

Duality for Unit-Commitment

Primal Heuristics

Noisy Oracle

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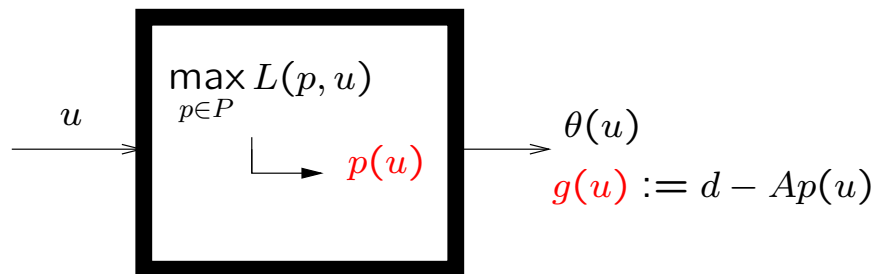
Recalls I: Lagrangian Relaxation

Hard Problem

$$\max_{p \in P} c^\top p, \quad Ap = d \in \mathbb{R}^m$$

Easy pb: Given $u \in \mathbb{R}^m$

$$\left[\max_{p \in P} L(p, u) := c^\top p + u^\top (d - Ap) \right] =: \theta(u)$$



New pb: find appropriate u^*
+ recover appropriate p^*

Theory

- θ convex
- $\partial\theta(u) = \text{conv} \{d - Ap\}_{p=p(u)}$

Idea find p^* as **convex combination** of $p(u)$'s

Want $\sum_k \alpha_k (d - Ap_k) = 0$ i.e. $0 \in \partial\theta$

Minimize θ and

Exhibit **optimality condition**. At u^* :

$$\exists \{\alpha_k\}, \{p_k(u^*)\} : \underbrace{\sum_k \alpha_k (d - Ap_k(u^*))}_{d - Ap^*} = 0$$

$$p^* = \sum_k \alpha_k p_k(u^*) = \boxed{\text{pseudo-schedule}}$$

Theorem p^* solves

$$\max c^\top p, \quad p \in \text{conv} P, \quad Ap = d$$

Recalls II: Dual Algs.

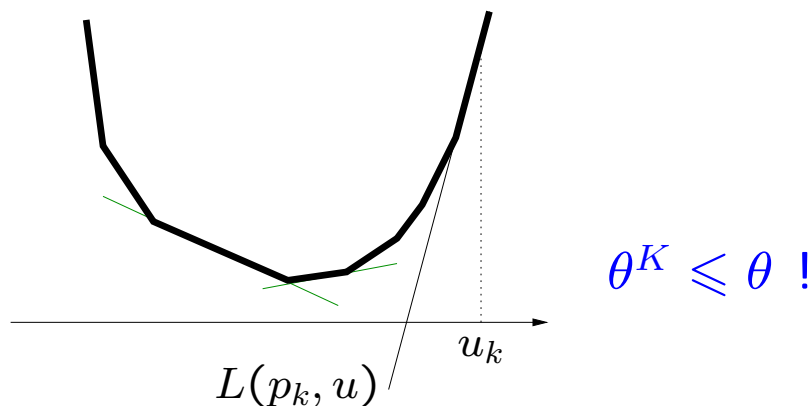
Working Horse Cutting planes

At each u_k , linearize θ : $\forall k \ p_k := p(u_k)$

$$\begin{aligned}\theta(u) &\geq \underbrace{\theta(u_k)}_{L(p_k, u_k)} + \underbrace{g(u_k)}_{d - Ap_k}^\top (u - u_k) \\ &= c^\top p(u_k) + u^\top (d - Ap_k) \\ &= L(p_k, u)\end{aligned}$$

Model of θ : given $\{u_k\}_{k=1, \dots, K}$

$$\theta^K(u) := \underbrace{\max_k L(p_k, u)}_{\leq \max_p L(p, u)}$$



Aim of the game find $\{u_k\}_k$

(i) close together:

(ii) such that $\sum_k \alpha_k (d - Ap(u_k))$ small

$$\begin{aligned}\theta(u_*) &\simeq \theta(u_k) && [\theta \text{ continuous}] \\ &\simeq c^\top p_k + u_*(d - Ap_k) && [u_* \simeq u_k] \\ &\simeq c^\top \sum \alpha_k p(u_k) && [\text{conv. comb.}] \\ &= c^\top p_* \\ \implies u_* &\text{ approx. optimal} && [\text{weak duality}]\end{aligned}$$

u_+ obtained as

Kelley
 $\min \theta^K(u)$

bundle
 $\min \theta^K(u) + \mu|u - \hat{u}|^2$

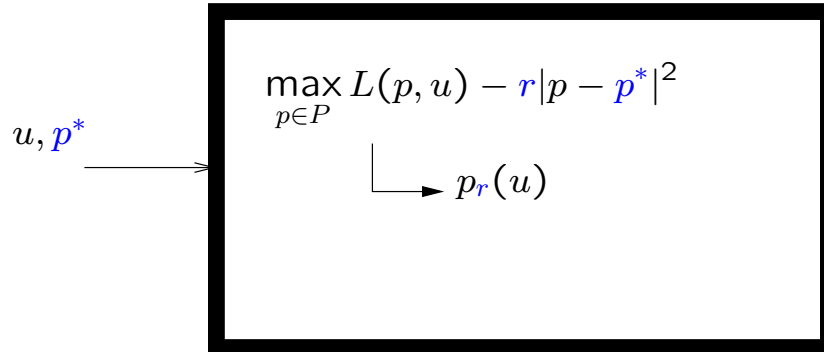
(ii) automatic

(ii) asymptotic

Primal Recovery

Pseudo-Schedule $\left\{ \begin{array}{l} \text{good balance} \\ \text{not a schedule} \end{array} \right.$

Idea Force $p(u)$ toward p_*



The diagram shows a rectangular box with a thick black border. Inside the box, the mathematical expression $\max_{p \in P} L(p, u) - r|p - p^*|^2$ is written. Below this expression, there is a small L-shaped symbol (a vertical line on the left and a horizontal line on the bottom) with an arrow pointing to the right, labeled $p_r(u)$. To the left of the box, the text u, p^* is written in blue, with an arrow pointing towards the box.

- Variant, knowing that $Ap = \sum_j A_j p_j$:

$$L_r(p, \lambda) = L(p, u) - r \sum_j |A_j(p_j - p_j^*)|^2$$

closer to augmented Lagrangian

$$-r \left| \sum_j A_j(p_j - p_j^*) \right|^2$$

= Phase II

- New Lagrangian still decomposable
- Same dual algorithm as Phase I
- Constructs schedules, retain best one
- Numerical results: ?

Compared with current “augmented Lagrangian”

– 2002: consistently	faster
	more accurate
	more reliable

– 2012: 

- Putting the method in perspective . . .

General Framework

Primal prox (Bertsekas 1979)

Theoretical $p^{k+1} = p_r(p^k)$, with

$$p_r(q) := \underset{p \in P}{\operatorname{Argmax}} \left\{ \underbrace{c^\top p - r|p - q|^2}_{\text{more concave}} : Ap = d \right\}$$

Theorem Cluster point p^∞ is

- global max if r small
- **any** local max if r large

- N.B. Local max probably close to p^1

Implementable $p^{k+1} = \tilde{p}_r(p^k)$

from Lagrangian relaxation

$$\min \theta_r(u) := \max_{p \in P} \underbrace{c^\top p + u^\top (d - Ap) - r|p - q|^2}_{\text{decomposable}}$$

Theorem Cluster point \tilde{p}^∞ is

- "usually" p^* if r small
- **any** local max if r large probably p^1
- In practice, r must balance $c^\top p$ and $|p - p^*|^2$

Conclusion

Iterating = probably bad idea

Initialization tricky $p^1 \neq p^*$!

Noise

$$\theta(u) \rightsquigarrow \theta_o(u) = \theta(u) - \eta$$

Noisy model **unchanged**

$$\theta_o^K = \max_k L(p_k, \cdot) = \theta^K$$

Cutting-plane paradigm **still OK**

Specific value $\underbrace{\theta(u)}_{\text{sampling point}}$ **useless**

Except for

- stopping test: $\theta_o(u_+) \leq \theta^K(u_+) + \eta$
nothing to conclude

- bundle: $\hat{u}_+ =$

$$\begin{cases} \text{null-step } \hat{u} & \text{if } \theta_o(u_+) \geq \theta_o(\hat{u}) \\ \text{descent-step } u_+ & \text{if } \theta_o(u_+) \ll \theta_o(\hat{u}) \end{cases}$$

possibly misleading

Bundle Features

1) Informative: \hat{u} optimal within

$$\eta_{\hat{u}} := \theta(\hat{u}) - \theta_o(\hat{u})$$

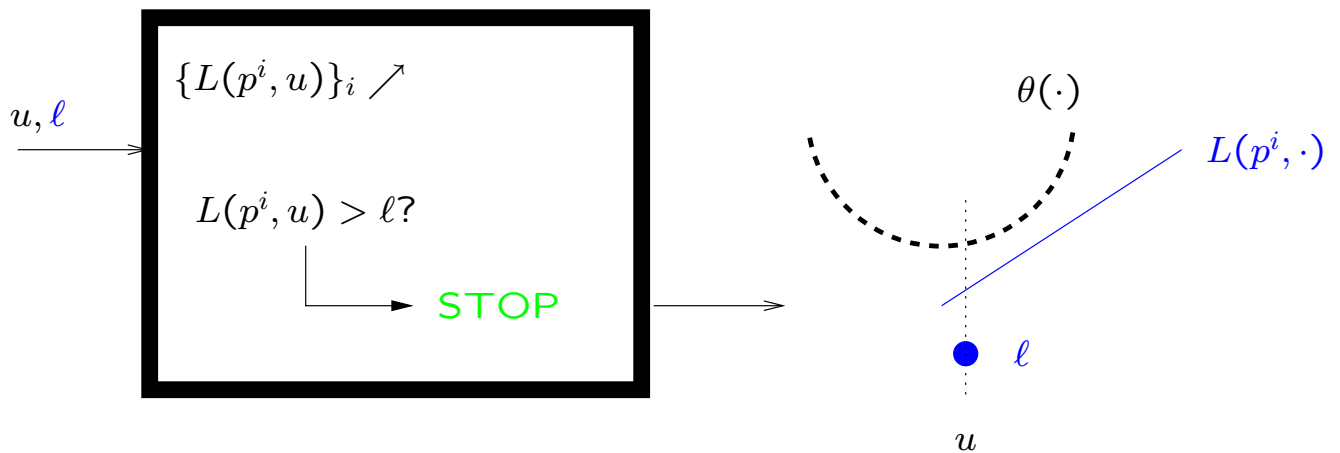
2) Friendly:

Noise possibly harmful **only** when

$$\theta_o(u) \leq \ell \quad [" = " \theta_o(\hat{u})] \quad \text{then } \hat{u} \text{ updated}$$

Sends **level** to oracle

Free if turns out that $\theta_o(u) > \ell$



3) Case of smart oracle: choose η

u, η \longrightarrow $\theta_o(u) \geq \theta(u) - \eta$ expensive if η small
cheap if $\eta = +\infty$

Sensible strategy

Call accurate oracle sometimes only

a) At each descent-step Gaudioso et al., Kiwiel

- yields optimality
- expensive oracle too often

b) After optimality if $\hat{\eta}$ too large

- very cheap
- convergence?

Synthesis

Malick, Oliveira, Zaourar

- Call accurate oracle at each \hat{u} -update **BUT**
- View computation of \hat{u}_+ as a

cutting-plane subalgorithm

– sequence of null-steps = a)

– full bundle = b)

– in between: anything

coarse bundle, pure Kelley, . . .

Convergence OK

Potentially substantial **improvement**