

On Optimal Design of Charging Stations for Electric Vehicles

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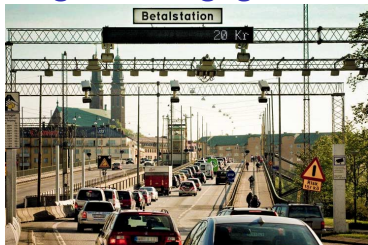
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September 17, 2015

Application Areas: E-Mobility and Design of Telecom Networks

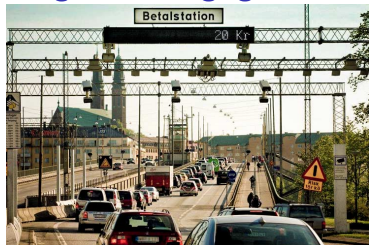
- **E-Mobility:** E-cars need to recharge after traveling a certain distance
- **Congestion charging mechanisms**



- **Goal:** Fulfill the demands while minimizing the cost of road tolls and charging stations.

Application Areas: E-Mobility and Design of Telecom Networks

- **E-Mobility:** E-cars need to recharge after traveling a certain distance
- **Congestion charging mechanisms**



- **Goal:** Fulfill the demands while minimizing the cost of road tolls and charging stations.

Network Design: Signals can only be transmitted over limited distances (signal deterioration). Signal regenerators to be placed, or additional lines to be purchased.

e⁴-share

Models for **E**cological, Car-Sharing
Economical,
Efficient,
Electric

Consortium:



universität
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iC *consulenten*

Outline

- 1 Problem Definition
- 2 Our Contribution
- 3 Communication Graphs
- 4 MIP Models
- 5 Results

Problem Definition

- Undirected graph $G = (V, E)$
- **Edge costs** $w : E \rightarrow \mathbb{Q}_0^+$ and **edge lengths** $d : E \rightarrow \mathbb{Q}^+$
- Maximum distance $d_{\max} \in \mathbb{N}^+$
- **Relay costs** $c : V \rightarrow \mathbb{Q}^+$
- Set of **node pairs** $\mathcal{K}$ that need to communicate

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- Set of **node pairs** $\mathcal{K}$ that need to communicate
- An s - t path p is **feasible** iff its length $d(p) \leq d_{\max}$.
Otherwise, relays $\{r_1, \dots, r_k\}$ to be placed so that

$$p = (s, p_1, r_1, p_2, r_2, \dots, r_k, p_{k+1}, t),$$

and length of every subpath p_i is $d(p_i) \leq d_{\max}$.

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and length of every subpath p_i is $d(p_i) \leq d_{\max}$.

Goal:

Choose a subset of relays and edges with minimal total costs s.t. there exists a feasible path for every pair in $\mathcal{K}$.

Example

Graph $G = (V, E)$, $d_{\max} = 4$

$\mathcal{K} = \{(0, 3), (0, 4), (2, 5), (3, 4)\}$

Free (existing) edges E_0 :

$E^0 = \{e | w(e) = 0\}$

Augmenting edges E^* :

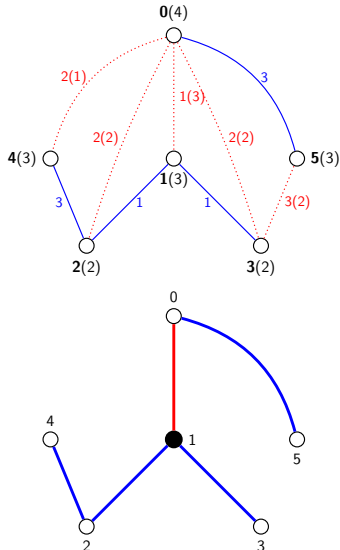
$E^* = \{e | w(e) > 0\}$

nodes **index (relay cost)**

edges **cost (distance)**

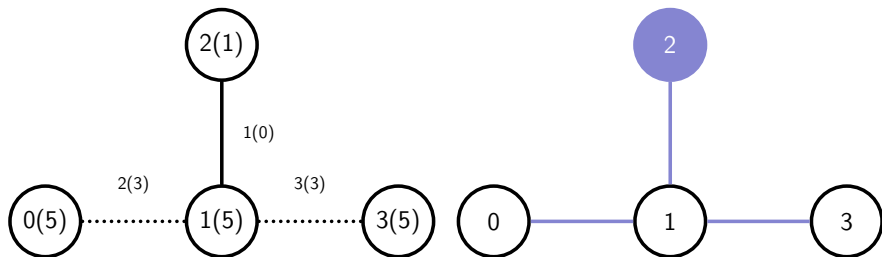
Optimal solution:

1 + 3



Cycle Property

- $d_{max} = 4$, $\mathcal{K} = \{(0, 3)\}$



Property 1

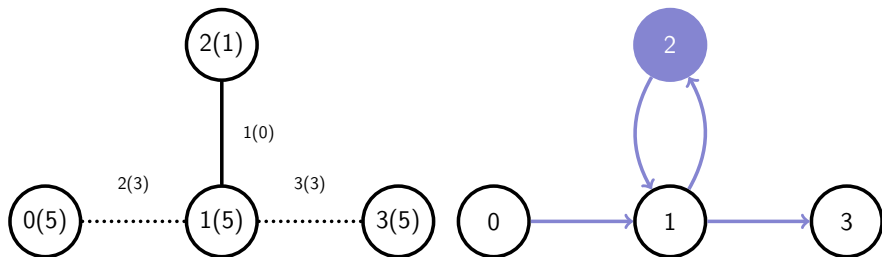
In an optimal solution there exists for every pair $(u, v) \in \mathcal{K}$ a path from u to v visiting each **relay at most once**.

Property 2

In an optimal solution there exists for every pair $(u, v) \in \mathcal{K}$ a path from u to v visiting each **non-relay at most twice**.

Cycle Property

- $d_{max} = 4$, $\mathcal{K} = \{(0, 3)\}$



Property 1

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Previous Work

- E. A. Cabral, E. Erkut, G. Laporte, and R. A. Patterson. The network design problem with relays. *European Journal of Operational Research*, 180(2):834–844, 2007.
- A. Konak. Network design problem with relays: A genetic algorithm with a path-based crossover and a set covering formulation. *European Journal of Operational Research*, 218(3):829–837, 2012.
- S. Lin, X. Li, K. Wei, and C. Yue. A tabu search based metaheuristic for the network design problem with relays. In *Service Systems and Service Management (ICSSSM), 2014 11th International Conference on*, pages 1–6, 2014.

Our Contribution

- **Our contribution:** We introduce 3 MIP models derived on the communication graph.
- Derive two Branch-and-Price and a Branch-Price-and-Cut algorithm.
- Outperform heuristics on smaller instances from the literature and solve them to optimality.
- Provide best known UBs for unsolved instances.

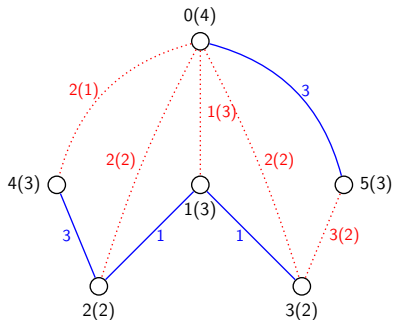
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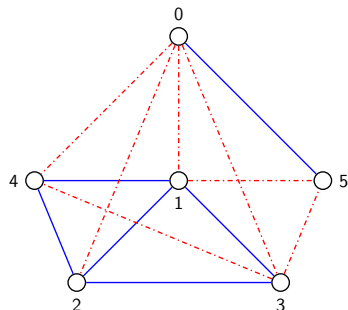
Communication Graph: Idea

Used by Chen et al. for solving the Regenerator Location Problem. Main idea:

- Graph $\mathbf{G_C} = (\mathbf{V}, \mathbf{C^0} \cup \mathbf{C^*})$
- Contains edges between all vertex pairs that can be connected **without** the use of **relays**
- Each edge $b \in \mathbf{C^0} \cup \mathbf{C^*}$ corresponds to a set of paths P_b in G

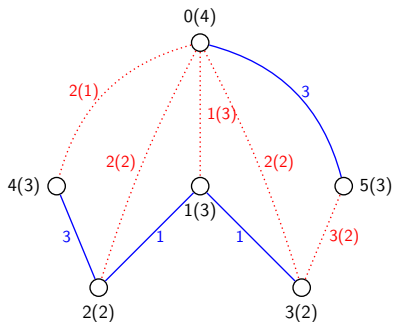


(a) Original Graph

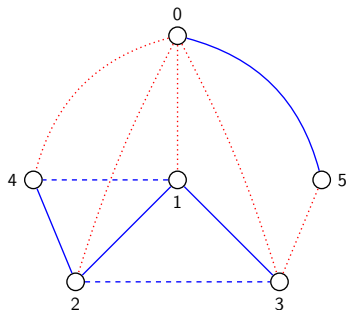


(b) Final Communication Graph

Communication Graph: Example



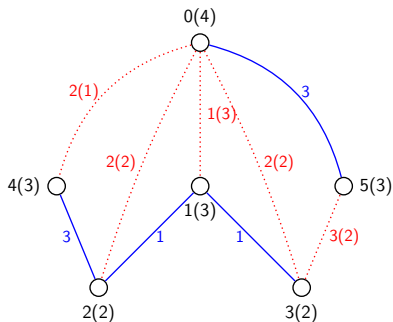
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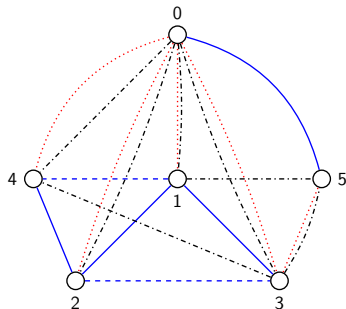
(b) Adding all feasible connections using edges in E_0 (dashed lines)

$$d_{\max} = 4$$

Communication Graph: Example



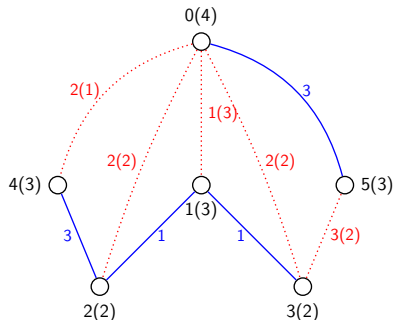
(a) Original Graph



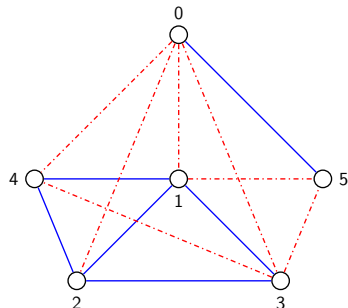
(b) Adding all feasible connections using edges in $E_O \cup E^*$ (dash-dotted lines)

$$d_{\max} = 4$$

Communication Graph: Example



(a) Original Graph



(b) Final Communication Graph

$$d_{\max} = 4$$

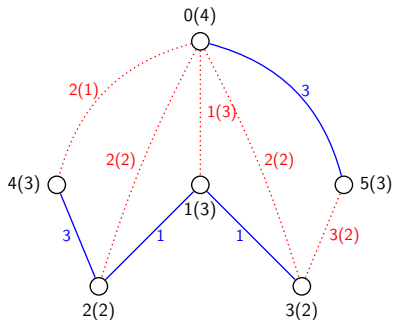
$$G_C = (V, C) \text{ where } C = C^0 \cup C^*$$

Communication Graph: Properties

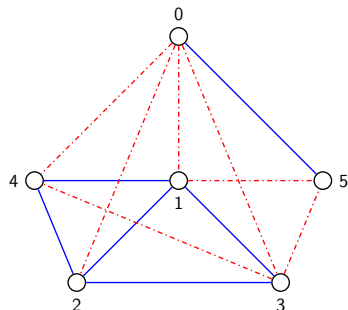
Consider a pair $(u, v) \in \mathcal{K}$.

- Either u and v are directly connected in G_C , or
- Relays need to be placed, so that there is a u - v path **in G_C** with relay placed at **all intermediate nodes**

Identify cost-optimal connections among the exponentially many possibilities $\Rightarrow$ **Column Generation**



(a) Original Graph

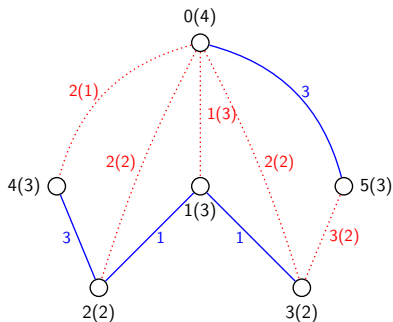


(b) Final Communication Graph

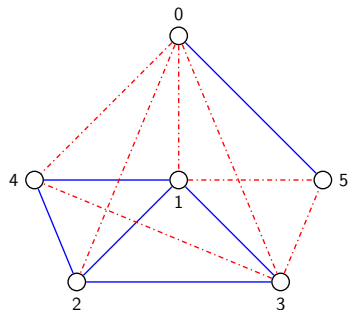
Communication Graph: Properties

Consider a pair $(u, v) = (4, 5)$.

- Place relay at node 1 and use path $(4, 1, 5)$
- Edge $(1, 5) \in C$, so we should choose an appropriate 1-5 path **in G**.
- Since $(1, 5) \in C^*$, edge costs are involved
- Optimal path chosen by **Column Generation**



(a) Original Graph



(b) Final Communication Graph

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Communication Graph Models

Theorem

*In an optimal solution mapped on a communication graph there exists **for every $u \in \mathcal{K}_S$ an arborescence rooted at u reaching all targets $v \in K(u)$.***

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Three MIP Formulations

Model Name	Graphs	Connectivity	Type
<i>MCF</i>	comm.graph	multi-commodity flow	B&P
<i>SCF</i>	comm.graph	single-commodity flow	B&P
<i>CUT</i>	directed comm. graph	cutset inequalities	B&P&C

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*In an optimal solution mapped on a communication graph there exists **for every $u \in \mathcal{K}_S$ an arborescence rooted at u reaching all targets $v \in K(u)$.***

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Major Difficulty

Connect the arborescences in the communication graph with the edges of the original graph.

MCF Variables

$$x_e = \begin{cases} 1, & e \text{ is in solution,} \\ 0, & \text{otherwise} \end{cases} \quad \forall e \in E$$

$$y_i = \begin{cases} 1, & \text{relay is placed at } i, \\ 0, & \text{otherwise} \end{cases} \quad \forall i \in V$$

$$f_a^{uv} = \begin{cases} 1, & a \text{ is used to connect } (u, v) \text{ in } G_C, \\ 0, & \text{otherwise} \end{cases} \quad \forall (u, v) \in \mathcal{K}, \forall a \in A_C$$

Path Variables

Consider a vertex pair $b = (u, v)$. Let

$$P_b = \{p \mid p \text{ is a } u\text{-}v \text{ path in } G, \text{ s.t. } d(p) \leq d_{\max}\}$$

Basic idea:

represent each feasible path $p \in P_b$ for a given commodity pair $b = (u, v) \in \mathcal{K}$ as a simple path from u to v in G_C .

Path Variables

Mapping between edges in G_C and paths in G :

$$\lambda_b^p = \begin{cases} 1, & p \text{ is used to connect node pair } b, \\ 0, & \text{otherwise} \end{cases} \quad \forall b \in C^*, \forall p \in P_b$$

Exponential number of λ variables $\Rightarrow$ column generation.

MCF Model

$$\min \sum_{i \in V} c_i y_i + \sum_{e \in E^*} w_e x_e$$

$$\sum_{a \in \delta^-(i)} f_a^{uv} - \sum_{a \in \delta^+(i)} f_a^{uv} = \begin{cases} -1 & i = u \\ 0 & i \neq u, i \neq v \\ 1 & i = v \end{cases} \quad \begin{matrix} \forall (u, v) \in \mathcal{K}, \\ \forall i \in V_C^u \end{matrix} \quad (1)$$

$$\sum_{a \in \delta^+(i)} f_a^{uv} \leq y_i \quad \begin{matrix} \forall (u, v) \in \mathcal{K}, \\ \forall i \in V, \\ i \neq u, i \neq v \end{matrix} \quad (2)$$

MCF Model

$$\min \sum_{i \in V} c_i y_i + \sum_{e \in E^*} w_e x_e$$

$$\sum_{a \in \delta^-(i)} f_a^{uv} - \sum_{a \in \delta^+(i)} f_a^{uv} = \begin{cases} -1 & i = u \\ 0 & i \neq u, i \neq v \\ 1 & i = v \end{cases} \quad \begin{matrix} \forall (u, v) \in \mathcal{K}, \\ \forall i \in V_C^u \end{matrix} \quad (1)$$

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$$f_{ij}^{uv} + f_{ji}^{uv} \leq \sum_{p \in P_b} \lambda_b^p \quad \begin{matrix} \forall (u, v) \in \mathcal{K}, \\ \forall b = \{i, j\} \in C^* \end{matrix} \quad (\mu_b^{uv}) \quad (3)$$

$$\sum_{p \in P_b: e \in p} \lambda_b^p \leq x_e \quad \forall e \in E^*, \forall b \in C^* \quad (\alpha_b^e) \quad (4)$$

MCF: Pricing Subproblem

Given current LP solution, let $\tilde{\mu}_b^{uv}$ and $\tilde{\alpha}_b^e$ be values of dual variables.

Pricing Subproblem for each $b = \{i, j\} \in C^*$

Find a feasible path $p \in P_b$ with minimum reduced costs:

$$\arg \min_{p \in P_b} \left(\sum_{e \in E^* \cap p} \tilde{\alpha}_b^e - \sum_{(u,v) \in \mathcal{K}} \tilde{\mu}_b^{uv} \right)$$

For a fixed b , $\sum_{(u,v) \in \mathcal{K}} \tilde{\mu}_b^{uv}$ is a constant, the problem boils down to:

$$\tilde{p}_b = \arg \min_{p \in P_b} \sum_{e \in E^* \cap p} \tilde{\alpha}_b^e \quad \forall b \in C^*$$

Weight Constrained Shortest Path Problem. Pseudo-polynomial time.
Dynamic programming procedure proposed by Gouveia et al (2008).

MCF: Pros and Cons

Cons:

Huge number of design variables ($|V| + |E| + |\mathcal{K}||V|^2$) (in addition to λ !)

Pros:

Strong LBs!

Trade the size of the model and the strength of the bounds:
single-commodity flow model *SCF*
(not shown in this talk)

CUT Formulation: Directed Communication Graph

Basic idea:

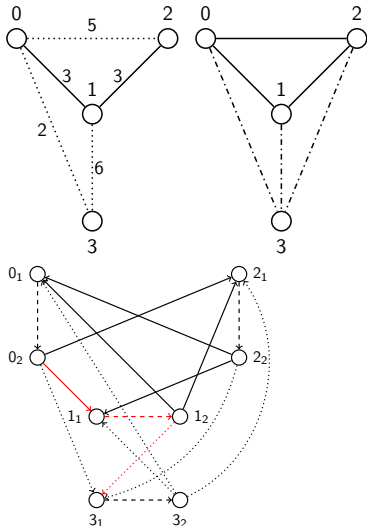
A **feasible path** p for a given commodity pair $b = (u, v) \in \mathcal{K}$ is a **directed path** from u to v in G'_C .

$$x_e = \begin{cases} 1, & e \text{ is in solution, } \forall e \in E \\ 0, & \text{otherwise} \end{cases}$$

$$X_a = \begin{cases} 1, & a \text{ is used in a feasible path, } \forall a \in A'_C \\ 0, & \text{otherwise} \end{cases}$$

One-to-one correspondence between the arcs in A'_C and the relays.

Example: a path between **0** and **3** in communication using a **relay at 1**



$$\min \sum_{i \in V} c_i X_{(i_1, i_2)} + \sum_{e \in E^*} w_e X_e$$

$$\min \sum_{i \in V} c_i X_{(i_1, i_2)} + \sum_{e \in E^*} w_e x_e$$

$$\sum_{a \in \delta^-(W)} x_a \geq 1$$

$$\forall (u, v) \in \mathcal{K}, \forall W \subset V'_G \\ v_1 \in W, u_2 \notin W$$

$$\min \sum_{i \in V} c_i X_{(i_1, i_2)} + \sum_{e \in E^*} w_e x_e$$

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$$\forall (u, v) \in \mathcal{K}, \forall W \subset V'_G \\ v_1 \in W, u_2 \notin W$$

$$x_{uv} \leq \sum_{p \in P_b} \lambda_b^p$$

$$\forall b = \{u, v\} \in C^* \quad (\mu_b^1)$$

$$x_{vu} \leq \sum_{p \in P_b} \lambda_b^p$$

$$\forall b = \{u, v\} \in C^* \quad (\mu_b^2)$$

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$$\forall b = \{u, v\} \in C^* \quad (\mu_b^2)$$

$$\sum_{p \in P_b: e \in p} \lambda_b^p \leq x_e$$

$$\forall e \in E^*, \forall b \in C^* \quad (\alpha_e^e)$$

$$x_a, x_e \in \{0, 1\} \\ \lambda_b^p \geq 0$$

$$\forall e \in E^*, \forall a \in A'_C \\ \forall b \in C^*, p \in P_b$$

CUTS: Pricing Subproblem

Pricing Subproblem for each $b \in C^*$

Find a feasible path $p \in P_b$ with minimum reduced costs:

$$\arg \min_{p \in P_b} \left(\sum_{e \in E^* \cap p} \tilde{\alpha}_b^e - \tilde{\mu}_b^1 - \tilde{\mu}_b^2 \right)$$

For a fixed b , $\tilde{\mu}_b^1 + \tilde{\mu}_b^2$ is a constant, the problem boils down to:

$$\tilde{p}_b = \arg \min_{p \in P_b} \sum_{e \in E^* \cap p} \tilde{\alpha}_b^e \quad \forall b \in C^*$$

Weight Constrained Shortest Path Problem. **Advantage:** connectivity cuts do not influence the pricing subproblem. Row- and column-generation can be performed independently!!

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Cabral - Instances

- Originally introduced in Cabral et al. [2007]
- 4-grid graphs
- Only augmenting edges
- Cost and edge length values are selected uniformly at random from $[10, 30]$
- Communication pairs have a common origin node

Instance	$ V $	$ E^* $	$ E^0 $	$ K $	d_{max}
4A5B70L5K	20	31	0	5	70
4A5B70L10K	20	31		10	
5A5B70L5K	25	40	0	5	70
5A5B70L10K	25	40		10	
6A5B70L5K	30	49	0	5	70
6A5B70L10K	30	49		10	
7A5B70L5K	35	58	0	5	70
7A5B70L10K	35	58		10	
8A5B70L5K	40	67	0	5	70
8A5B70L10K	40	67		10	
9A5B70L5K	45	76	0	5	70
9A5B70L10K	45	76		10	
10A5B70L5K	50	85	0	5	70
10A5B70L10K	50	85		10	
11A5B70L5K	55	94	0	5	70
11A5B70L10K	55	94		10	
12A5B70L5K	60	103	0	5	70
12A5B70L10K	60	103		10	

Results: Cabral - Instances¹

Instance	LP Gap [%]			LP - t [s]			Optimality Gap [%]			t [s]			RMPI
	MC FM	SC FM	CUTS	MC FM	SC FM	CUTS	MC FM	SC FM	CUTS	MC FM	SC FM	CUTS	
4A5B70L5K	18.8	69.0	23.7	0	0	0	0.0	0.0	0.0	1	1	1	1
4A5B70L10K	36.6	79.5	42.2	0	0	0	0.0	0.0	0.0	5	17	7	4
5A5B70L5K	28.6	67.9	33.8	0	0	0	0.0	0.0	0.0	2	9	5	2
5A5B70L10K	39.3	81.2	46.8	1	0	0	0.0	0.0	0.0	18	196	25	30
6A5B70L5K	27.9	67.0	32.9	0	0	0	0.0	0.0	0.0	6	30	10	8
6A5B70L10K	40.3	78.6	46.3	2	0	1	0.0	0.0	0.0	42	433	40	88
7A5B70L5K	32.8	66.4	38.7	0	0	0	0.0	0.0	0.0	8	21	11	7
7A5B70L10K	39.7	78.5	45.1	4	0	1	0.0	0.0	0.0	102	1312	89	184
8A5B70L5K	31.8	69.2	36.0	1	0	0	0.0	0.0	0.0	21	238	32	34
8A5B70L10K	38.5	79.9	43.1	5	0	1	0.0	1.9	0.0	130	3772	157	523
9A5B70L5K	31.8	67.7	38.5	1	0	0	0.0	0.0	0.0	24	257	36	21
9A5B70L10K	39.0	81.7	42.5	8	0	2	0.0	10.8	0.0	282	5303	271	339
10A5B70L5K	31.2	65.9	34.8	2	0	0	0.0	1.3	0.0	59	1068	81	46
10A5B70L10K	38.1	77.4	42.7	13	0	1	0.0	12.4	0.0	844	5674	547	1419
11A5B70L5K	34.0	67.0	39.1	2	0	0	0.0	0.0	0.0	40	458	50	34
11A5B70L10K	38.0	76.7	42.4	22	0	2	0.0	18.3	0.0	1073	7056	588	3496
12A5B70L5K	34.9	68.0	39.1	3	0	1	0.0	2.3	0.0	459	1085	660	549
12A5B70L10K	38.0	78.3	42.2	27	0	2	4.1	25.0	1.3	2661	6587	2196	4656

¹Each row corresponds to the mean over 10 instances.

NDPR - Instances

- Modified version of the instances provided in Konak [2012]
- Euclidean distances have been rounded up to obtain integral edge weights and lengths
- Only augmenting edges
- Type I: $w_e = d_e$
- Type II: $w_e = d_{max} - d_e$

Instance	$ V $	$ E^* $	$ E^0 $	$ K $	d_{max}
40N5K30L	40	198	0	5	30
40N5K35L		272		5	35
40N10K30L		198		10	30
40N10K35L		272		10	35
50N5K30L	50	279	0	5	30
50N5K35L		372		5	35
50N10K30L		279		10	30
50N10K35L		372		10	35
60N5K30L	60	305	0	5	30
60N5K35L		412		5	35
60N10K30L		305		10	30
60N10K35L		412		10	35
80N5K30L	80	641	0	5	30
80N5K35L		853		5	35
80N10K30L		641		10	30
80N10K35L		853		10	35
160N5K30L	160	2773	0	5	30
160N5K35L		3624		5	35
160N10K30L		2773		10	30
160N10K35L		3624		10	35

Results: NDPR - Instances (Type I)

Instance	LP Gap [%]			LP - t [s]			Optimality Gap [%]			t [s]		
	MCFM	SCFM	CUTS	MCFM	SCFM	CUTS	MCFM	SCFM	CUTS	MCFM	SCFM	CUTS
40N_5K_30L	21.5	21.5	24.9	0	0	0	0.0	0.0	0.0	76	72	98
40N_5K_35L	38.5	38.5	43.4	3	3	1	11.6	11.4	11.8	7200	7200	7200
40N_10K_30L	26.2	26.9	28.9	4	3	0	0.0	0.0	0.0	2850	3109	1163
40N_10K_35L	40.1	40.3	44.6	6	5	2	17.5	17.5	20.8	7200	7200	7200
50N_5K_30L	8.5	13.5	15.5	1	1	1	0.0	0.0	0.0	6	8	20
50N_5K_35L	22.5	25.4	27.6	2	2	2	0.0	0.0	0.0	39	46	83
50N_10K_30L	24.6	25.2	31.1	9	7	2	0.0	0.0	0.0	737	828	1841
50N_10K_35L	27.6	28.1	37.4	22	18	6	0.0	0.0	0.0	2098	1890	3209
60N_5K_30L	28.1	28.1	35.8	2	2	2	0.0	0.0	0.0	63	67	236
60N_5K_35L	24.3	24.3	34.1	4	5	4	0.0	0.0	0.0	141	121	429
60N_10K_30L	32.3	32.3	40.3	11	11	2	0.0	0.0	5.0	2534	2908	7200
60N_10K_35L	33.1	33.1	43.7	17	36	6	0.0	3.6	12.8	7155	7200	7200
80N_5K_30L	44.6	51.0	52.2	24	16	14	28.6	34.4	33.9	7200	7200	7200
80N_5K_35L	53.7	59.2	61.6	83	49	33	41.8	47.9	45.0	7200	7200	7200
80N_10K_30L	53.1	56.5	59.9	195	139	26	44.0	46.4	47.4	7200	7200	7200
80N_10K_35L	66.3	68.3	73.1	1046	602	63	63.7	65.1	64.2	7200	7200	7200
160N_5K_30L	55.8	55.8	64.5	4183	3625	1414	55.8	54.9	62.9	7200	7200	7200
160N_5K_35L	-	-	73.4	7200	7200	6402	-	-	73.2	7200	7200	7200
160N_10K_30L	-	-	74.5	7200	7200	7200	-	-	74.5	7200	7200	7200
160N_10K_35L	-	-	85.8	7200	7200	7200	-	-	85.8	7200	7200	7200

Results: NDPR - Instances (Type II)

Instance	LP Gap [%]			LP - t [s]			Optimality Gap [%]			t [s]		
	<i>MC FM</i>	<i>SC FM</i>	<i>CUTS</i>	<i>MC FM</i>	<i>SC FM</i>	<i>CUTS</i>	<i>MC FM</i>	<i>SC FM</i>	<i>CUTS</i>	<i>MC FM</i>	<i>SC FM</i>	<i>CUTS</i>
40N_5K_30L.p3	0.3	0.3	1.6	0	0	0	0.0	0.0	0.0	0	0	0
40N_5K_35L.p3	7.8	7.8	12.9	2	1	1	0.0	0.0	0.0	6	4	6
40N_10K_30L.p3	6.6	8.0	9.7	2	2	0	0.0	0.0	0.0	11	10	9
40N_10K_35L.p3	10.1	10.9	16.1	7	7	1	0.0	0.0	0.0	61	55	29
50N_5K_30L.p3	0.0	6.5	0.0	0	0	0	0.0	0.0	0.0	0	1	0
50N_5K_35L.p3	1.9	9.8	7.4	1	1	2	0.0	0.0	0.0	2	4	22
50N_10K_30L.p3	2.5	5.7	7.6	1	1	2	0.0	0.0	0.0	3	2	21
50N_10K_35L.p3	3.0	4.0	11.4	7	8	7	0.0	0.0	0.0	56	39	64
60N_5K_30L.p3	14.9	14.9	23.0	1	2	1	0.0	0.0	0.0	8	8	27
60N_5K_35L.p3	0.0	0.0	0.0	0	0	2	0.0	0.0	0.0	0	0	2
60N_10K_30L.p3	13.7	13.7	19.6	4	5	2	0.0	0.0	0.0	58	53	44
60N_10K_35L.p3	6.9	6.9	10.2	6	7	4	0.0	0.0	0.0	39	30	39
80N_5K_30L.p3	7.8	15.9	13.3	8	6	11	0.0	0.0	0.0	54	85	117
80N_5K_35L.p3	6.2	16.1	12.0	13	14	36	0.0	0.0	0.0	59	208	229
80N_10K_30L.p3	12.1	16.1	18.4	86	55	22	0.0	0.0	0.0	1227	1105	526
80N_10K_35L.p3	18.9	23.4	25.6	348	244	118	14.5	15.0	8.6	7200	7200	7200
160N_5K_30L.p3	7.3	7.3	11.6	715	658	882	0.0	0.0	0.0	1896	1954	6641
160N_5K_35L.p3	10.9	10.9	14.1	1301	1348	2119	5.1	5.7	9.5	7200	7200	7200
160N_10K_30L.p3	14.1	14.1	19.4	2553	2843	2584	13.8	13.8	17.8	7200	7200	7200
160N_10K_35L.p3	-	-	33.2	7200	7200	7200	-	-	33.2	7200	7200	7200

ARLP - Instances

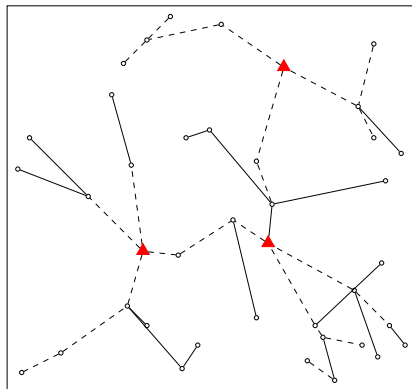
- New Instances with a high amount of commodities
- Edge lengths based on rounded up euclidean distances
- Edge costs normally distributed around edge lengths ($\mu = d_e, \sigma = 5$)
- Also free edges

Instance	$ V $	$ E^* $	$ E^0 $	$ K $	d_{max}
40N50L20F_A	40	124	26	724	50
40N50L20F_B		123	35	688	
40N50L50F_A		78	89	513	
40N50L50F_B		72	71	586	
40N50L80F_A		32	146	443	
40N50L80F_B		35	154	423	
50N50L20F_A	50	212	44	1111	50
50N50L20F_B		235	59	1022	
50N50L50F_A		157	132	719	
50N50L50F_B		132	117	873	
50N50L80F_A		51	175	788	
50N50L80F_B		58	212	682	
60N50L20F_A	60	269	72	1549	50
60N50L20F_B		268	63	1588	
60N50L50F_A		204	216	1036	
60N50L50F_B		200	197	1103	
60N50L80F_A		85	311	854	
60N50L80F_B		74	283	1041	
80N50L20F_A	80	557	145	2599	50
80N50L20F_B		545	124	2659	
80N50L50F_A		345	313	1922	
80N50L50F_B		375	366	1902	
80N50L80F_A		148	548	1834	
80N50L80F_B		121	536	1709	

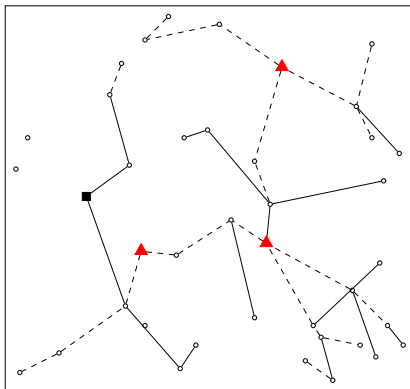
Results: ARLP - Instances

Instance	LP Gap [%]			LP - t [s]			Optimality Gap [%]			t [s]		
	MC FM	SC FM	CUTS	MC FM	SC FM	CUTS	MC FM	SC FM	CUTS	MC FM	SC FM	CUTS
40N50L20F_A	-	31.5	20.7	7200	177	4	-	0.0	0.0	7200	1517	189
40N50L20F_B	-	30.8	24.3	7200	113	2	-	0.0	0.0	7200	816	86
40N50L50F_A	15.6	19.6	17.1	157	4	0	0.0	0.0	0.0	1733	57	4
40N50L50F_B	6.6	13.2	9.0	471	5	0	0.0	0.0	0.0	3532	31	4
40N50L80F_A	0.0	0.0	0.0	7	0	2	0.0	0.0	0.0	7	0	2
40N50L80F_B	6.6	8.7	10.3	23	1	0	0.0	0.0	0.0	83	10	2
50N50L20F_A	ML	26.3	13.7	ML	746	8	ML	14.6	0.0	ML	7200	1268
50N50L20F_B	ML	26.1	9.5	ML	570	7	ML	9.1	0.0	ML	7200	110
50N50L50F_A	ML	14.7	16.3	ML	17	1	ML	0.0	0.0	ML	68	6
50N50L50F_B	ML	9.8	7.4	ML	21	1	ML	0.0	0.0	ML	192	22
50N50L80F_A	ML	14.1	17.1	ML	2	0	ML	0.0	0.0	ML	10	5
50N50L80F_B	ML	0.3	0.0	ML	1	4	ML	0.0	0.0	ML	2	4
60N50L20F_A	ML	25.8	13.6	ML	1193	15	ML	16.4	0.0	ML	7200	862
60N50L20F_B	ML	37.4	25.3	ML	1401	20	ML	33.1	0.0	ML	7200	4158
60N50L50F_A	ML	14.3	15.0	ML	49	1	ML	0.0	0.0	ML	436	21
60N50L50F_B	ML	20.4	10.4	ML	60	1	ML	0.0	0.0	ML	787	25
60N50L80F_A	ML	2.2	2.2	ML	12	1	ML	0.0	0.0	ML	27	9
60N50L80F_B	ML	12.1	12.7	ML	7	1	ML	0.0	0.0	ML	27	10
80N50L20F_A	ML	-	26.0	ML	7200	89	ML	-	20.5	ML	7200	7200
80N50L20F_B	ML	-	31.9	ML	7200	94	ML	-	30.9	ML	7200	7200
80N50L50F_A	ML	21.2	18.2	ML	438	3	ML	0.0	0.0	ML	6054	104
80N50L50F_B	ML	11.7	16.2	ML	497	3	ML	0.0	0.0	ML	3807	56
80N50L80F_A	ML	2.6	3.2	ML	49	4	ML	0.0	0.0	ML	107	29
80N50L80F_B	ML	4.2	5.8	ML	57	2	ML	0.0	0.0	ML	223	31

Example 1



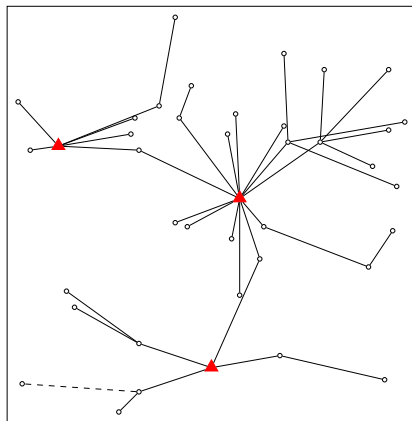
(a) 40N30C50L20F_A (original)



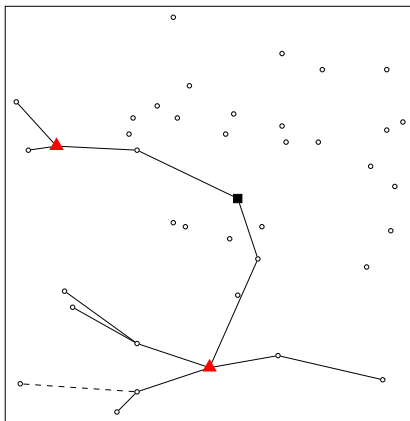
(b) 40N30C50L20F_A ($\mathcal{K}'$)

Solid lines: free edges, dashed lines: augmenting edges.
Selected relays: triangles. Single source: square.
724 commodities (left).

Example 2



(a) 40N30C50L80F_A (original)



(b) 40N30C50L80F_A ($\mathcal{K}'$)

80% of free edges. Solid lines: free edges, dashed lines: augmenting edges.

Selected relays: triangles. Single source: square.

443 commodities (left).

Conclusion

Summary:

- First study on exact algorithms for NDPR
- MIP models based on communication graph(s)
- Flow-based models (B&P) work well if very few commodities involved
- Cut-based model (B&P&C) better for a large number of commodities
- The new algorithms find optimal solutions for instances of:
 - ▶ 160 nodes and more than 3500 edges
 - ▶ 80 nodes and more than 1900 commodity pairs

Conclusion

Future Challenges:

- Not included in our model:
 - ▶ maximal number of charging stations along a single trip
 - ▶ maximal detouring length
 - ▶ maximal duration of the trip
 - ▶ different charging technologies

Conclusion

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- Still, the obtained solutions:
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 - ▶ in a step-by-step planning approach
 - ▶ as a starting heuristic solution that needs small repairs

Conclusion

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- Still, the obtained solutions:
 - ▶ can be used within some decomposition schemes (Lagrangian, Benders)
 - ▶ in a step-by-step planning approach
 - ▶ as a starting heuristic solution that needs small repairs
- More powerful exact algorithms, matheuristics, ...
- Models on **layered graphs**

Thank you for your Attention! Questions?

