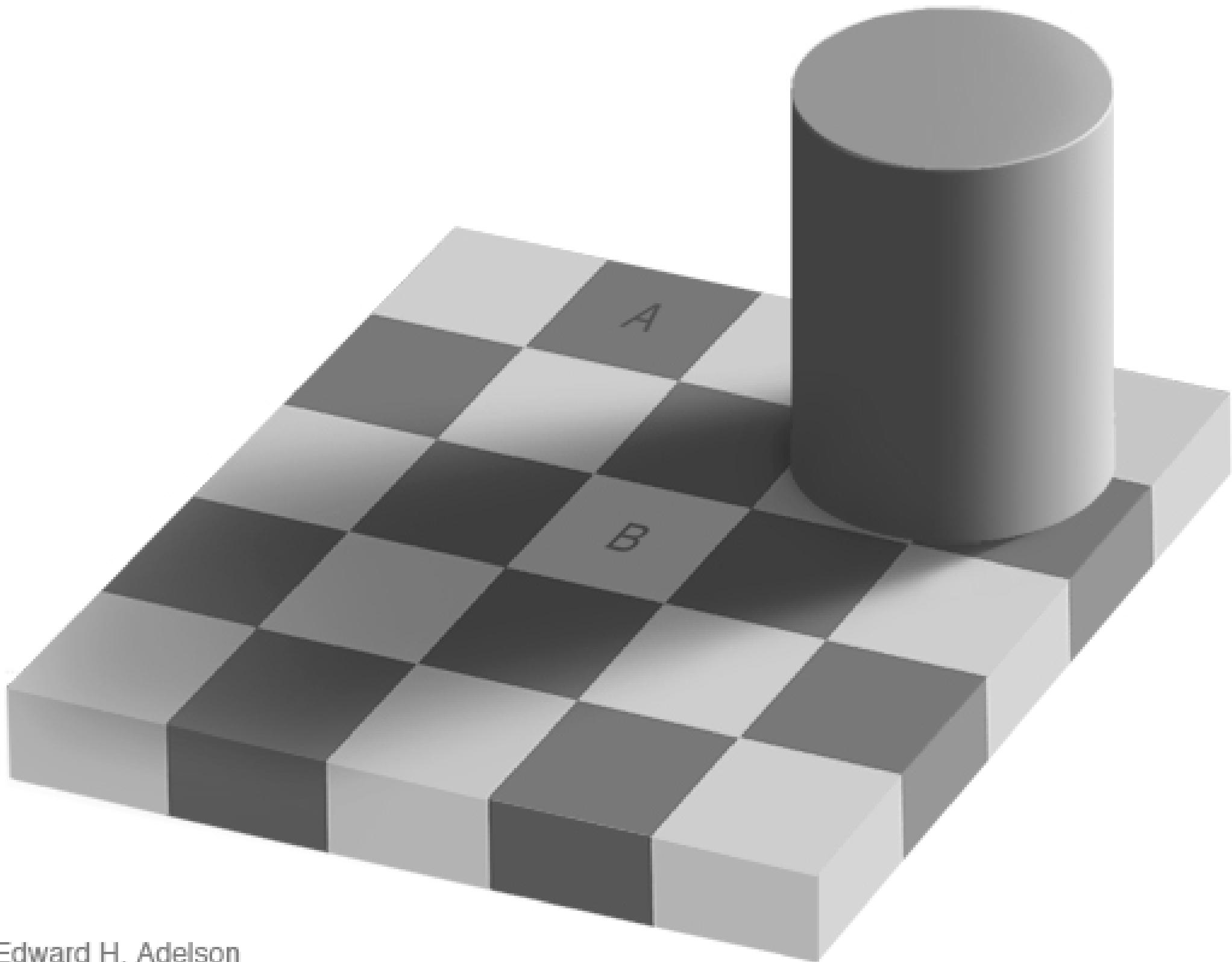


Funded under Germany's Excellence Strategy by

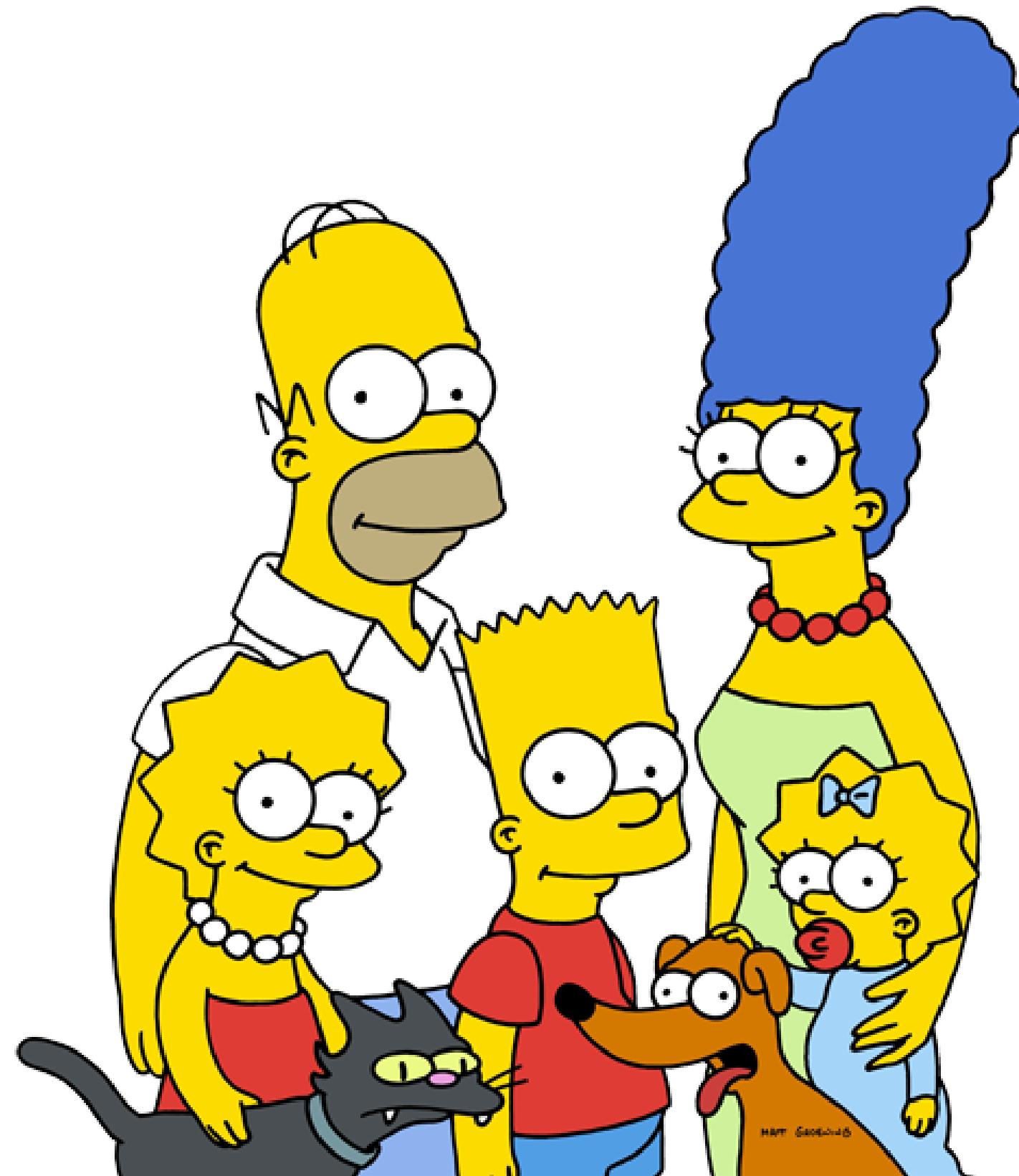
**DFG** Deutsche  
Forschungsgemeinschaft

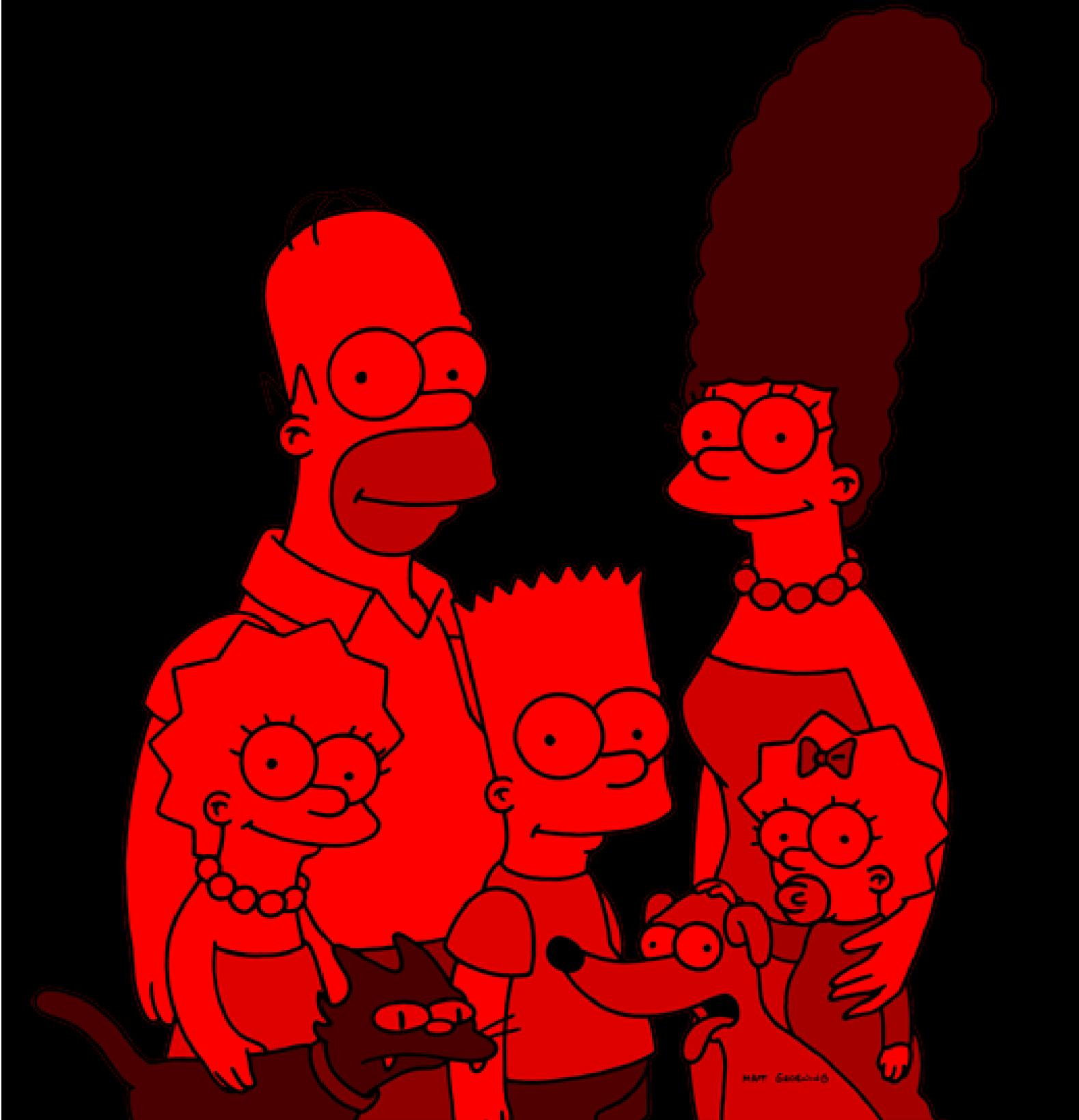






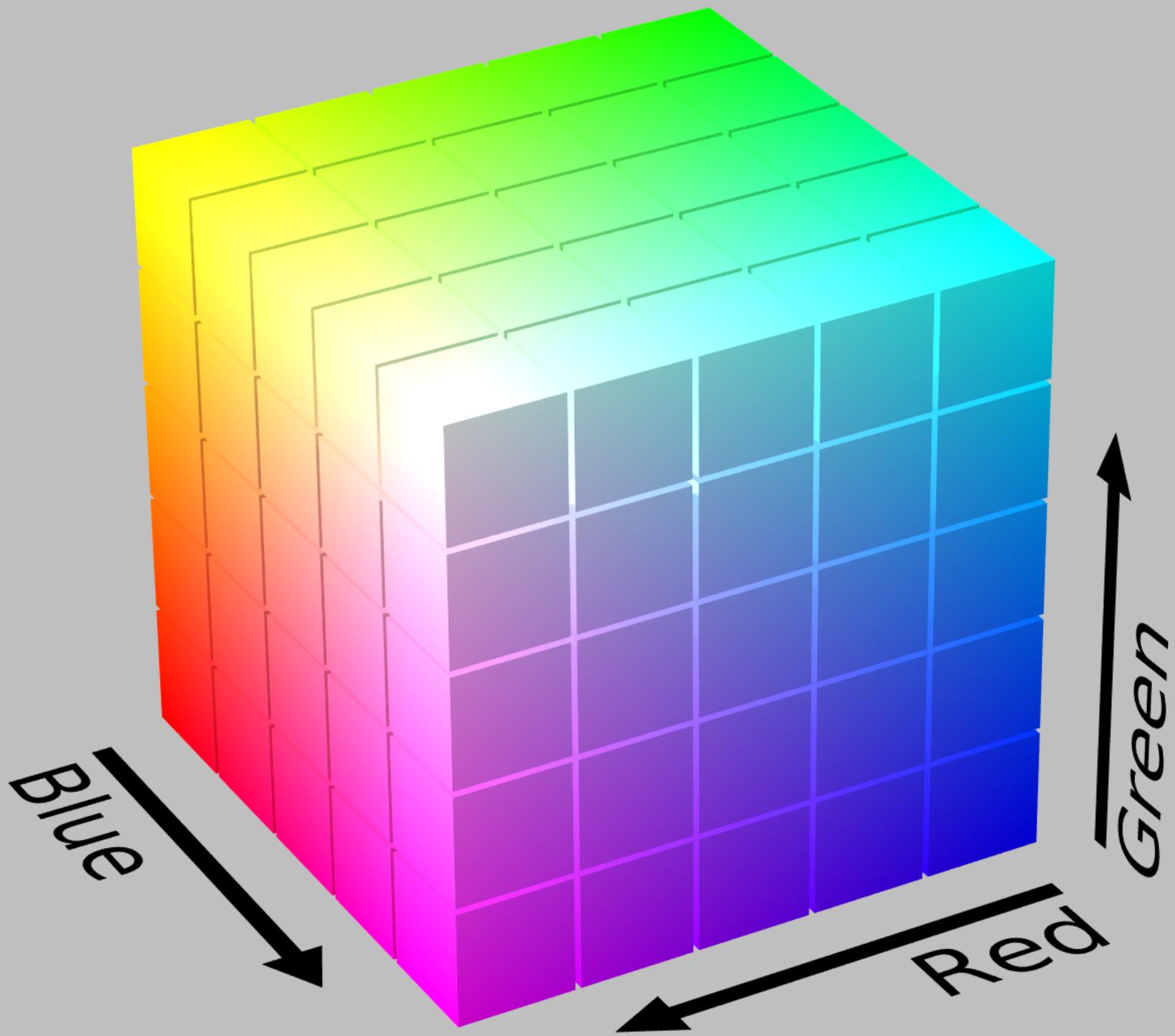
Edward H. Adelson

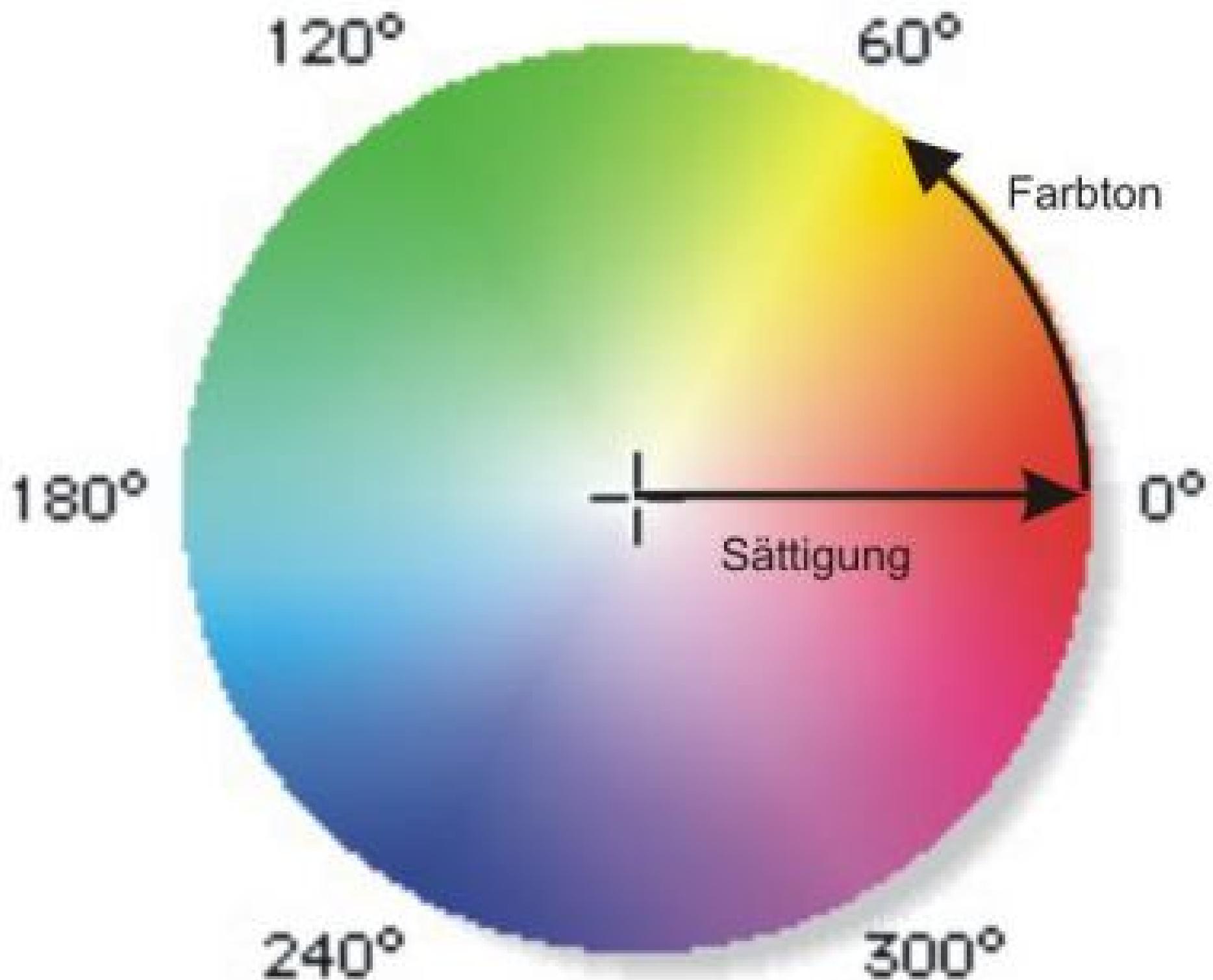


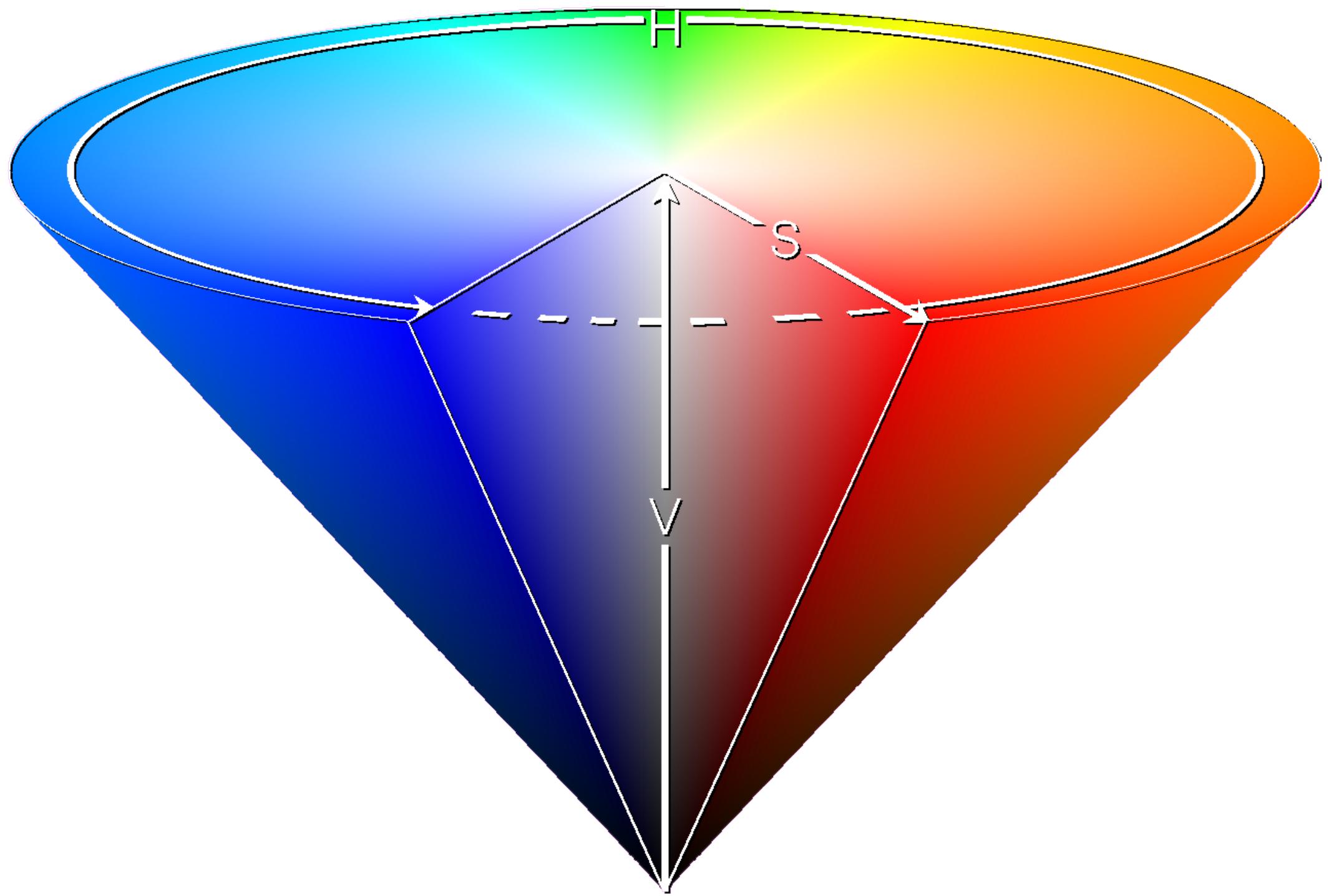


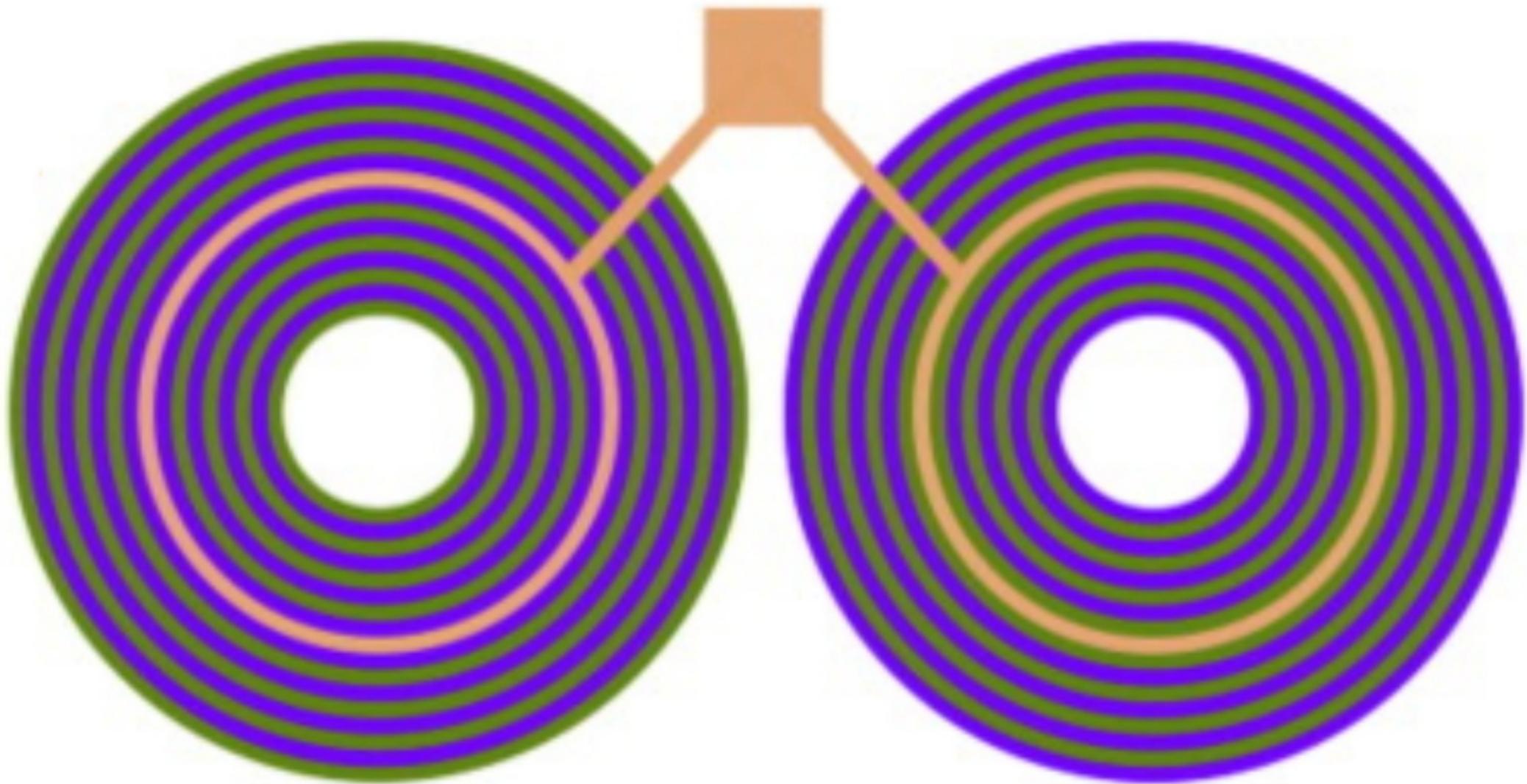


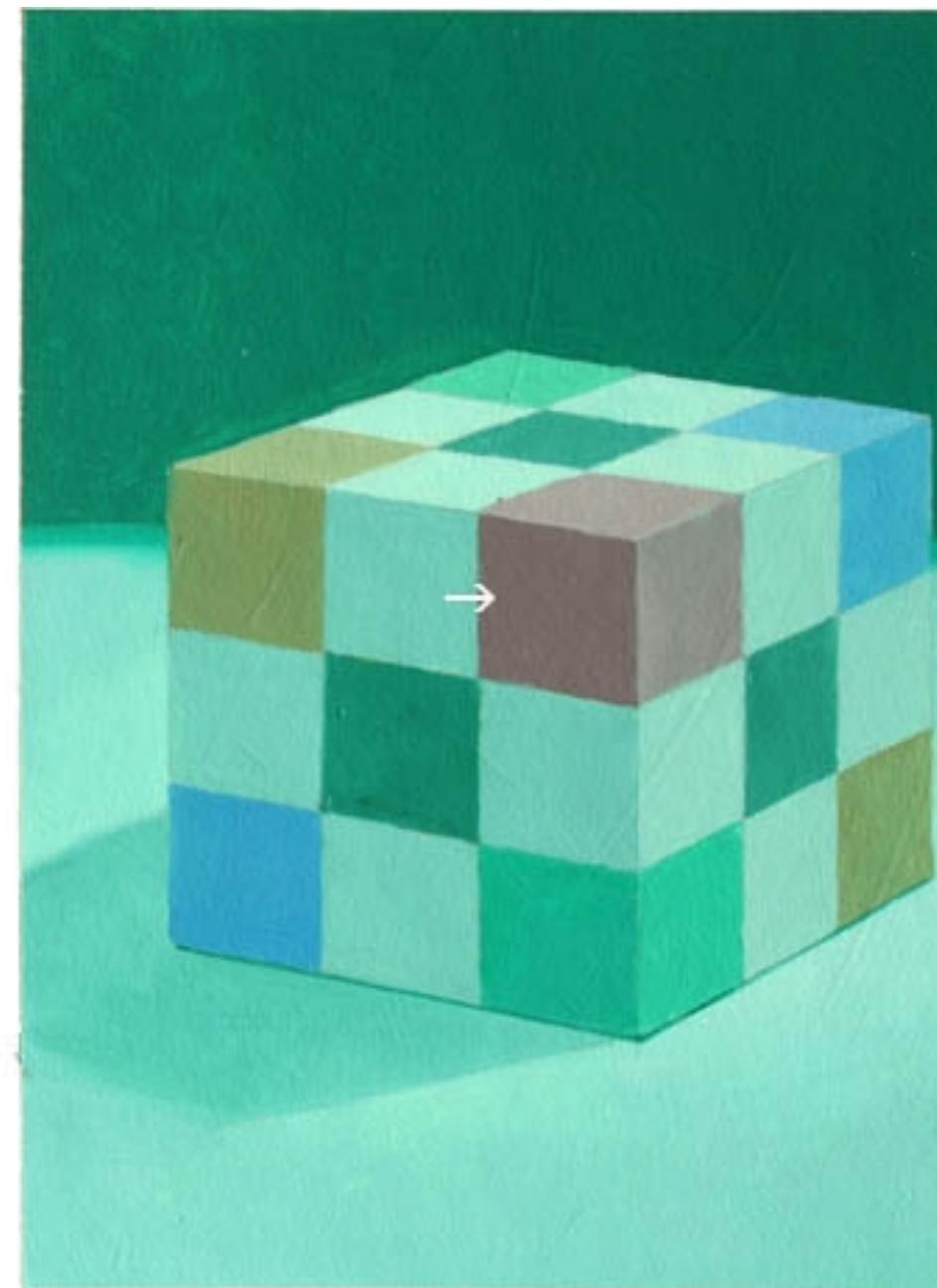
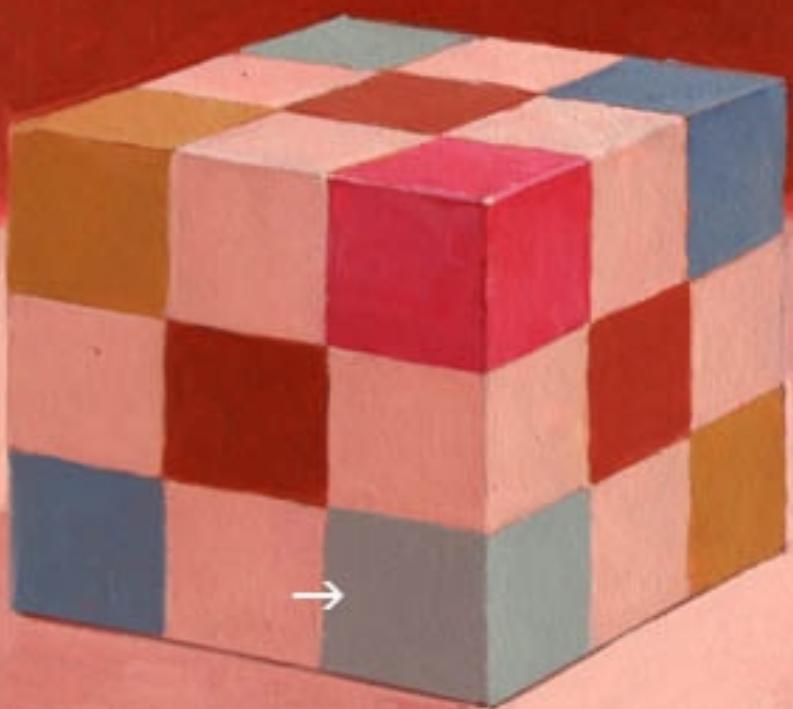




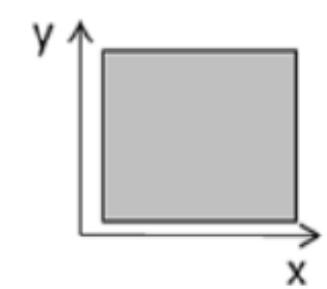




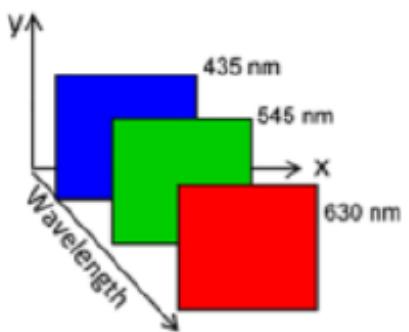




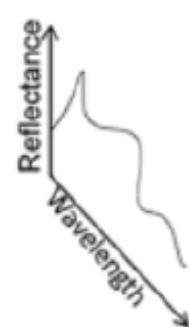
© James Gurney 2010



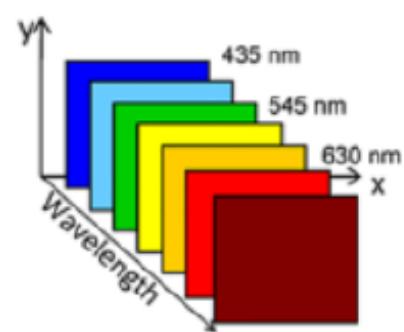
Monochrome



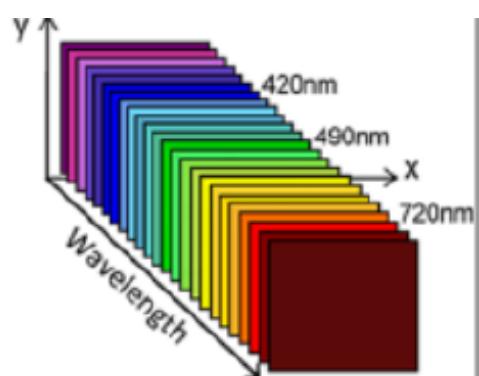
RGB



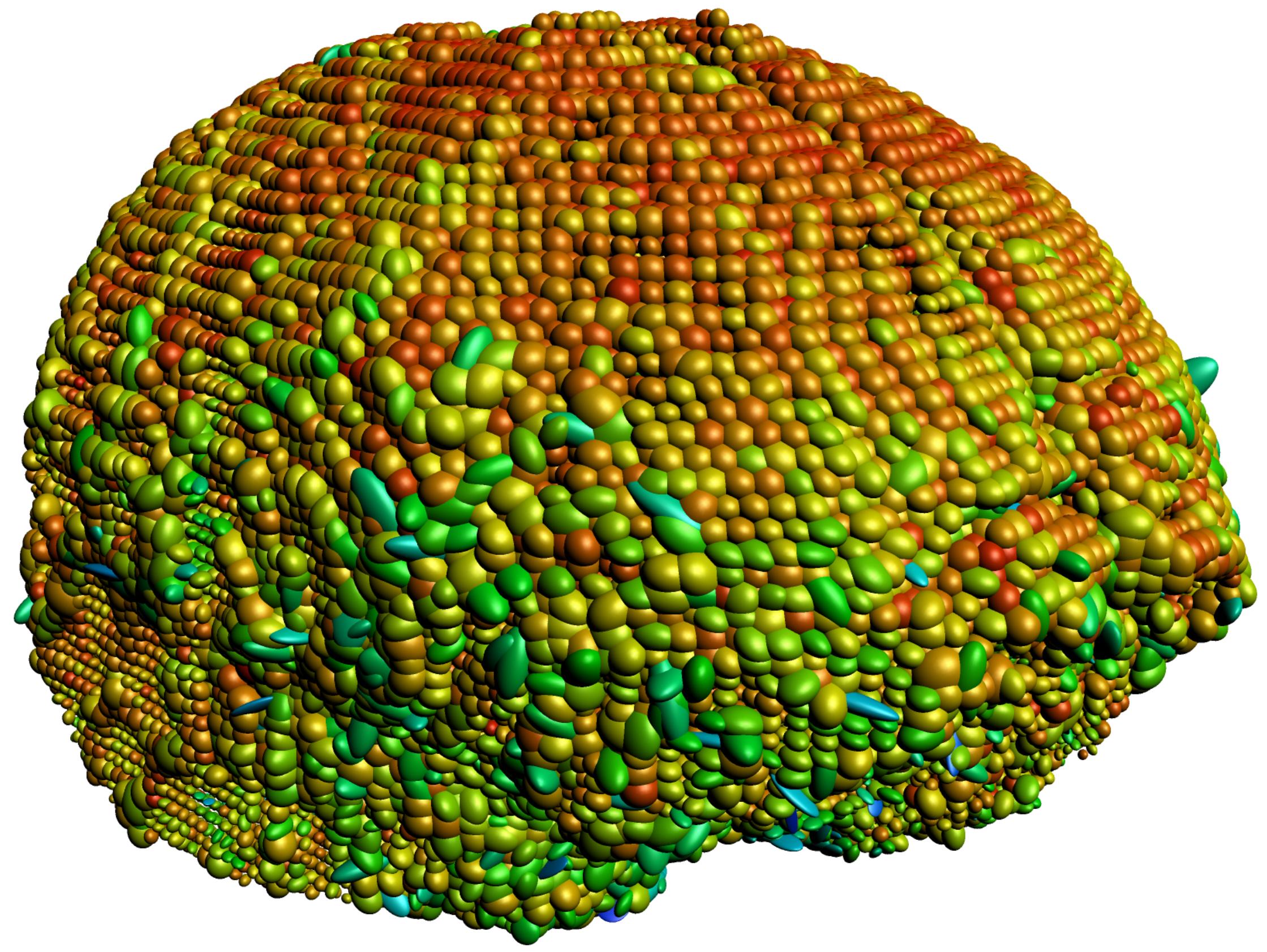
Spectroscopy

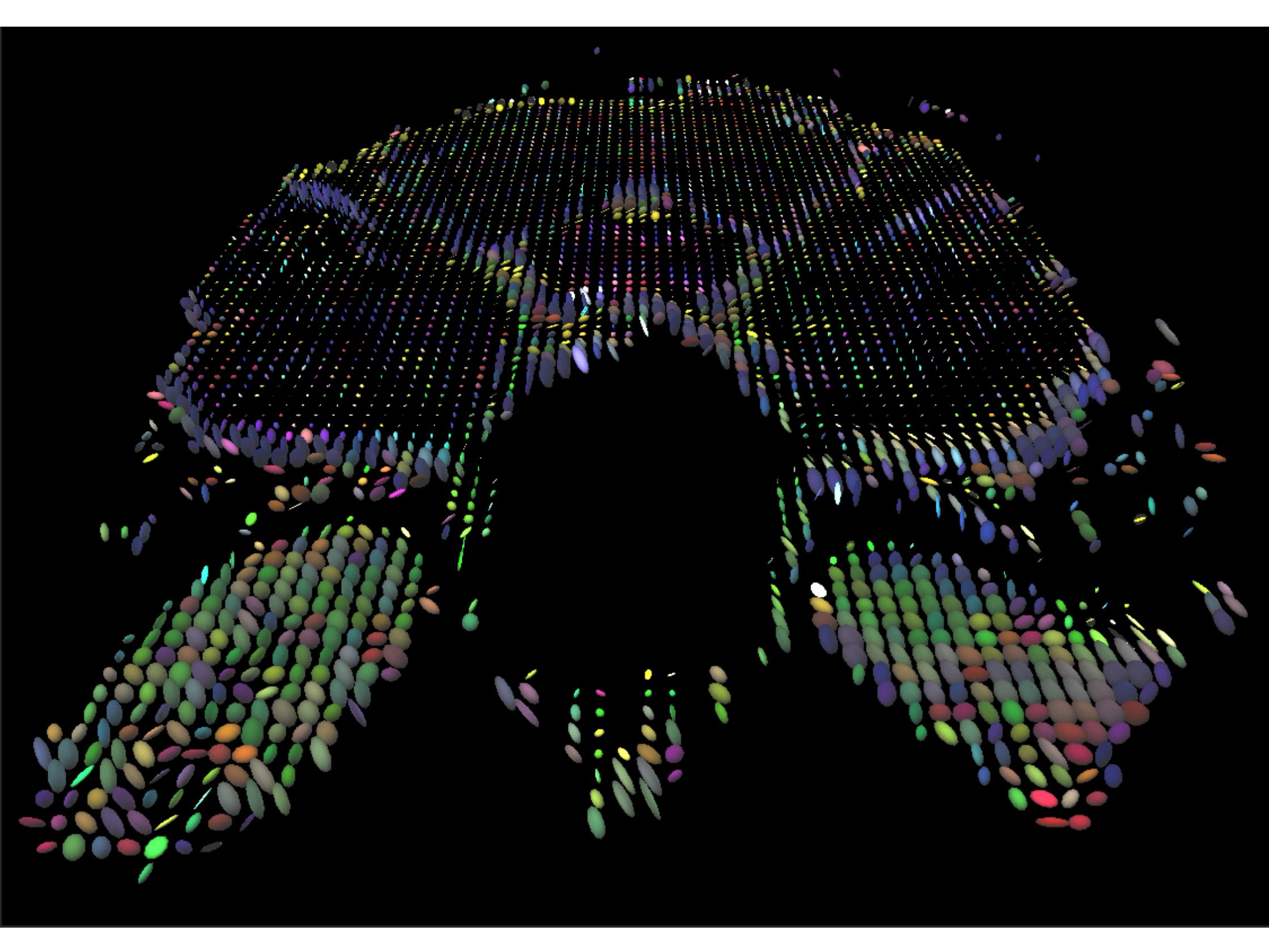


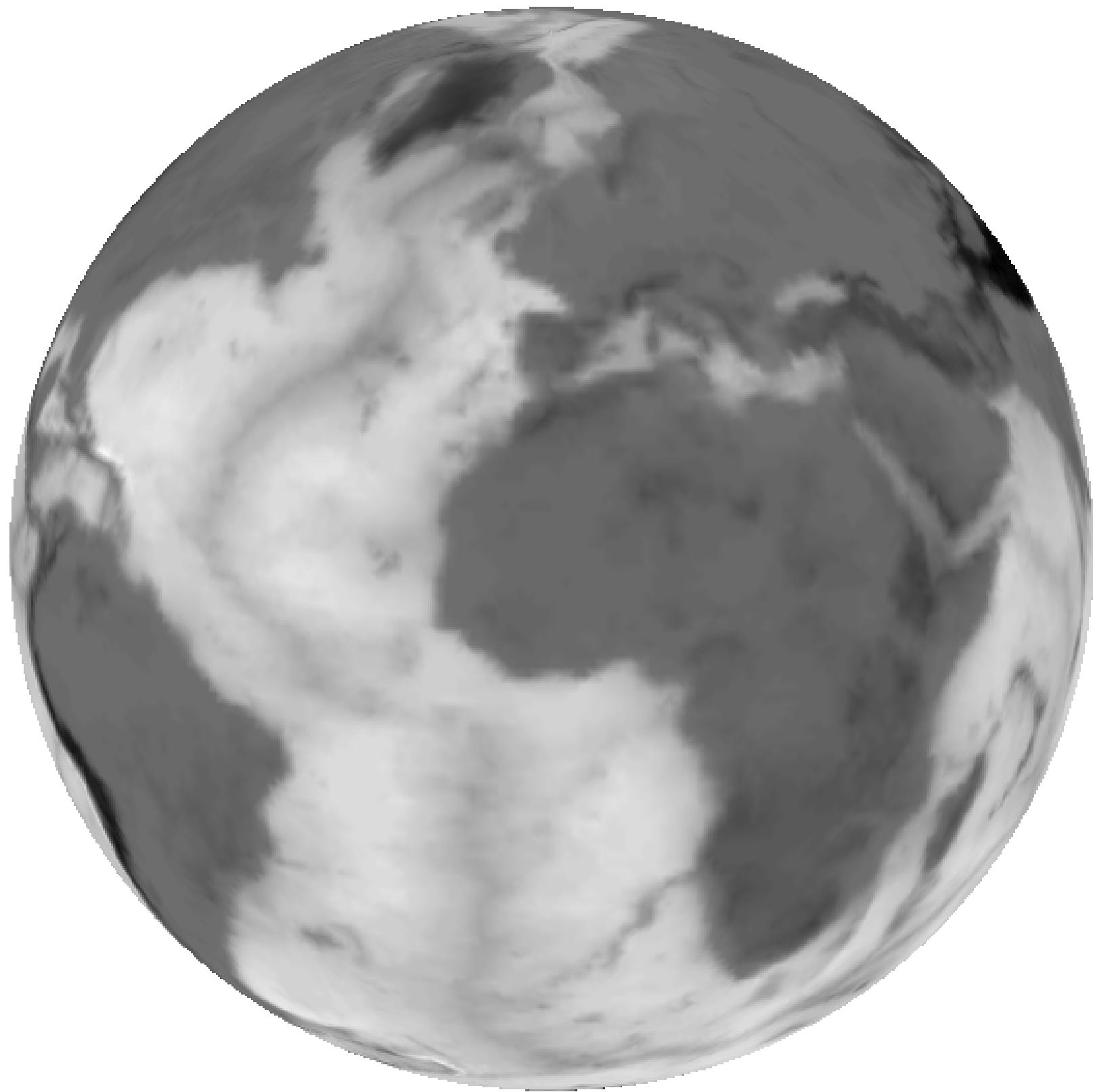
Multispectral

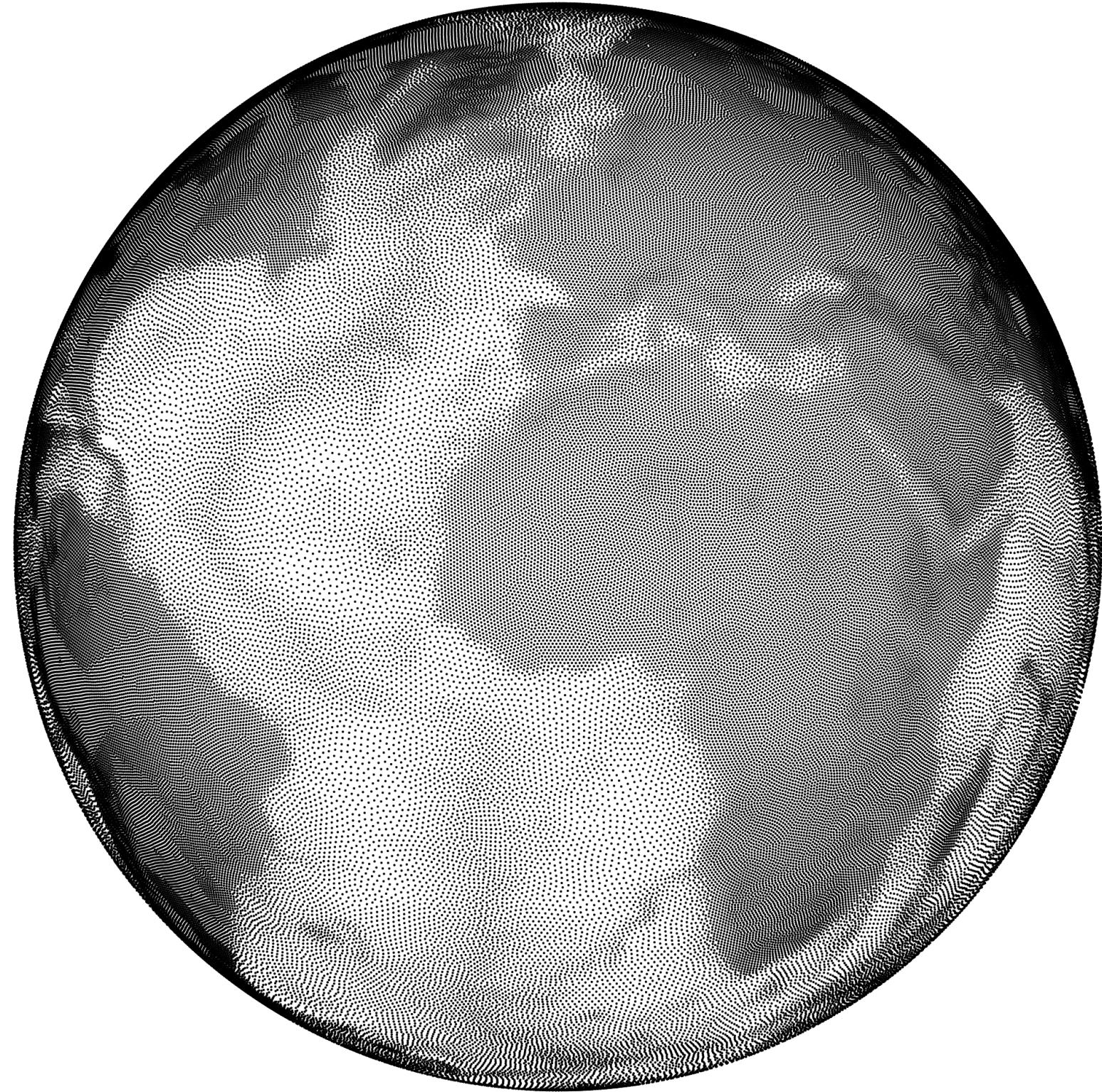


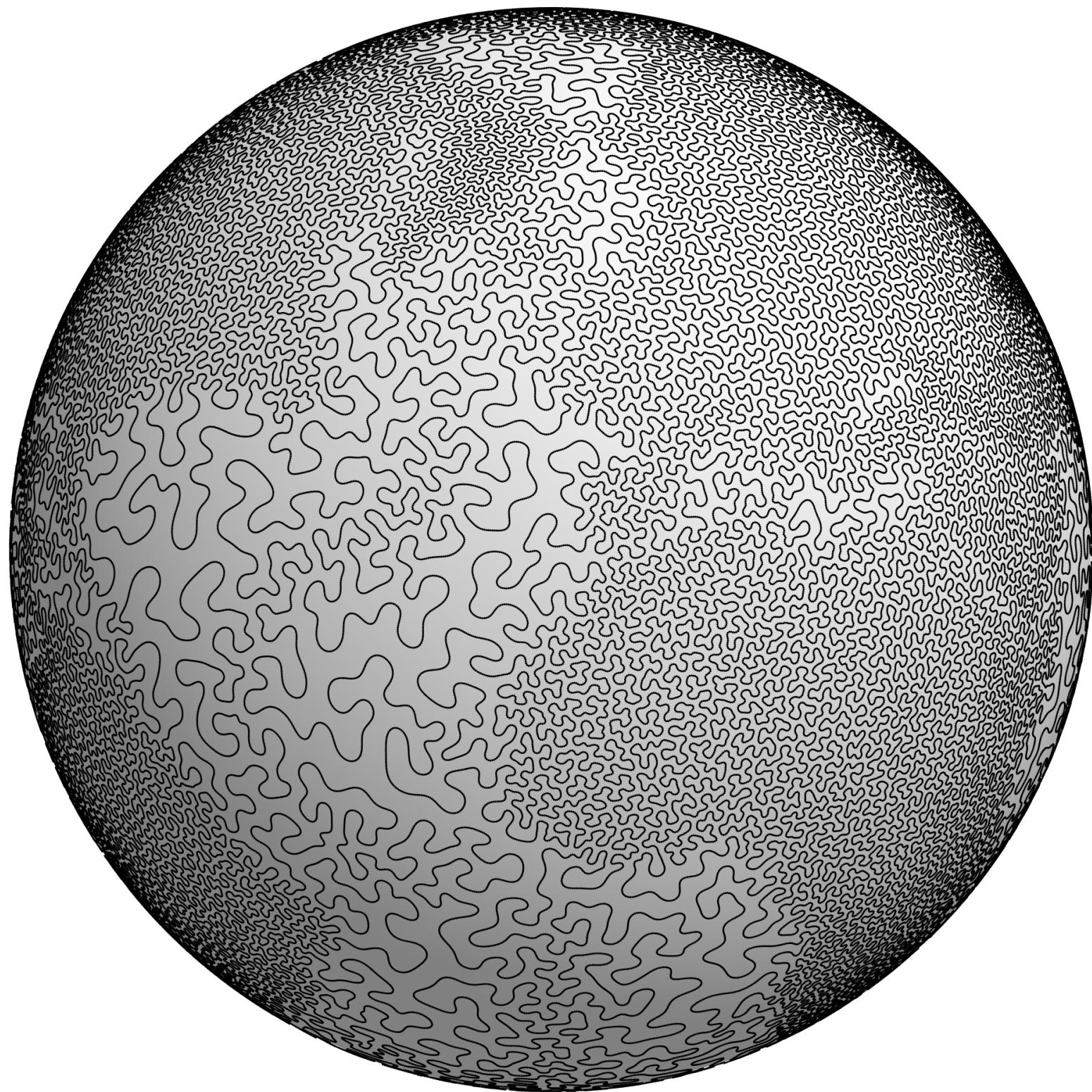
Hyperspectral







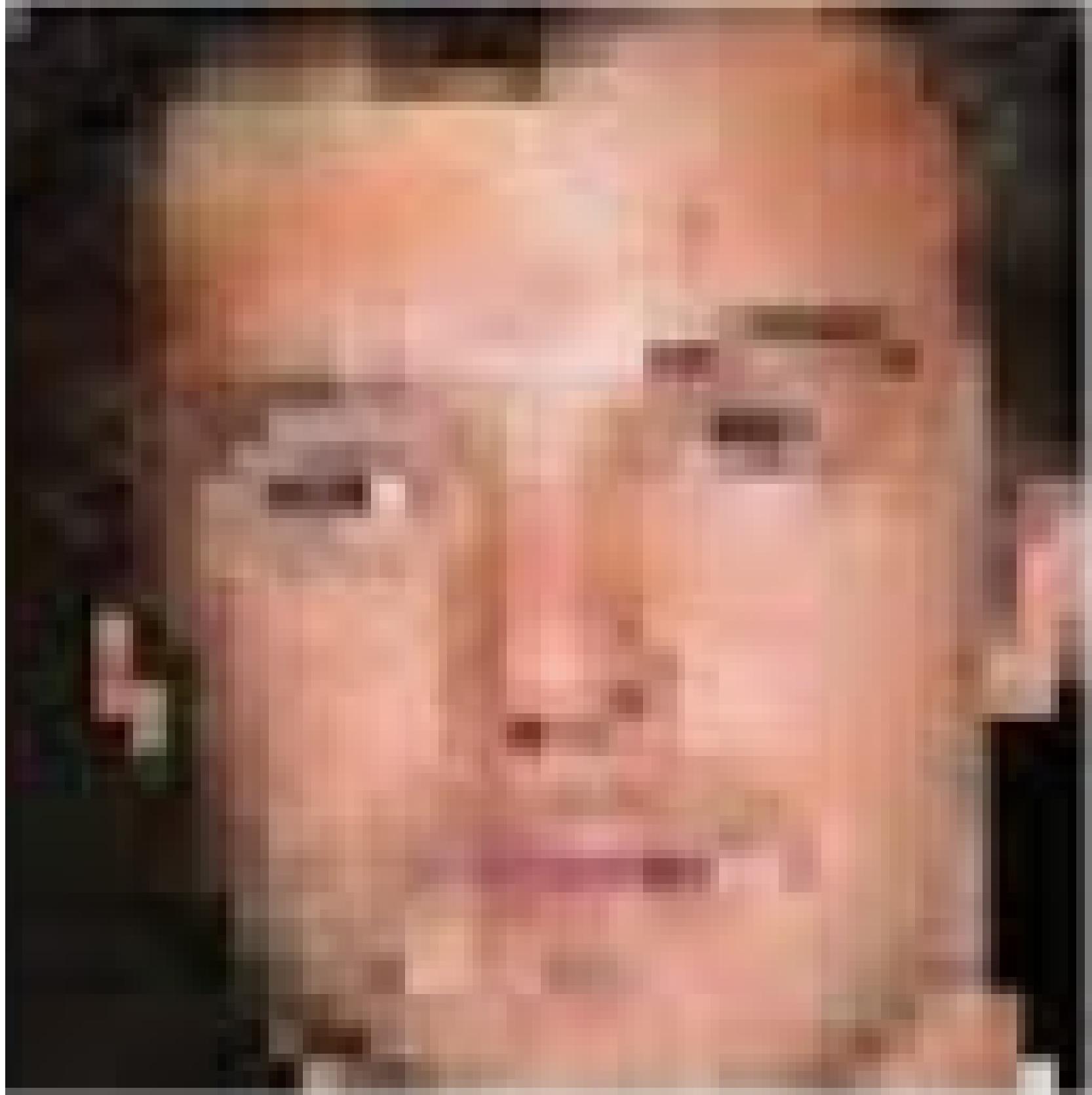


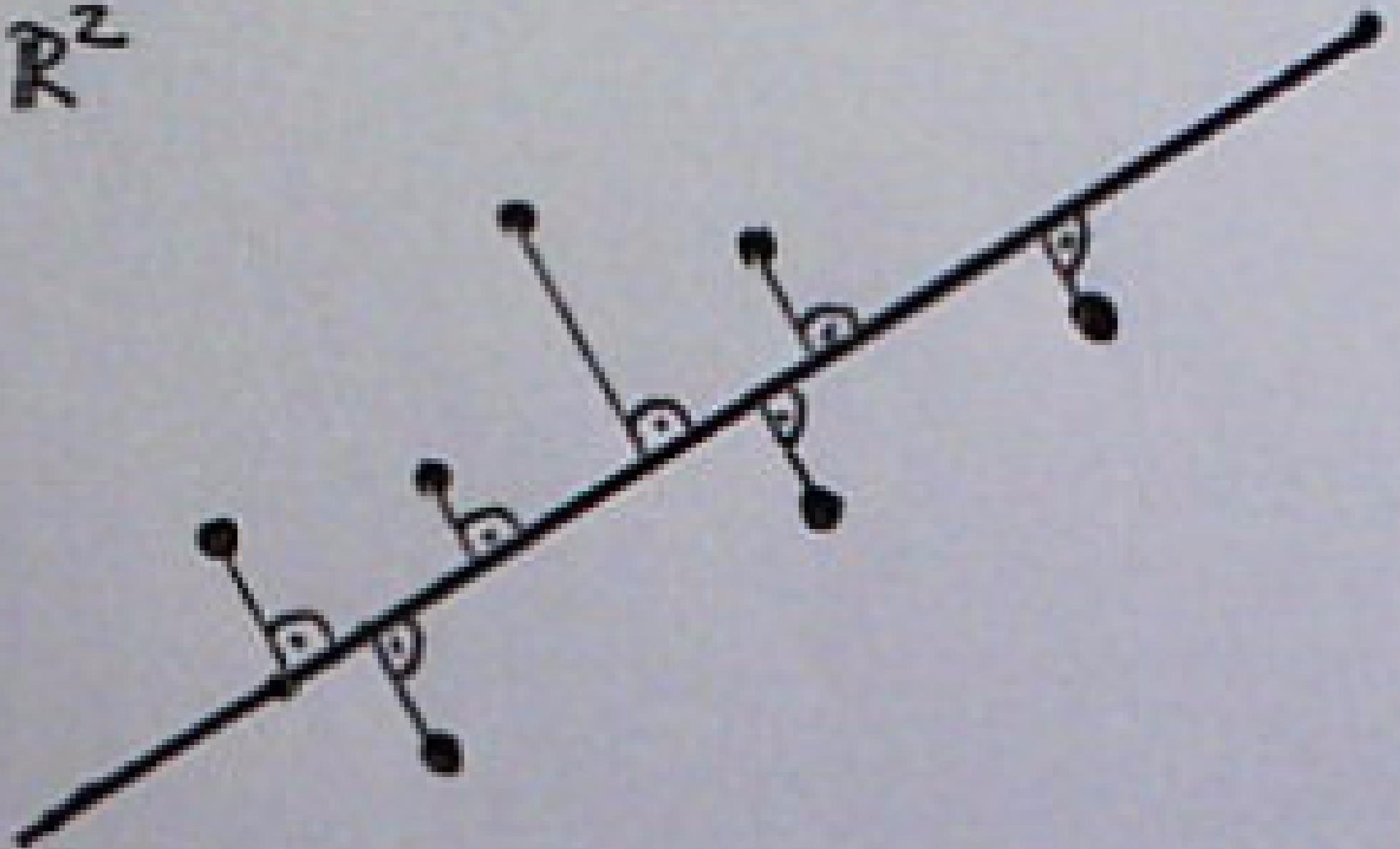




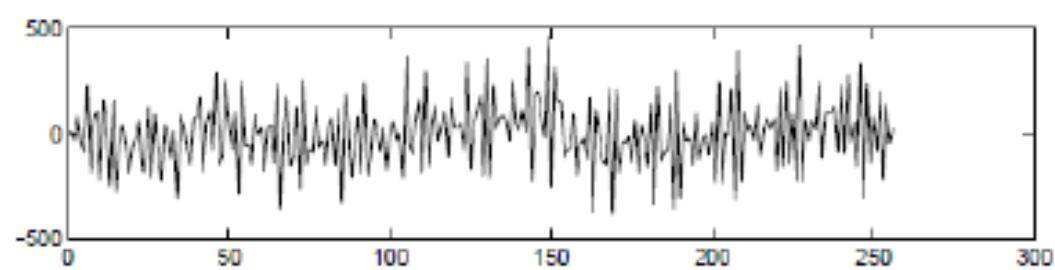
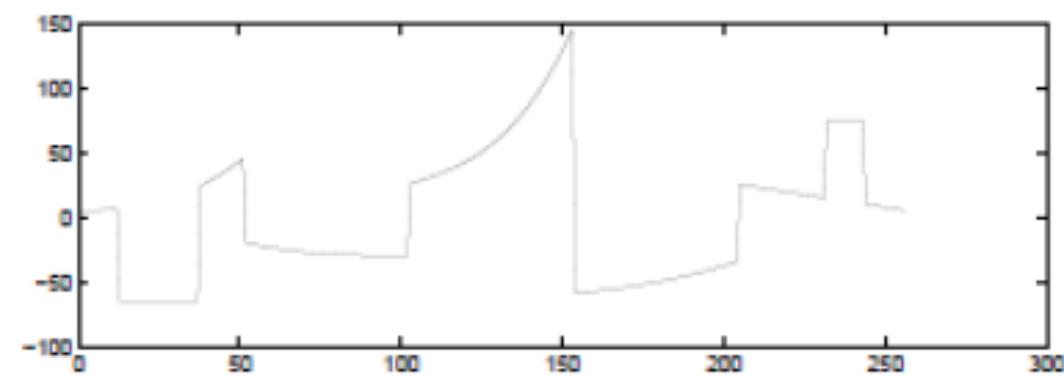
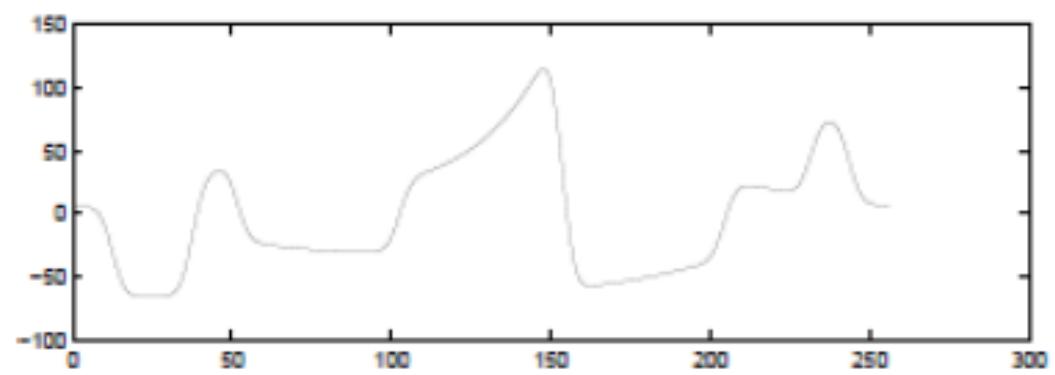
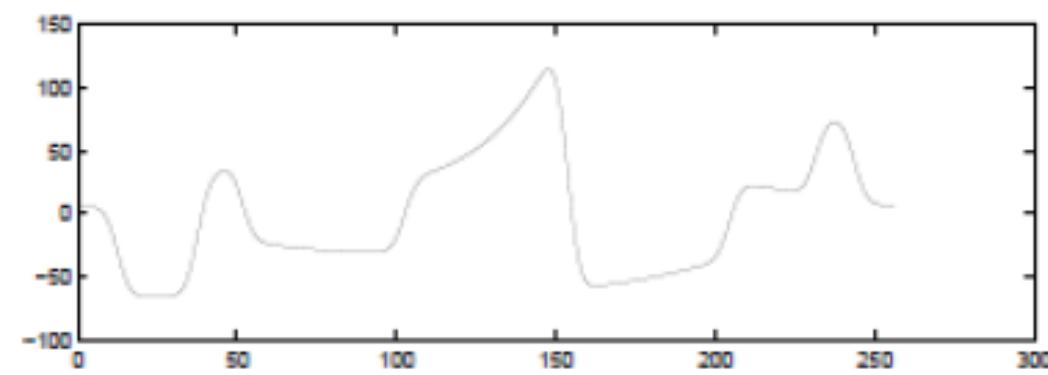


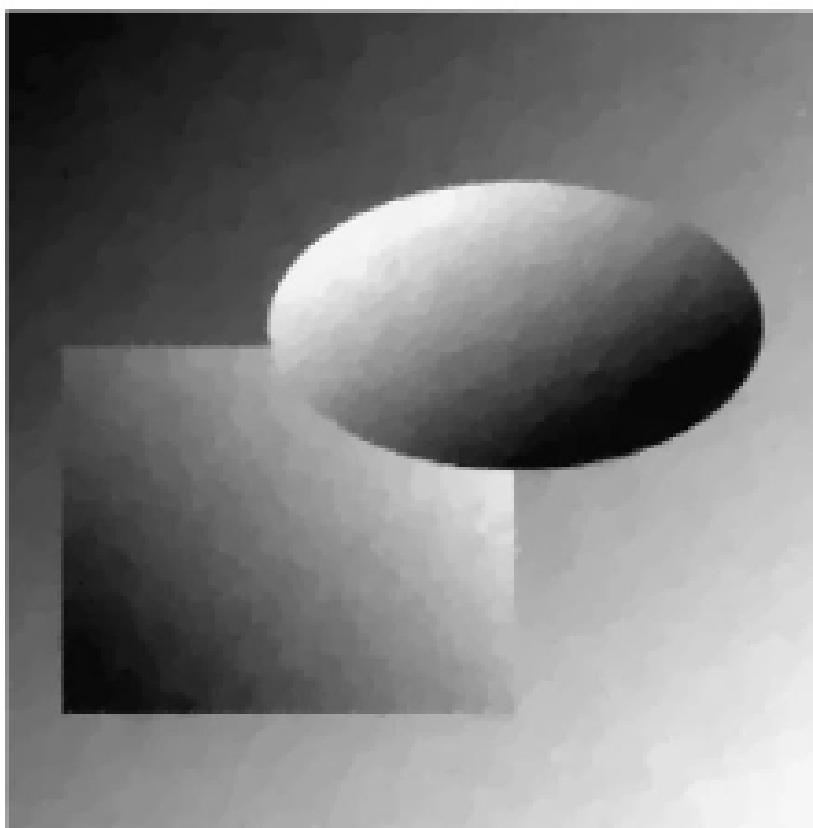
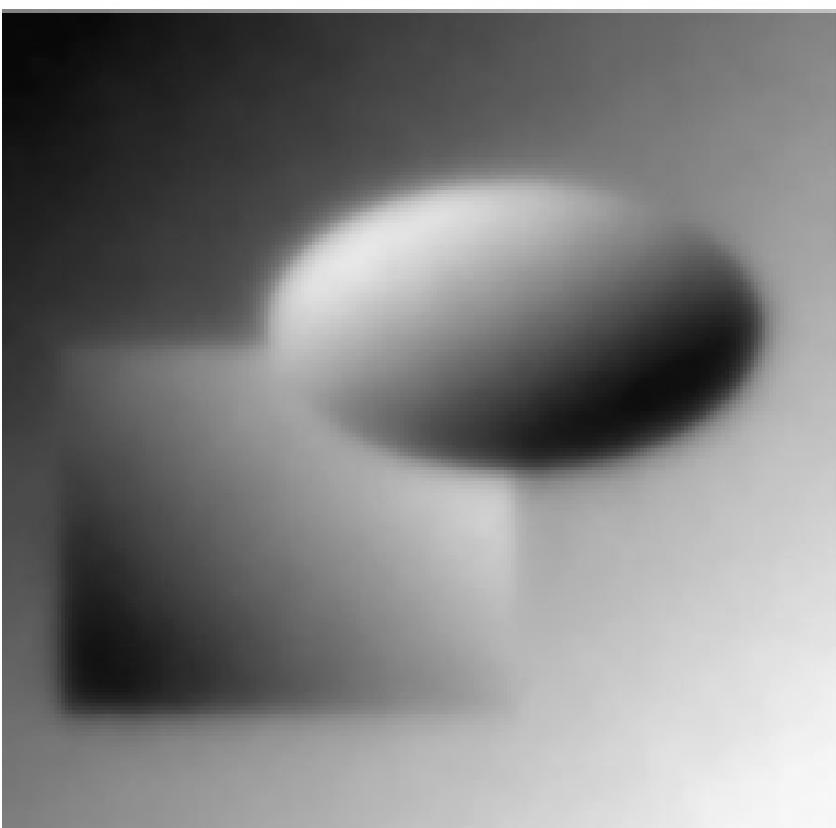
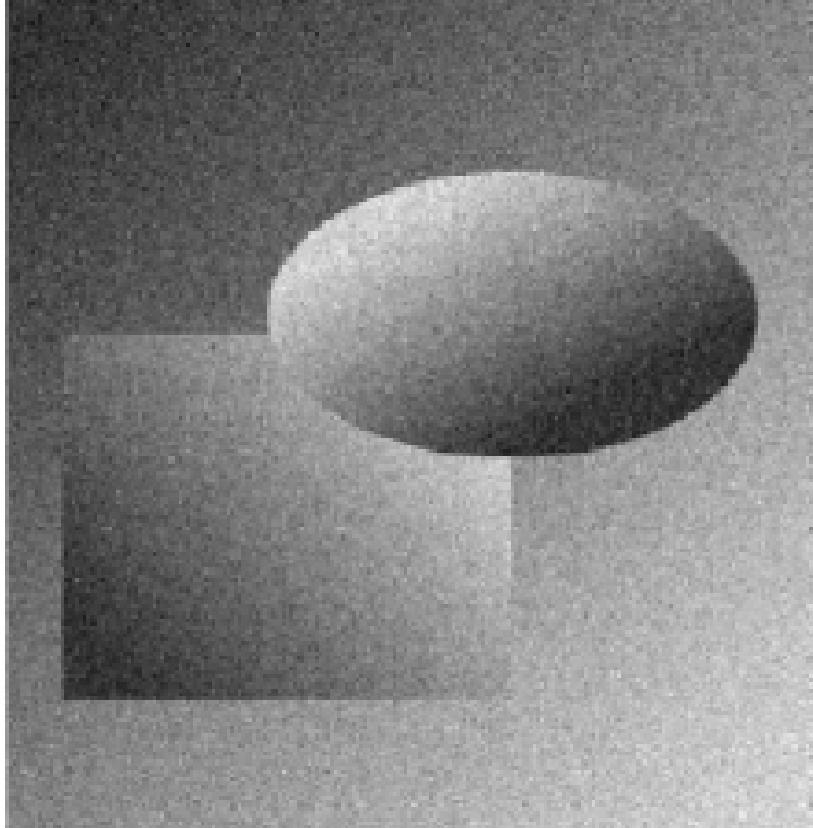
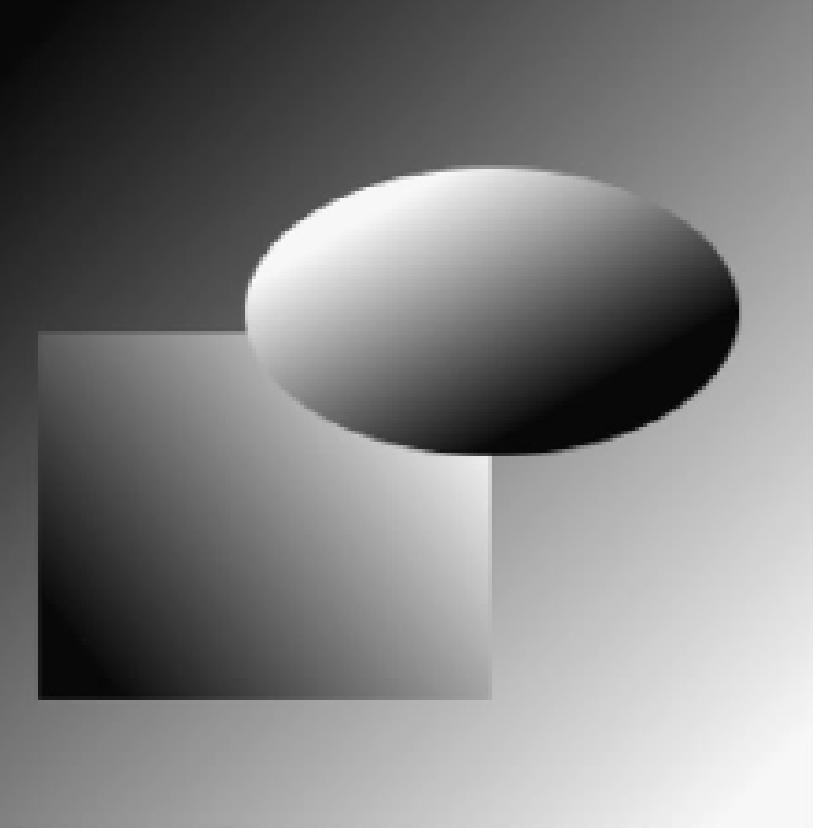


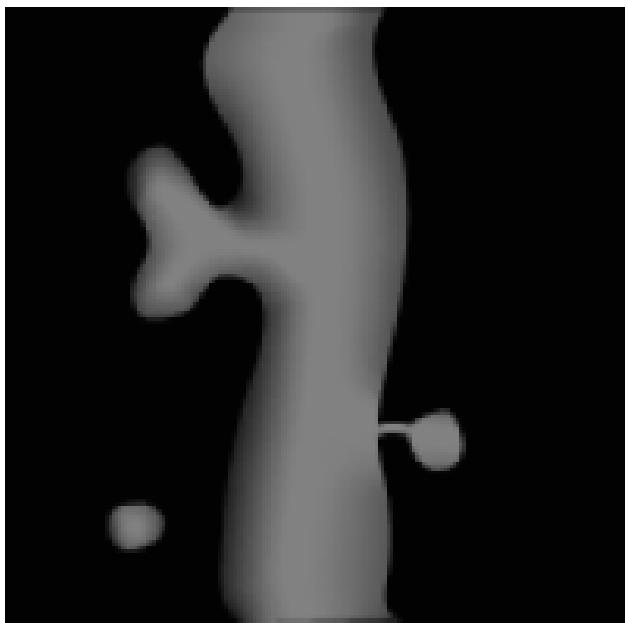


$\mathbb{R}^2$ 

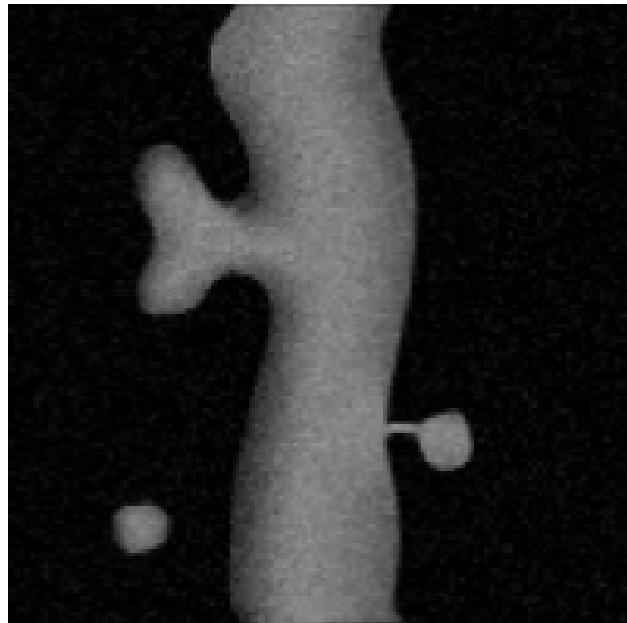




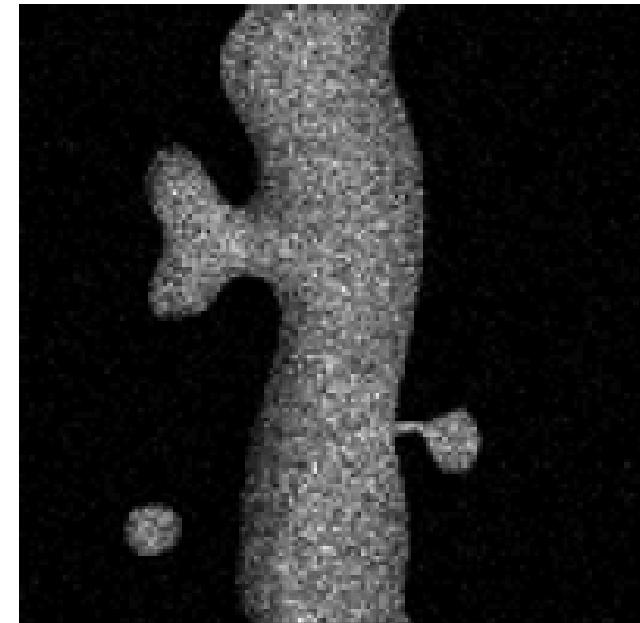




(a) Phantom.

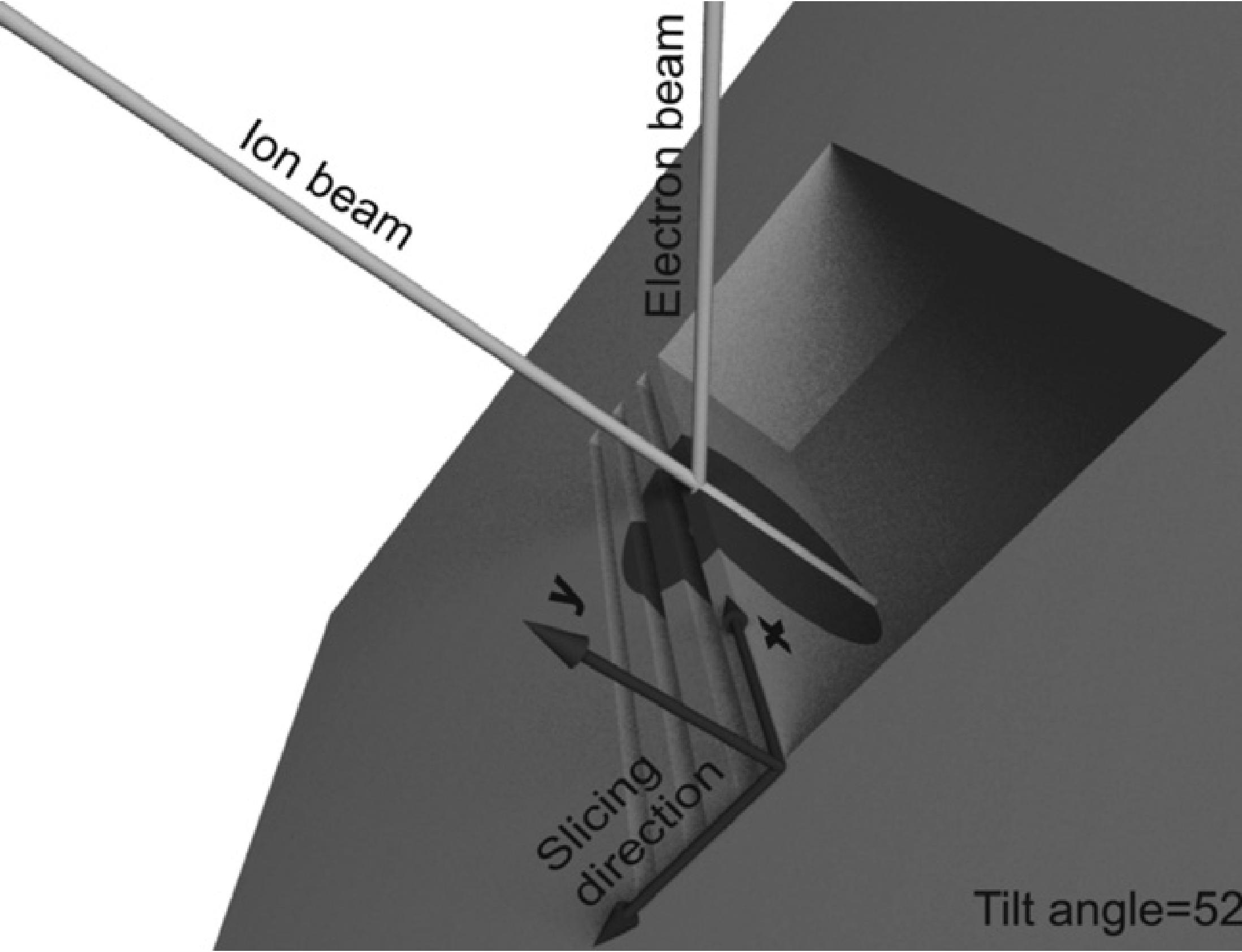


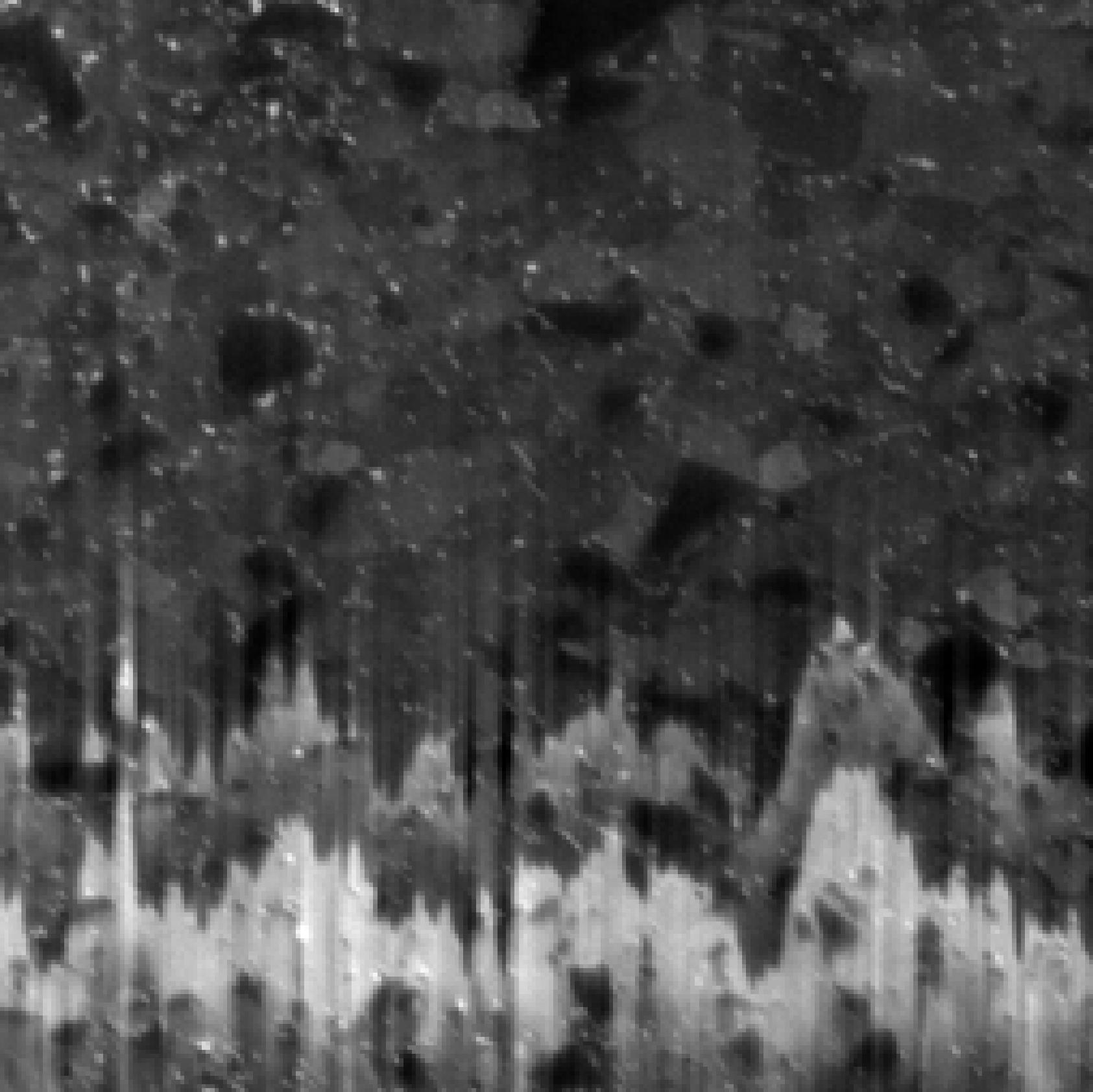
(b) Gaussian noise.

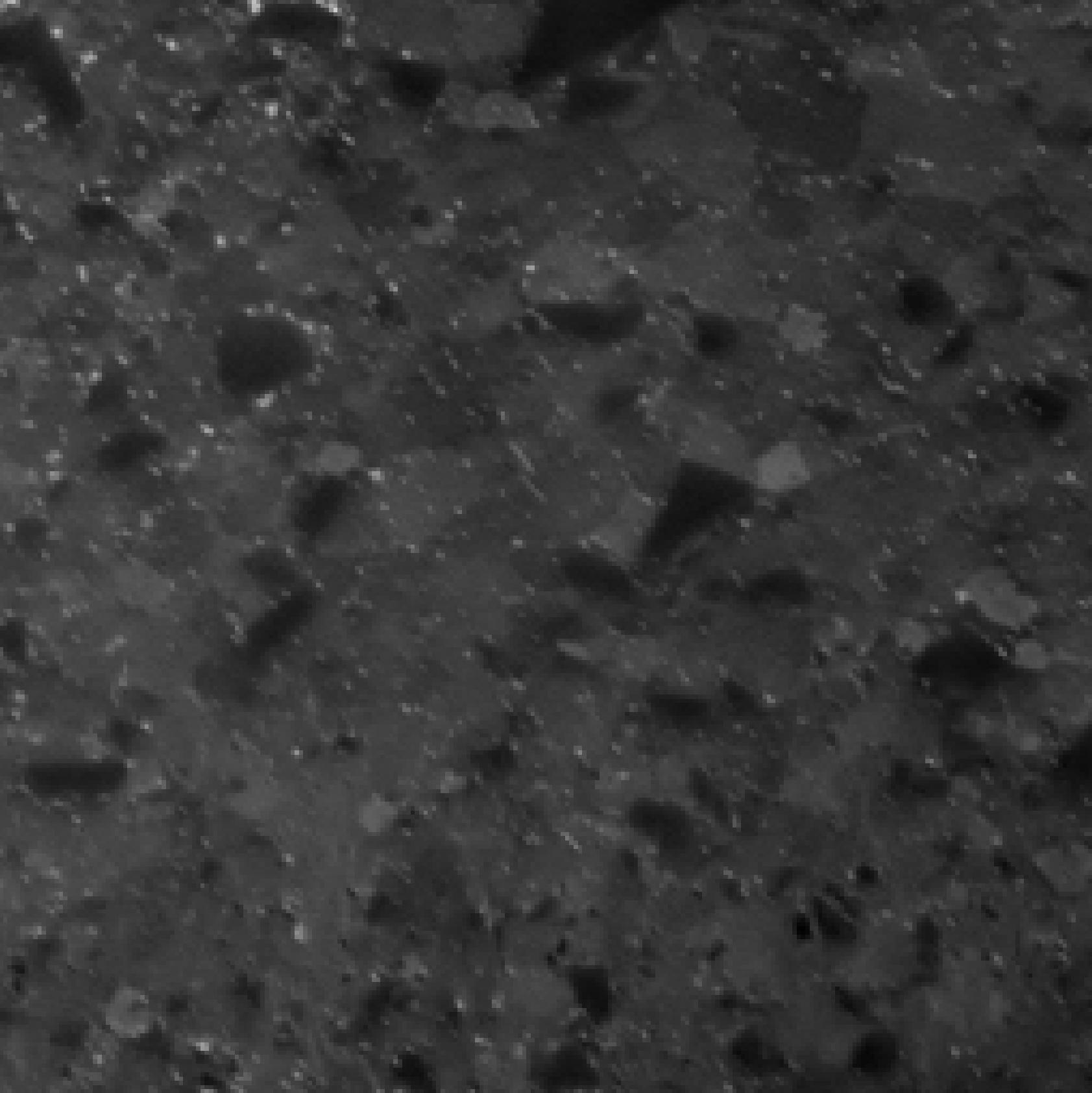


(c) Poisson noise

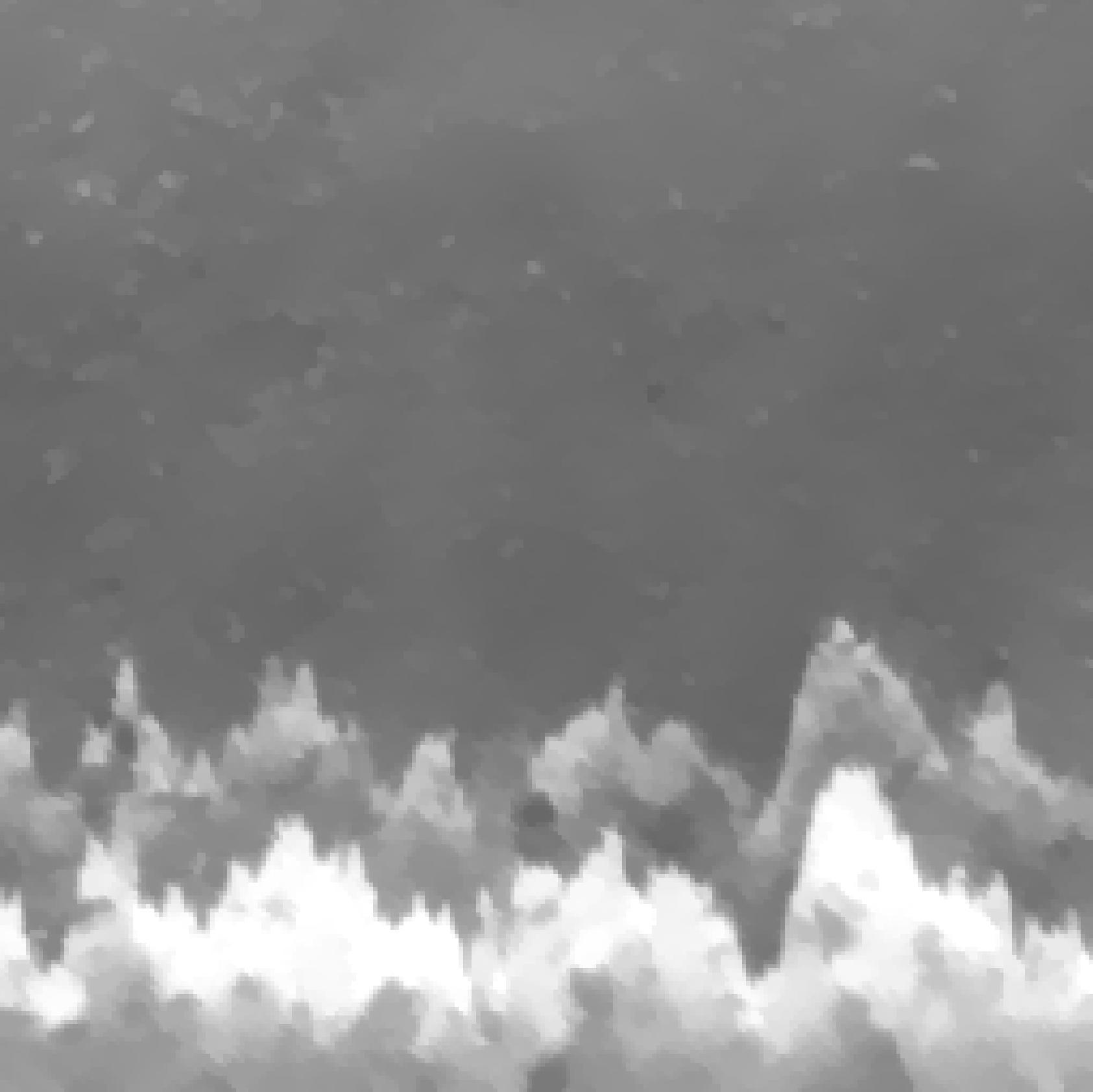




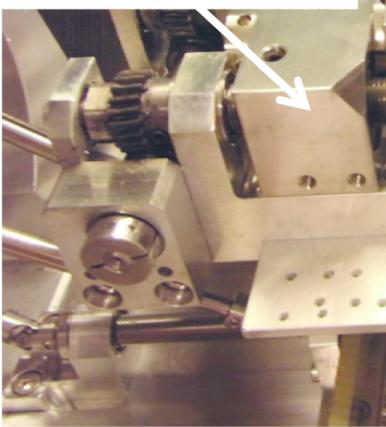




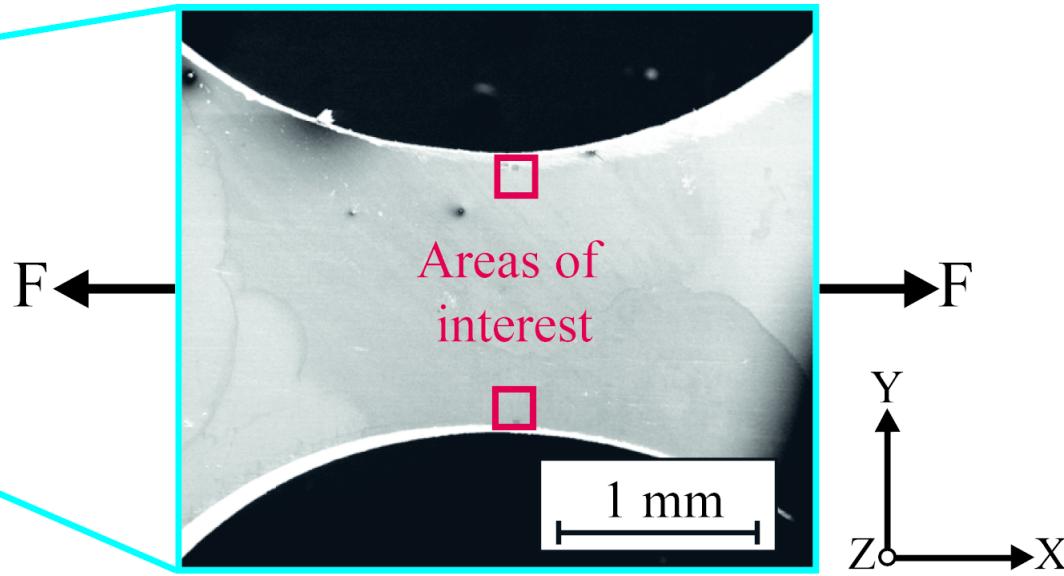
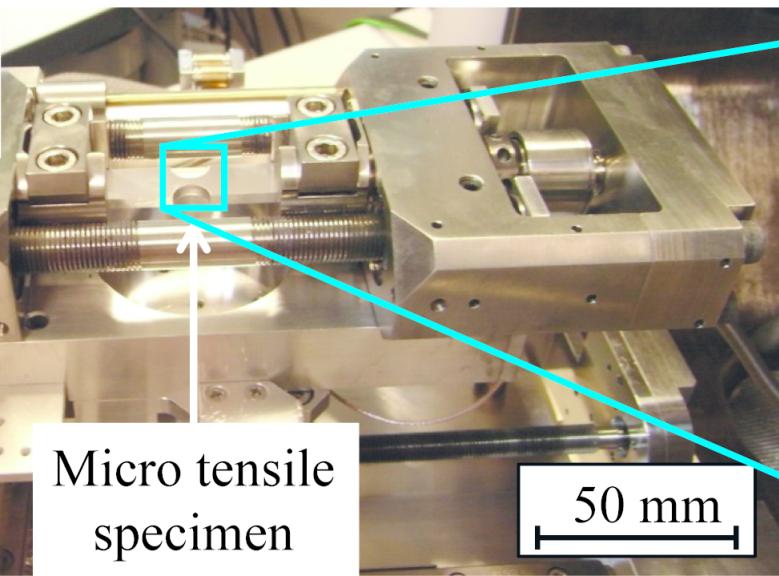


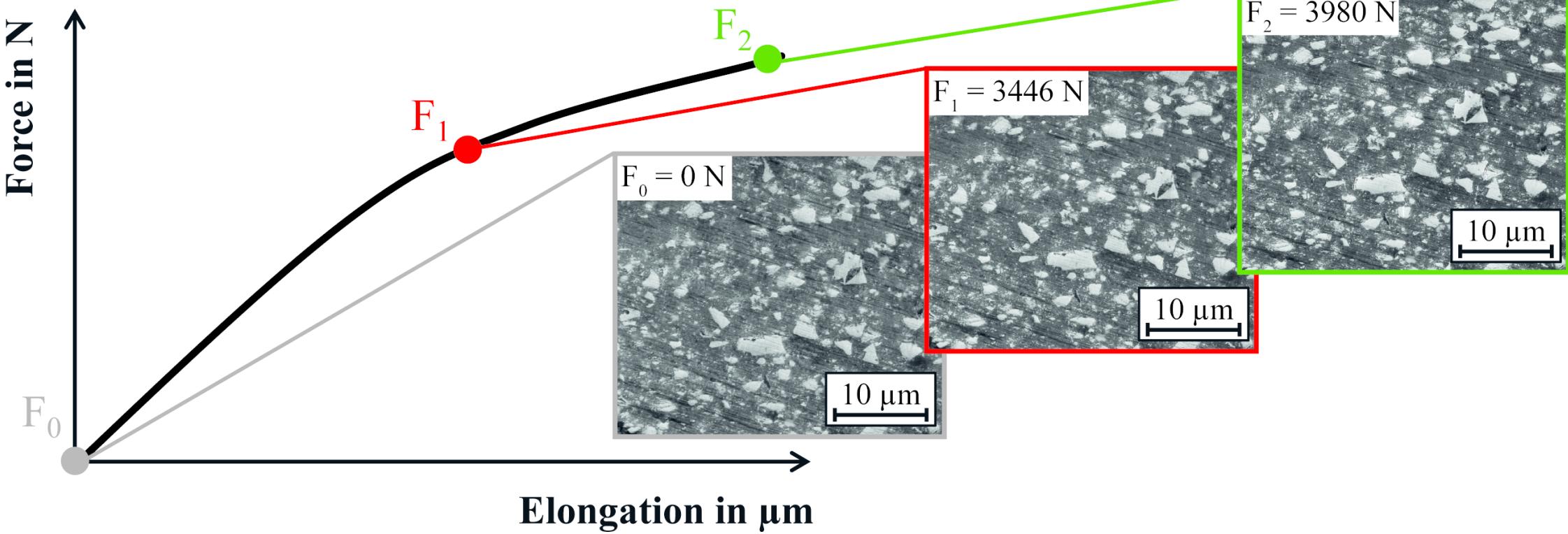


Mechanical loading system

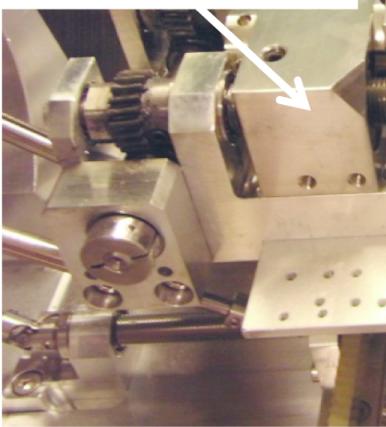


Micro tensile specimen

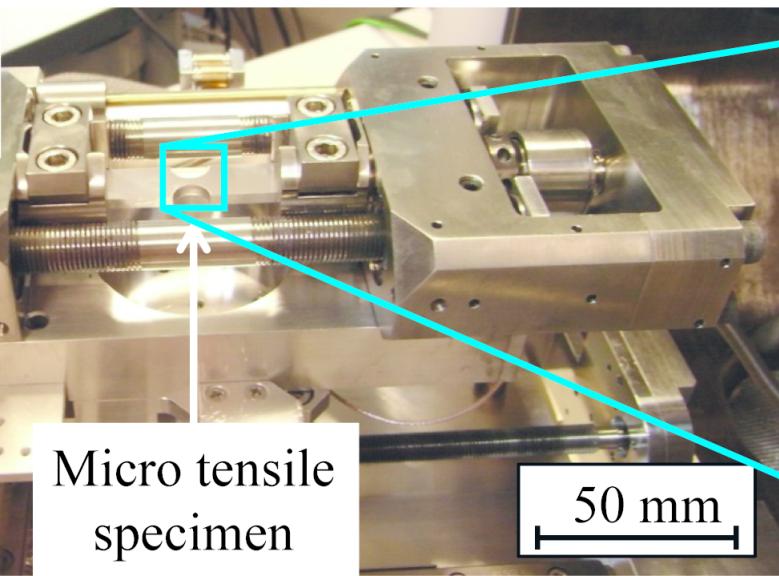




Mechanical loading system

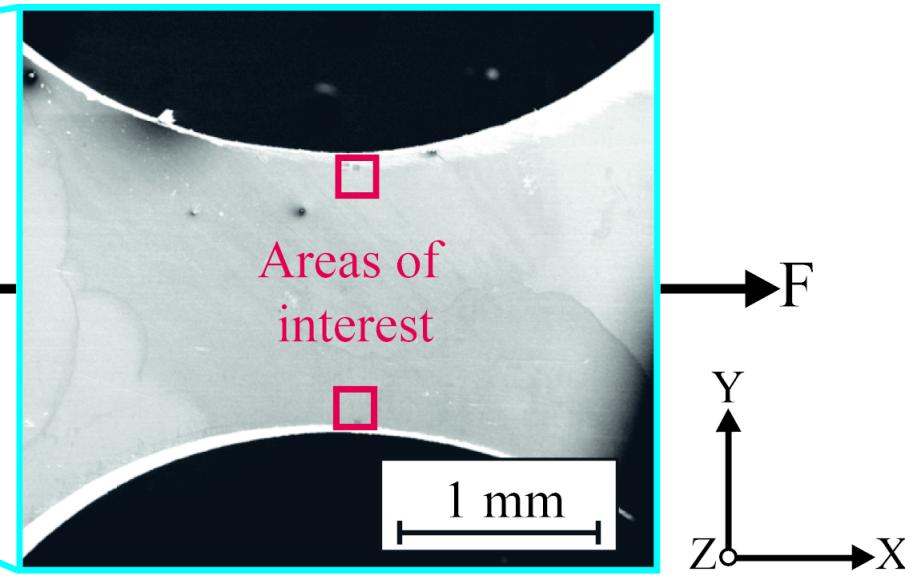


Micro tensile specimen



50 mm

$F \leftarrow$



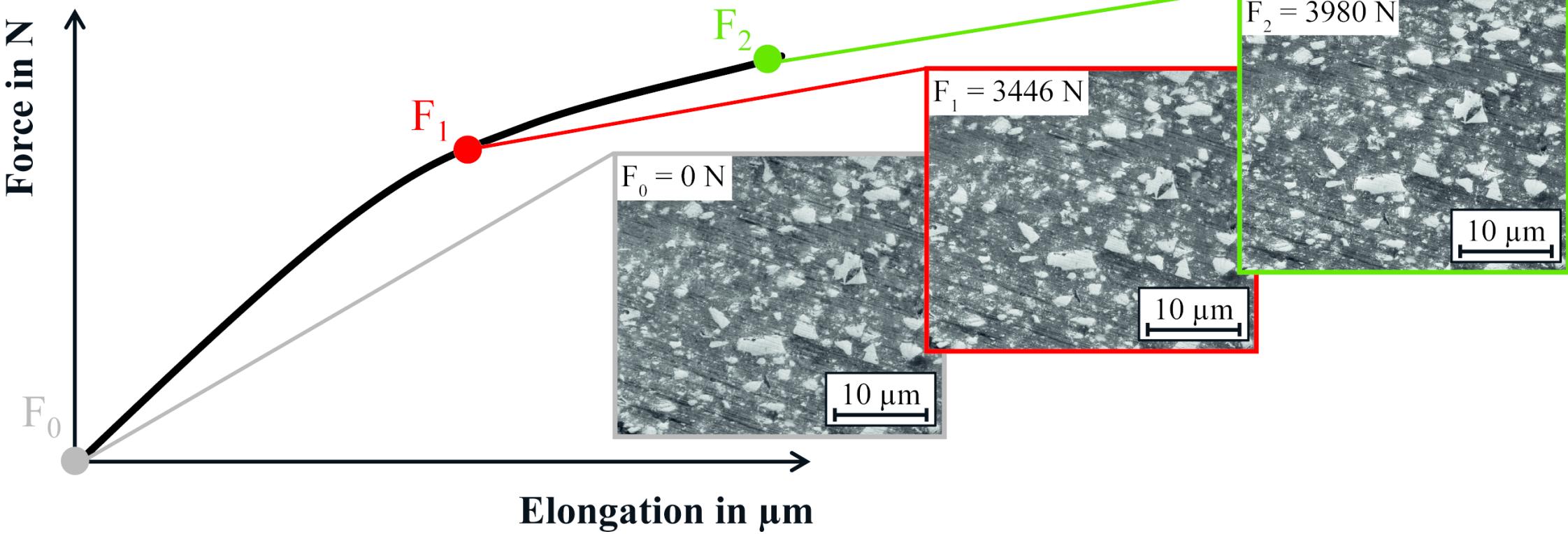
Areas of interest

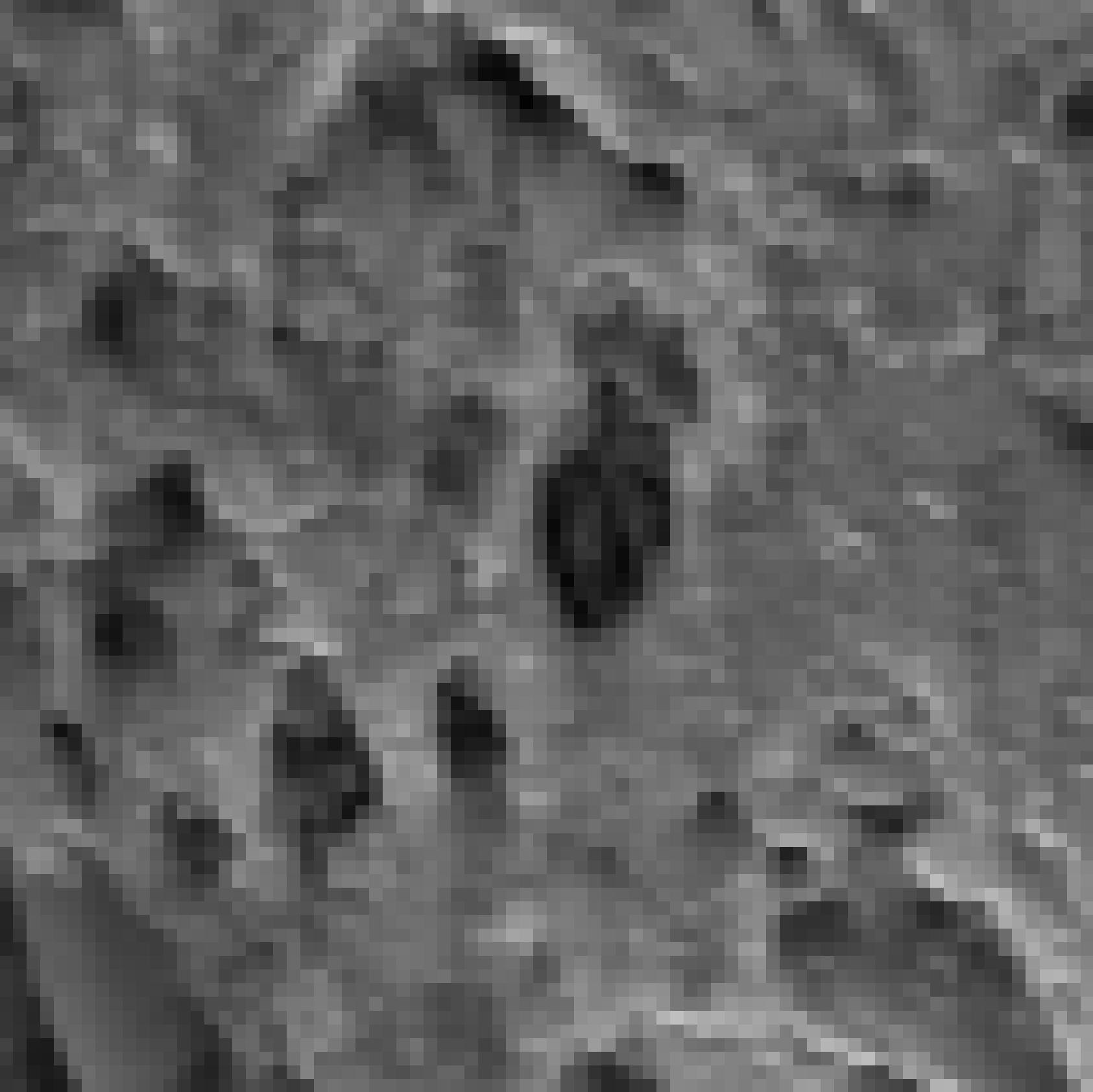


1 mm

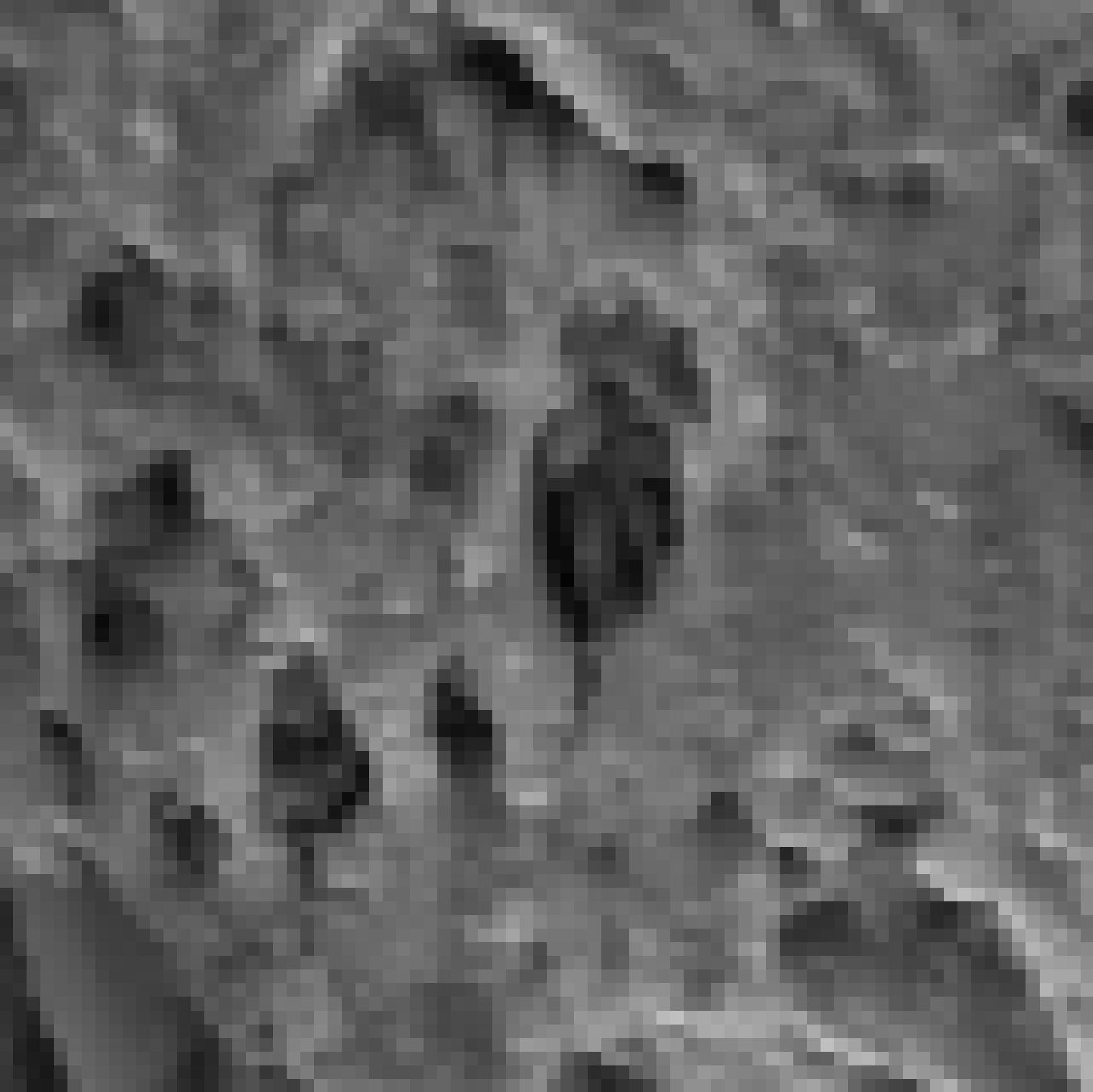
$F \rightarrow$

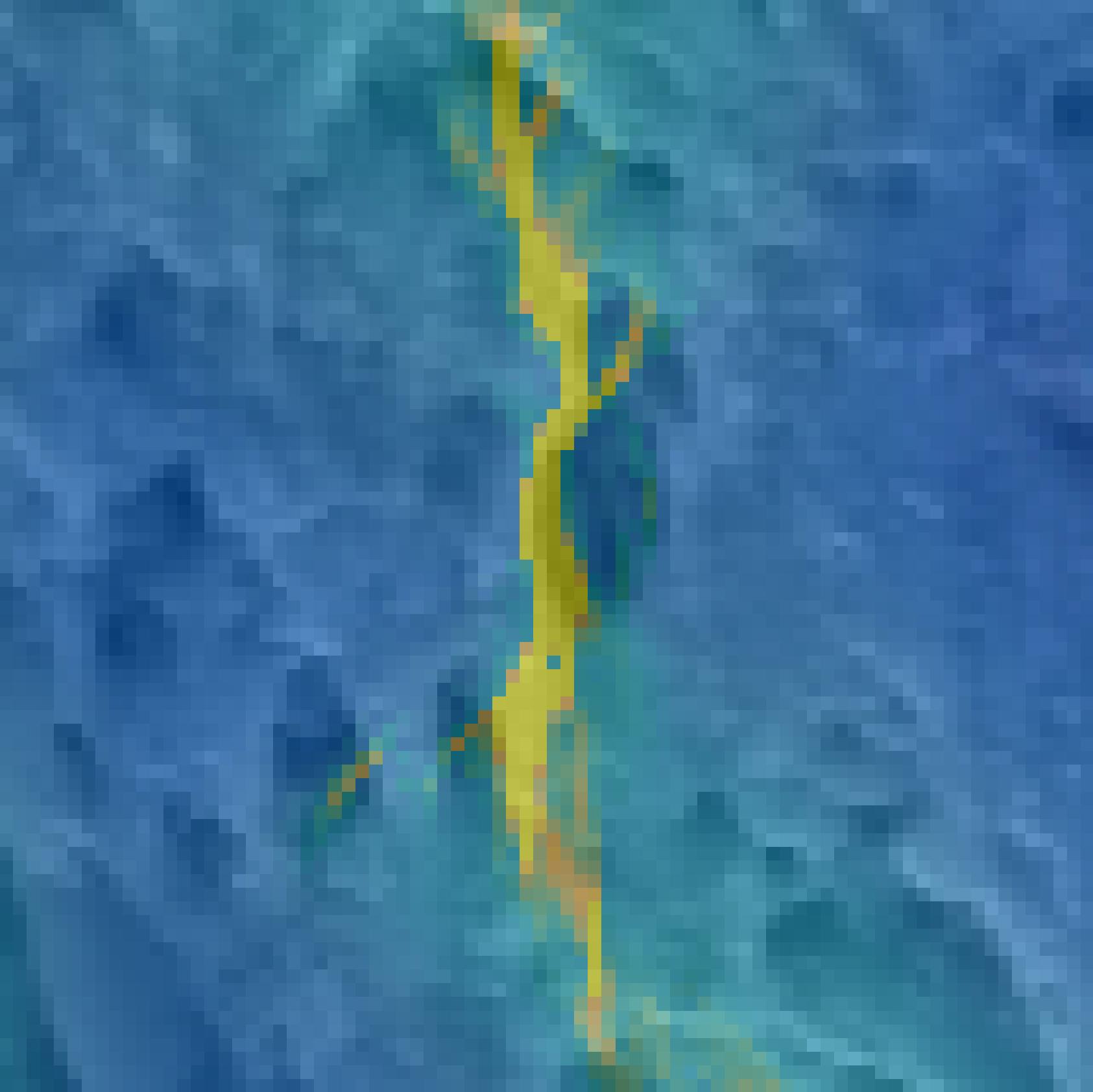
Y  
Z  
X

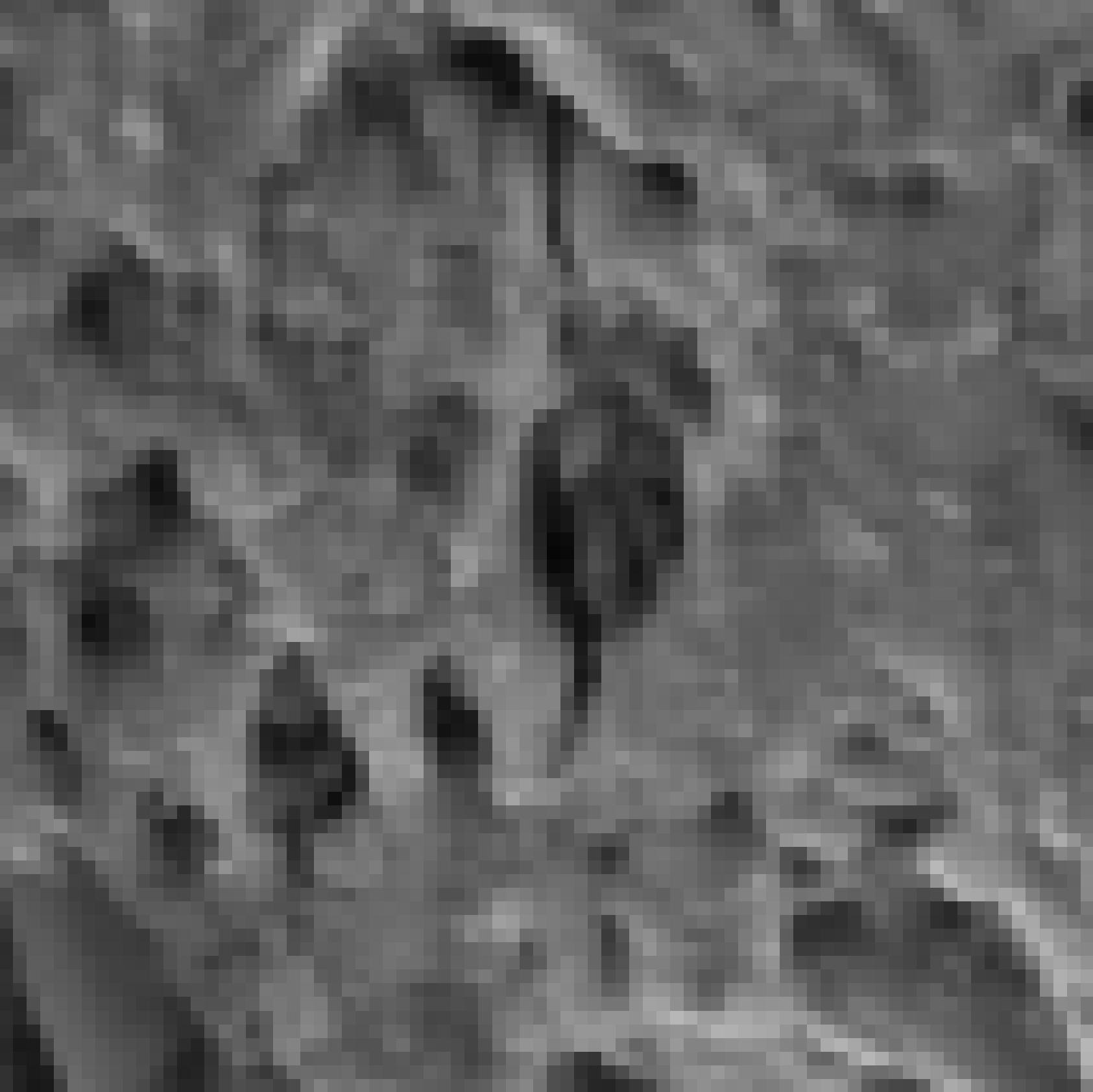


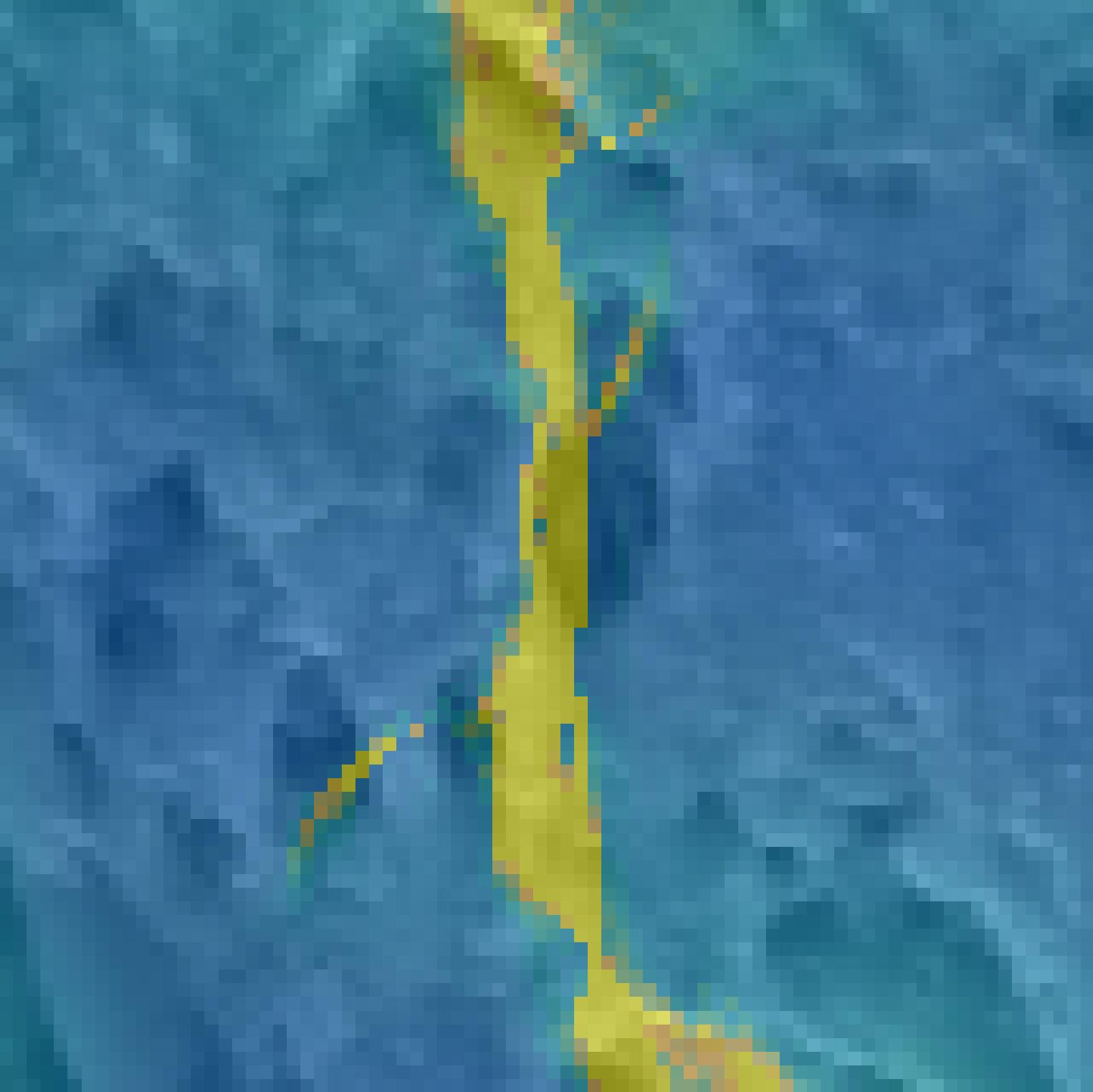


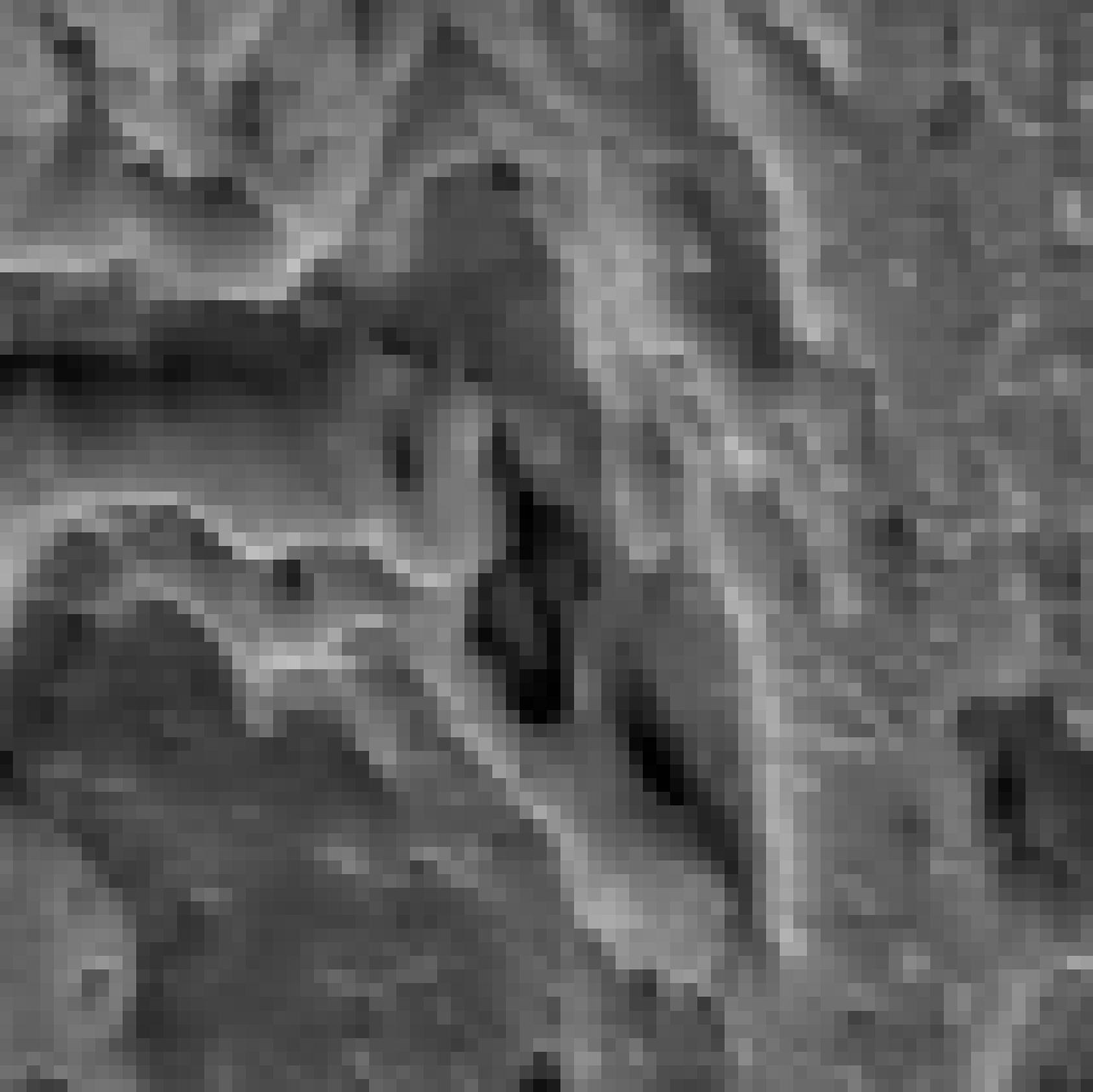


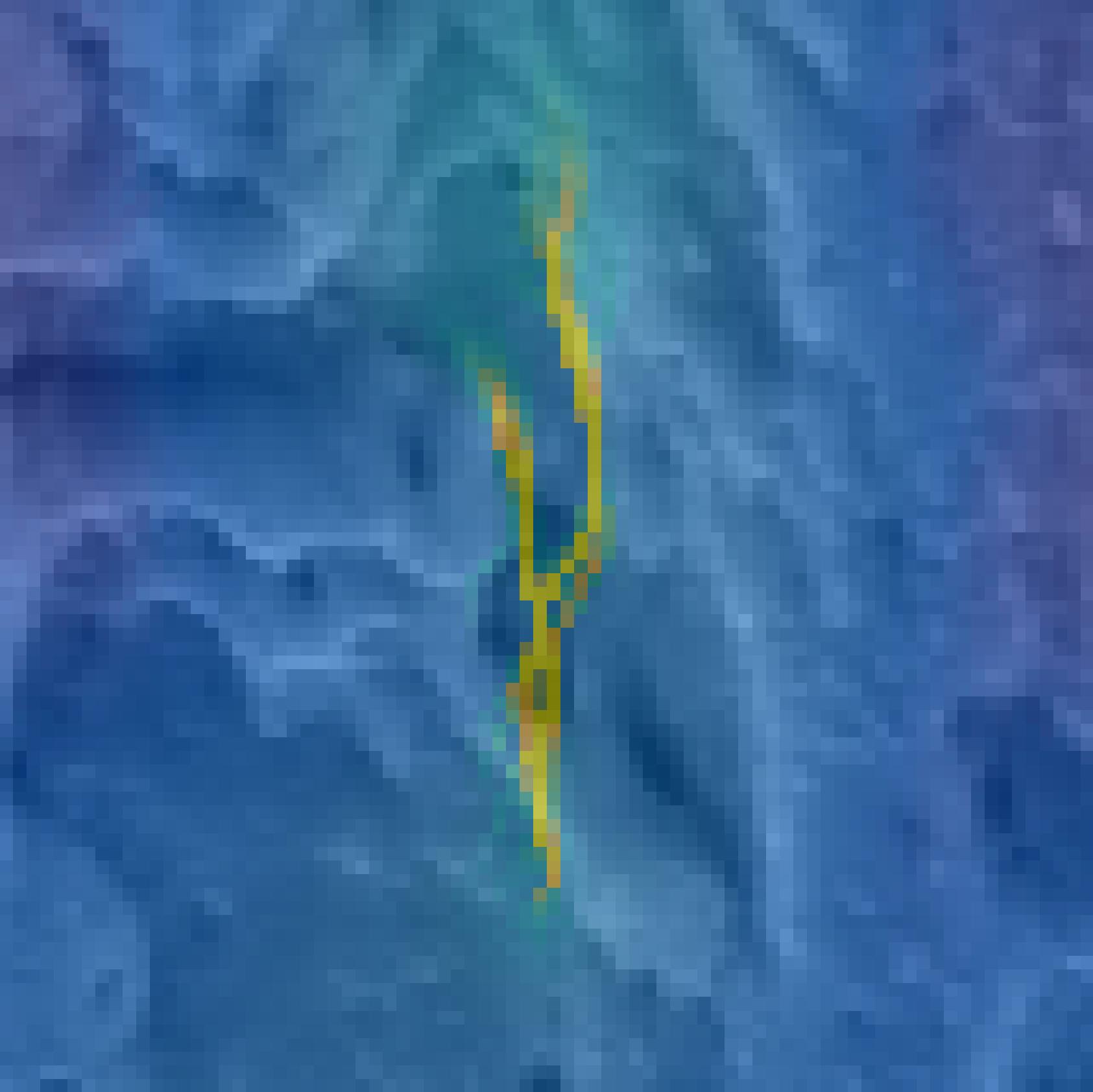


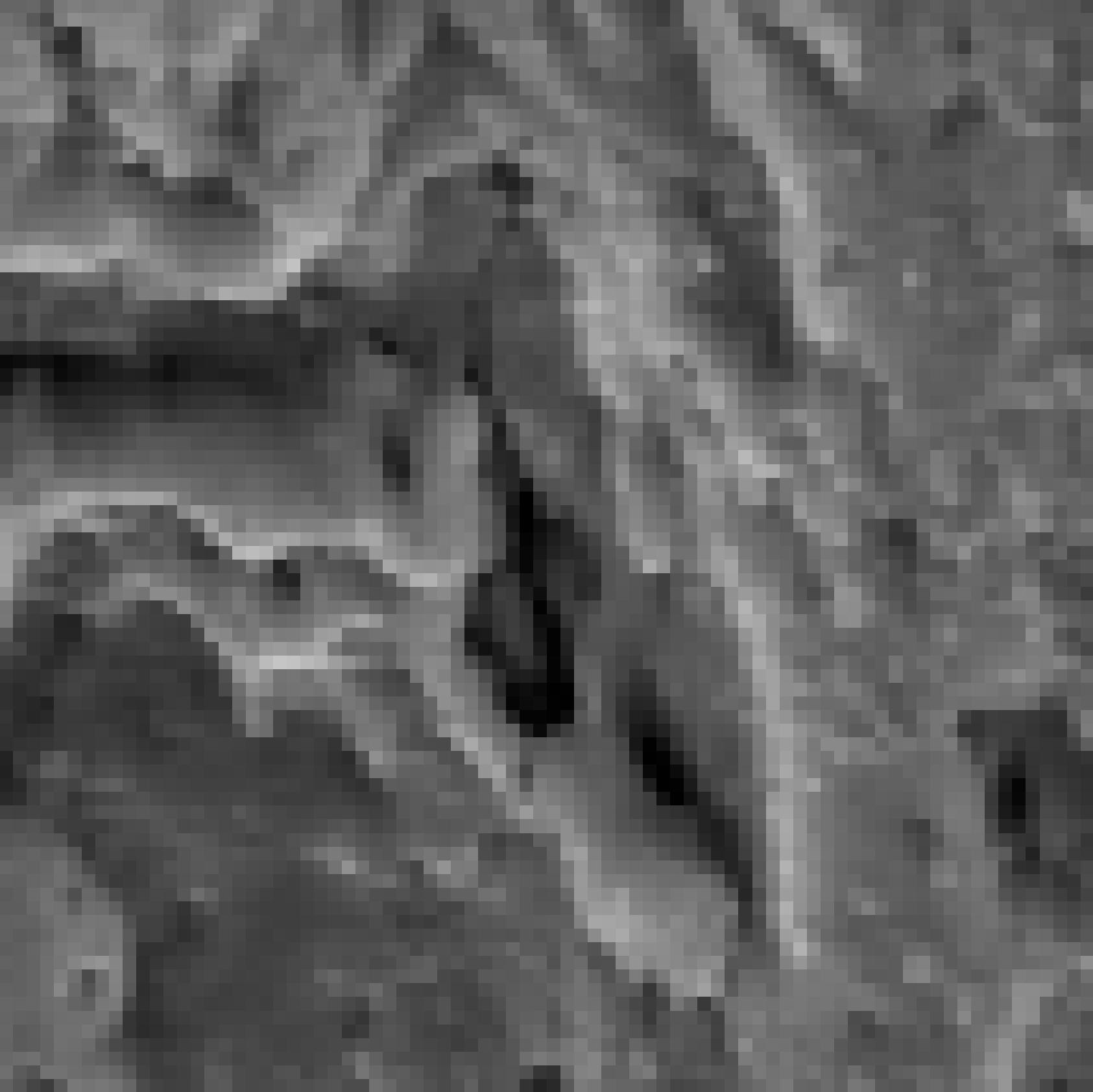


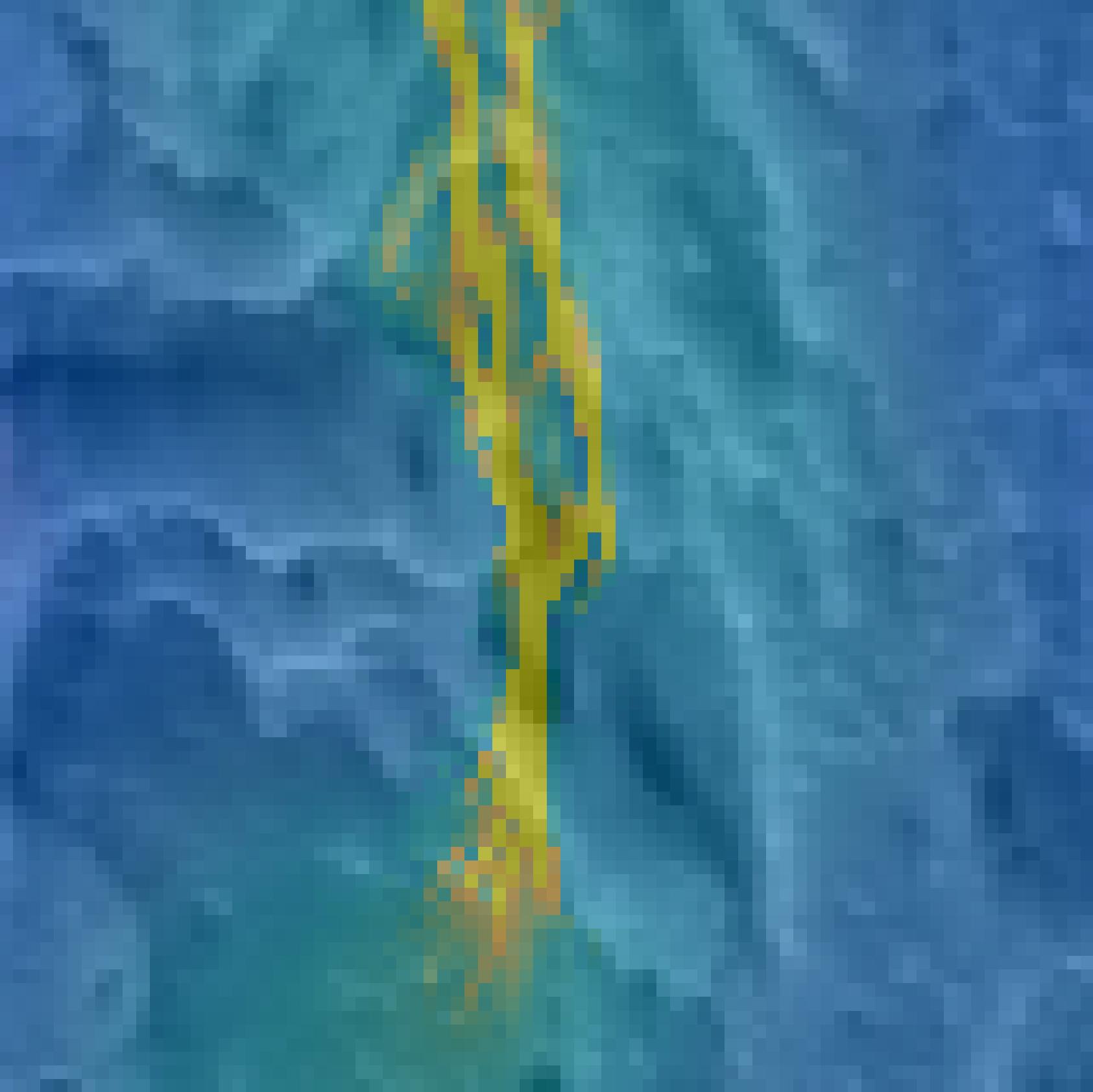


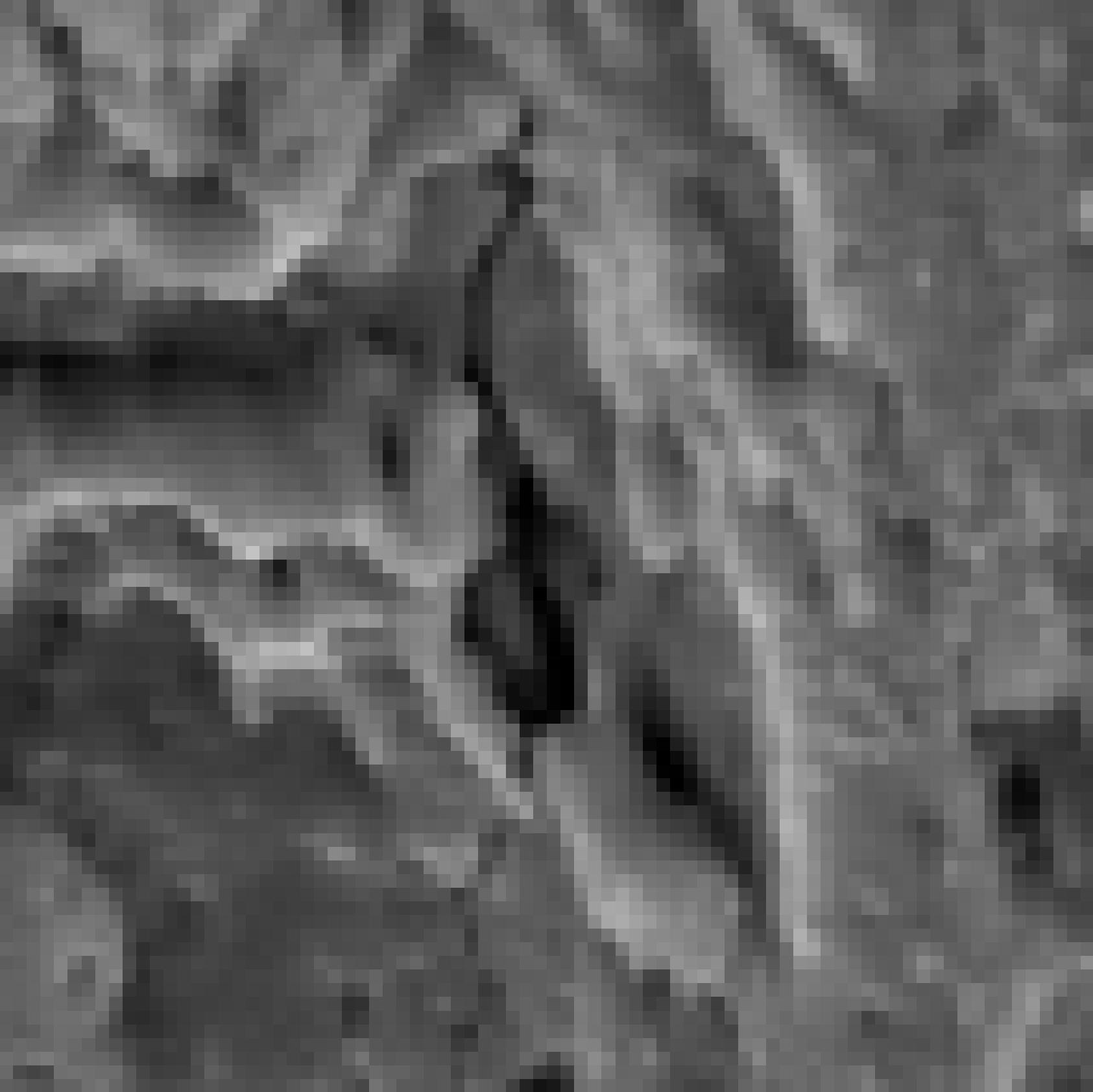


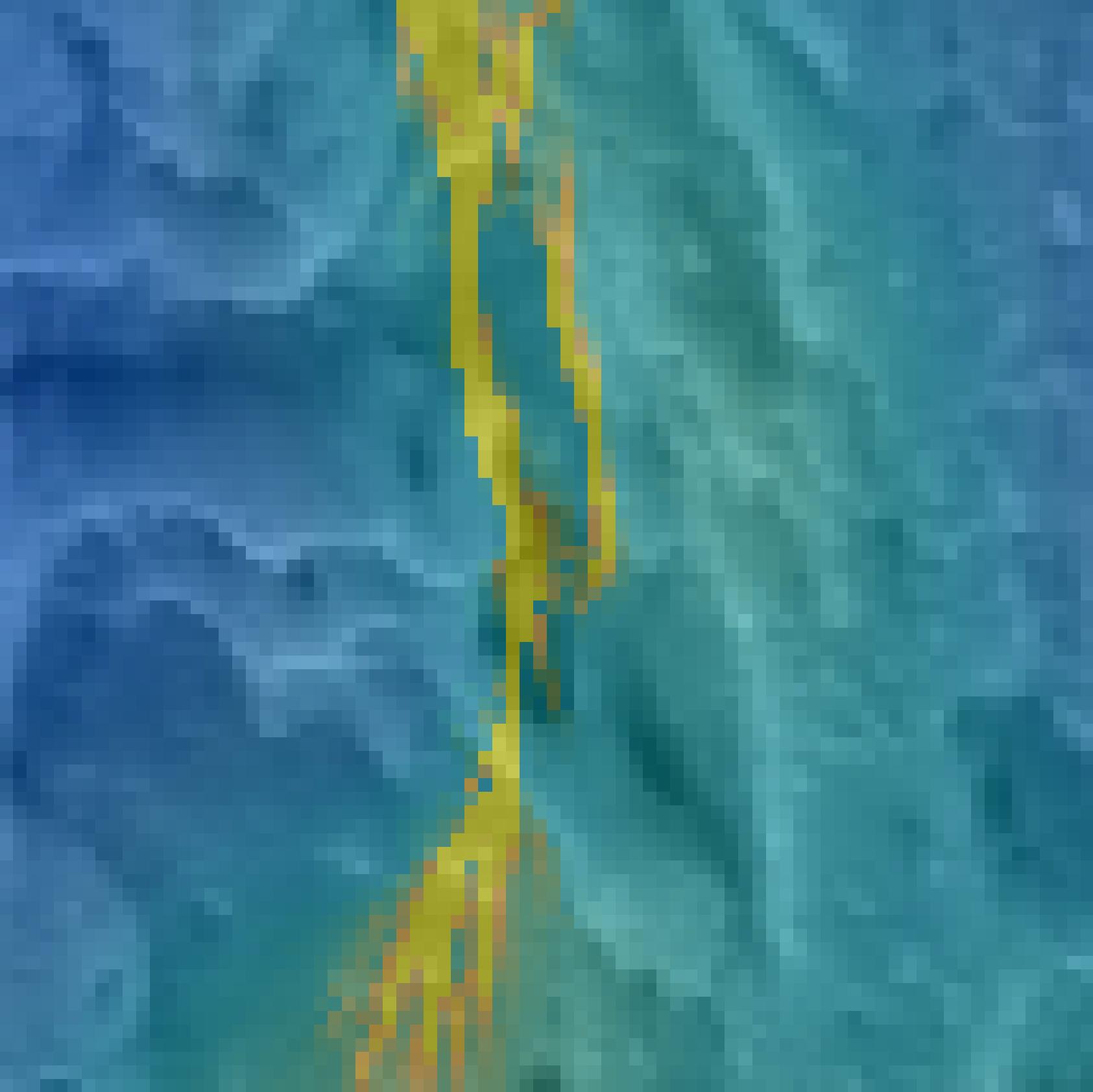














(a)



(b)



(c)



(d)



(e)



(f)

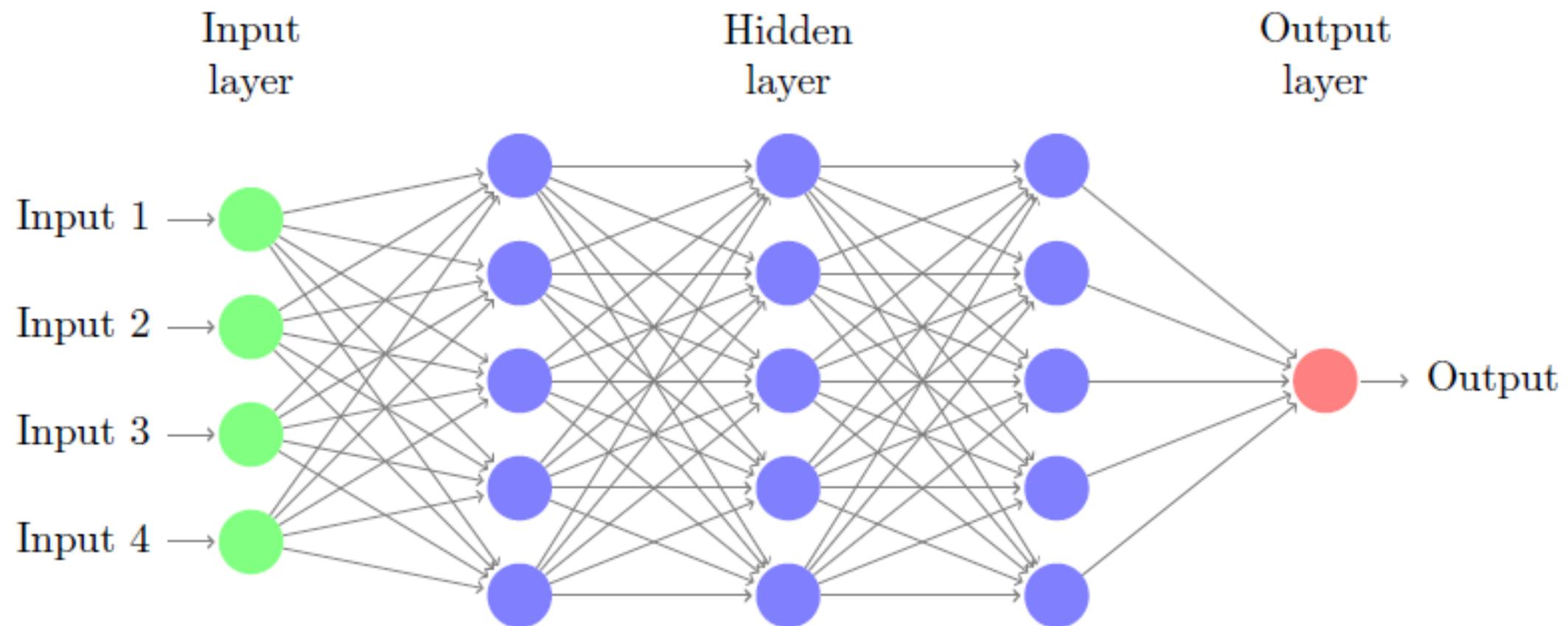
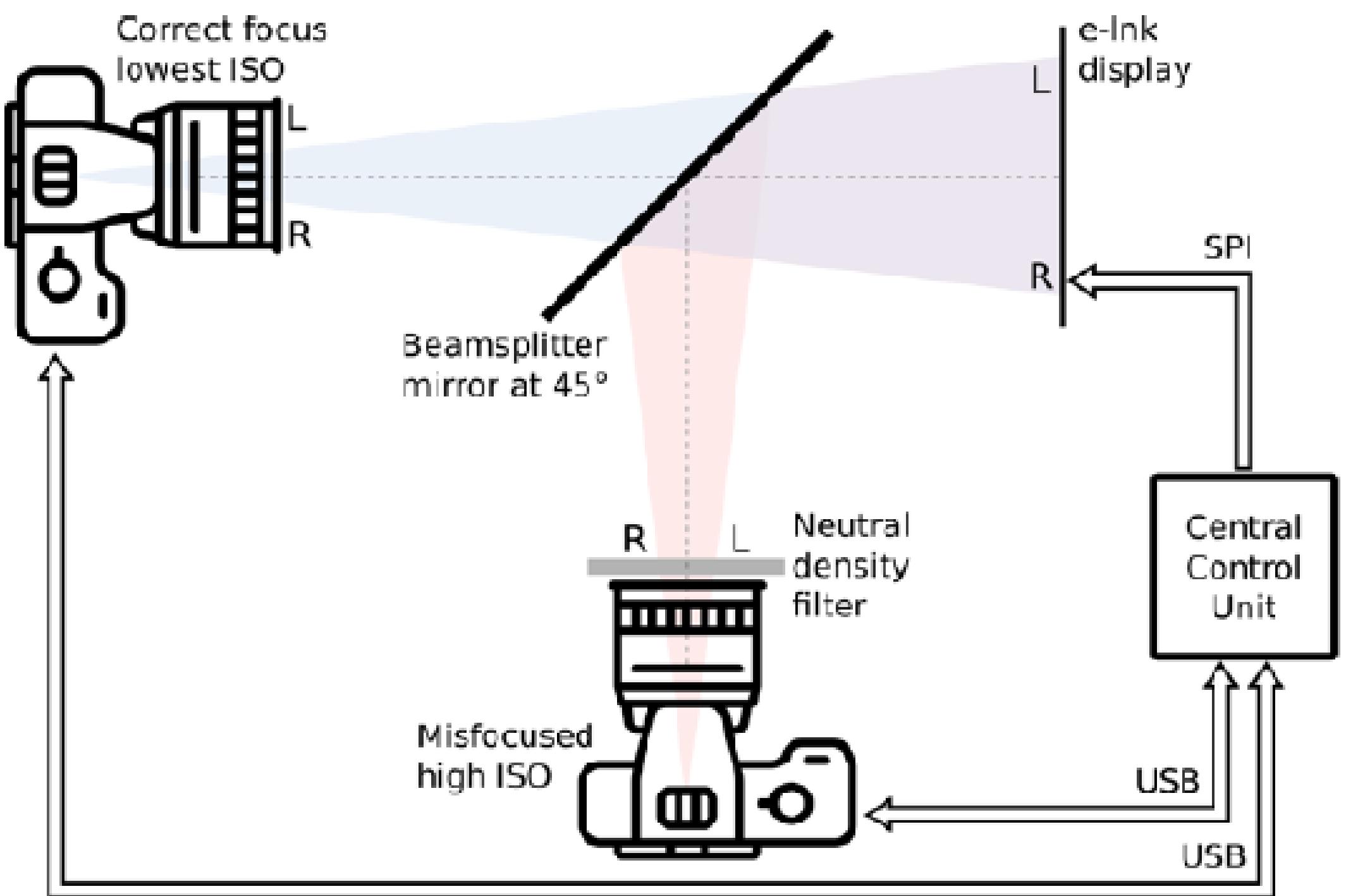


Figure 1: Model of a NN with three hidden layers, i.e.,  $d = 4$ ,  $K = 4$ ,  $n_1 = n_2 = n_3 = 5$ ,  $n_4 = 1$ .





|  |  |  |  |  |  |  |   |   |
|--|--|--|--|--|--|--|---|---|
| ZJXDGCiruE<br>KrextmkKeC<br>gSvmJmJEKE | ZJXDGCiruE<br>KrextmkKeC<br>gSvmJmJEKE | original characters:<br>ZJXDGCiruE<br>KrextmkKeC<br>gSvmJmJEKE<br>OCR_score: 100.0 |  | TFzATuNQEz<br>jaxigiuhg<br>PwyPYnTapD  | original characters:<br>TFzATuNQEz<br>jaxigiuhg<br>PwyPYnTapD<br>OCR_score: 100.0  |  | zM bisrpeJ<br>UgEEAuDJrT<br>LmfIQAtsV   | original characters:<br>zM bisrpeJ<br>UgEEAuDJrT<br>LmfIQAtsV<br>OCR_score: 90.0    |
| ZuYFSJuNTB<br>NTEXqAPhMa<br>nSxvTbWaYm | ZuYFSJuNTB<br>NTEXqAPhMa<br>nSxvTbWaYm | original characters:<br>ZuYFSJuNTB<br>NTEXqAPhMa<br>nSxvTbWaYm<br>OCR_score: 100.0 |  | NfYGMvQPwy<br>NRBgTRVztp<br>xGCCDnTbsp | original characters:<br>NfYGMvQPwy<br>NRBgTRVztp<br>xGCCDnTbsp<br>OCR_score: 100.0 |  | LxZxvGdD k<br>qLjLnUYKsw<br>anUSQzUhC   | original characters:<br>LxZxvGdD k<br>qLjLnUYKsw<br>anUSQzUhC<br>OCR_score: 100.0   |
| UNLtUSwXtP<br>DJJHWwEuWY<br>RXEgjKSpXC | UNLtUSwXtP<br>DJJHWwEuWY<br>RXEgjKSpXC | original characters:<br>UNLtUSwXtP<br>DJJHWwEuWY<br>RXEgjKSpXC<br>OCR_score: 95.0  |  | YdJb sHvRp<br>QdZYcfCEHP<br>hwuqjf YCD | original characters:<br>YdJb sHvRp<br>QdZYcfCEHP<br>hwuqjf YCD<br>OCR_score: 100.0 |  | fFSBTpYUVr<br>UWgBWdscMe<br>nxNBemjY j  | original characters:<br>fFSBTpYUVr<br>UWgBWdscMe<br>nxNBemjY j<br>OCR_score: 100.0  |
| cXF XfnuLM<br>ueBwRquMYc<br>vpSYztfNTM | cXF XfnuLM<br>ueBwRquMYc<br>vpSYztfNTM | original characters:<br>cXF XfnuLM<br>ueBwRquMYc<br>vpSYztfNTM<br>OCR_score: 90.0  |  | mZrgnyULjJ<br>gjSmxAvcNe<br>sSh AfFWsf | original characters:<br>mZrgnyULjJ<br>gjSmxAvcNe<br>sSh AfFWsf<br>OCR_score: 100.0 |  | SutLMcqJsB<br>asqmfmVyqh<br>gvE bmrnMQt | original characters:<br>SutLMcqJsB<br>asqmfmVyqh<br>gvE bmrnMQt<br>OCR_score: 100.0 |
| uQNGzUpgdQ<br>FHuxtmckpB<br>fkhuhvPjyh | uQNGzUpgdQ<br>FHuxtmckpB<br>fkhuhvPjyh | original characters:<br>uQNGzUpgdQ<br>FHuxtmckpB<br>fkhuhvPjyh<br>OCR_score: 100.0 |  | TvLzQgcWfE<br>LCwJPCssYb<br>Rwbt xcYxT | original characters:<br>TvLzQgcWfE<br>LCwJPCssYb<br>Rwbt xcYxT<br>OCR_score: 100.0 |  | SRyDbchI<br>zCFZBCfPBF<br>zfiyyMXqkD    | original characters:<br>SRyDbchI<br>zCFZBCfPBF<br>zfiyyMXqkD<br>OCR_score: 90.0     |
| PJqwpYrQQs<br>mbdaBVWnqB<br>tfdJHkbZwp | PJqwpYrQQs<br>mbdaBVWnqB<br>tfdJHkbZwp | original characters:<br>PJqwpYrQQs<br>mbdaBVWnqB<br>tfdJHkbZwp<br>OCR_score: 90.0  |  | TNUswyRbjq<br>mTDPVeEDjd<br>TSBWRNsfEB | original characters:<br>TNUswyRbjq<br>mTDPVeEDjd<br>TSBWRNsfEB<br>OCR_score: 100.0 |  | wffHxXXaEc<br>SWUQumRdPn<br>egSeovDYC   | original characters:<br>wffHxXXaEc<br>SWUQumRdPn<br>egSeovDYC<br>OCR_score: 80.0    |
| TtEHBnWNQg<br>PjCZiwGDkW<br>ubcDvzAZeF | TtEHBnWNQg<br>PjCZiwGDkW<br>ubcDvzAZeF | original characters:<br>TtEHBnWNQg<br>PjCZiwGDkW<br>ubcDvzAZeF<br>OCR_score: 100.0 |  | dmCSzMD np<br>fniCLxztPg<br>xsuuPEKziC | original characters:<br>dmCSzMD np<br>fniCLxztPg<br>xsuuPEKziC<br>OCR_score: 100.0 |  |   |   |

